

## SECTION H — ELECTRICITY

### H02 GENERATION, CONVERSION, OR DISTRIBUTION OF ELECTRIC POWER

**H02K DYNAMO-ELECTRIC MACHINES** (dynamo-electric relays H01H 53/00; conversion of DC or AC input power into surge output power H02M 9/00)

#### Note(s)

1. This subclass covers the structural adaptation of dynamo-electric machines for the purpose of their control.
2. This subclass does not cover starting, regulating, electronically commutating, braking, or otherwise controlling motors, generators or dynamo-electric converters, in general, which is covered by subclass H02P.
3. Attention is drawn to the Notes following the titles of class B81 and subclass B81B relating to "micro-structural devices" and "micro-structural systems".

#### Subclass index

##### GENERATORS OR MOTORS

###### Continuously rotating

AC machines: asynchronous; synchronous; with mechanical commutators.....17/00, 19/00, 21/00, 27/00

DC machines or universal AC/DC motors: with mechanical commutators; with interrupters.....23/00, 25/00

with non-mechanical commutating devices.....29/00

Acyclic machines; oscillating machines; motors rotating step by step.....31/00, 33/00, 35/00, 37/00

Generators producing a non-sinusoidal waveform.....39/00

Machines with more than one rotor or stator.....16/00

##### SPECIAL DYNAMO-ELECTRIC APPARATUS

Machines for transmitting angular displacements; torque motors.....24/00, 26/00

Machines involving dynamo-electric interaction with a plasma or a flow of conductive liquid or of fluid-borne conductive or magnetic particles.....44/00

Systems for propulsing a rigid body along a path.....41/00

Converters.....47/00

Dynamo-electric clutches or brakes; dynamo-electric gears.....49/00, 51/00

Alleged perpetua mobilia.....53/00

Machines operating at cryogenic temperatures.....55/00

Other machines.....99/00

##### DETAILS

Magnetic circuits; windings; casings.....1/00, 3/00, 5/00

Arrangements structurally associated with the machine for handling mechanical energy; cooling; measuring or protective devices; current collection or commutation.....7/00, 9/00, 11/00, 13/00

MANUFACTURE.....15/00

**1/00 Details of the magnetic circuit** (magnetic circuits for relays H01H 50/16)

1/02 • characterised by the magnetic material

1/04 • characterised by the material used for insulating the magnetic circuit or parts thereof

1/06 • characterised by the shape, form or construction

1/08 • • Salient poles

1/10 • • • Commutating poles

1/12 • • Stationary parts of the magnetic circuit

1/14 • • • Stator cores with salient poles

1/16 • • • Stator cores with slots for windings

1/17 • • • Stator cores with permanent magnets [5]

1/18 • • • Means for mounting or fastening magnetic stationary parts on to, or to, the stator structures

1/20 • • • with channels or ducts for flow of cooling medium

1/22 • • Rotating parts of the magnetic circuit

1/24 • • • Rotor cores with salient poles

1/26 • • • Rotor cores with slots for windings

1/27 • • • Rotor cores with permanent magnets [5]

1/28 • • • Means for mounting or fastening rotating magnetic parts on to, or to, the rotor structures

1/30 • • • • using intermediate parts, e.g. spiders

1/32 • • • with channels or ducts for flow of cooling medium

1/34 • • Reciprocating, oscillating or vibrating parts of the magnetic circuit

**3/00 Details of windings**

3/02 • Windings characterised by the conductor material

3/04 • Windings characterised by the conductor shape, form or construction, e.g. with bar conductors

3/12 • • arranged in slots

- 3/14 • • • with transposed conductors, e.g. twisted conductors
- 3/16 • • • for auxiliary purposes, e.g. damping or commutating
- 3/18 • • Windings for salient poles
- 3/20 • • • for auxiliary purposes, e.g. damping or commutating
- 3/22 • • consisting of hollow conductors
- 3/24 • • with channels or ducts for cooling medium between the conductors
- 3/26 • • consisting of printed conductors
- 3/28 • • Layout of windings or of connections between windings (windings for pole-changing H02K 17/06, H02K 17/14, H02K 19/12, H02K 19/32)
- 3/30 • Windings characterised by the insulating material
- 3/32 • Windings characterised by the shape, form or construction of the insulation
- 3/34 • • between conductors or between conductor and core, e.g. slot insulation [3]
- 3/38 • • around winding heads, equalising connectors, or connections thereto
- 3/40 • • for high voltage, e.g. affording protection against corona discharges
- 3/42 • Means for preventing or reducing eddy-current losses in the winding heads, e.g. by shielding [2]
- 3/44 • Protection against moisture or chemical attack; Windings specially adapted for operation in liquid or gas
- 3/46 • Fastening of windings on the stator or rotor structure
- 3/47 • • Air-gap windings, i.e. iron-free windings [3]
- 3/48 • • in slots
- 3/487 • • • Slot-closing devices [3]
- 3/493 • • • • magnetic [3]
- 3/50 • • Fastening of winding heads, equalising connectors, or connections thereto
- 3/51 • • • applicable to rotors only [3]
- 3/52 • • Fastening salient pole windings or connections thereto

#### 5/00 Casings; Enclosures; Supports

- 5/02 • Casings or enclosures characterised by the material thereof
- 5/04 • Casings or enclosures characterised by the shape, form or construction thereof
- 5/06 • • Cast metal casings
- 5/08 • • Insulating casings
- 5/10 • • with arrangements for protection from ingress, e.g. of water or fingers
- 5/12 • • specially adapted for operating in liquid or gas (combined with cooling arrangements H02K 9/00)
- 5/124 • • • Sealing of shafts [3]
- 5/128 • • • using air-gap sleeves or air-gap discs [3]
- 5/132 • • • Submersible electric motors (H02K 5/128 takes precedence) [3]
- 5/136 • • • explosion-proof [3]
- 5/14 • • Means for supporting or protecting brushes or brush holders [3]
- 5/15 • • Mounting arrangements for bearing-shields or end plates [3]
- 5/16 • • Means for supporting bearings, e.g. insulating supports or means for fitting bearings in the bearing-shields (magnetic bearings H02K 7/09)
- 5/167 • • • using sliding-contact or spherical cap bearings [3]

- 5/173 • • • using bearings with rolling contact, e.g. ball bearings [3]
- 5/18 • • with ribs or fins for improving heat transfer
- 5/20 • • with channels or ducts for flow of cooling medium
- 5/22 • • Auxiliary parts of casings not covered by groups H02K 5/06-H02K 5/20, e.g. shaped to form connection boxes or terminal boxes
- 5/24 • specially adapted for suppression or reduction of noise or vibrations
- 5/26 • Means for adjusting casings relative to their supports

#### 7/00 Arrangements for handling mechanical energy structurally associated with dynamo-electric machines, e.g. structural association with mechanical driving motors or auxiliary dynamo-electric machines

- 7/02 • Additional mass for increasing inertia, e.g. flywheels
- 7/04 • Balancing means
- 7/06 • Means for converting reciprocating motion into rotary motion or vice versa
- 7/065 • • Electromechanical oscillators; Vibrating magnetic drives [3]
- 7/07 • • using pawls and ratchet wheels [3]
- 7/075 • • using crankshafts or eccentrics [3]
- 7/08 • Structural association with bearings
- 7/09 • • with magnetic bearings [3]
- 7/10 • Structural association with clutches, brakes, gears, pulleys or mechanical starters
- 7/102 • • with friction brakes
- 7/104 • • with eddy-current brakes
- 7/106 • • with dynamo-electric brakes
- 7/108 • • with friction clutches
- 7/11 • • with dynamo-electric clutches
- 7/112 • • with friction clutches in combination with brakes
- 7/114 • • with dynamo-electric clutches in combination with brakes
- 7/116 • • with gears
- 7/118 • • with starting devices
- 7/12 • • with auxiliary limited movement of stators, rotors or core parts, e.g. rotors axially movable for the purpose of clutching or braking
- 7/14 • Structural association with mechanical loads, e.g. with hand-held machine tools or fans (with fan or impeller for cooling the machine H02K 9/06)
- 7/16 • • for operation above the critical speed of vibration of the rotating parts
- 7/18 • Structural association of electric generators with mechanical driving motors, e.g. with turbines
- 7/20 • Structural association with auxiliary dynamo-electric machines, e.g. with electric starter motors or exciters

#### 9/00 Arrangements for cooling or ventilating (channels or ducts in parts of the magnetic circuit H02K 1/20, H02K 1/32; channels or ducts in or between conductors H02K 3/22, H02K 3/24)

- 9/02 • by ambient air flowing through the machine
- 9/04 • • having means for generating a flow of cooling medium
- 9/06 • • • with fans or impellers driven by the machine shaft
- 9/08 • by gaseous cooling medium circulating wholly within the machine casing (H02K 9/10 takes precedence)
- 9/10 • by gaseous cooling medium flowing in closed circuit, a part of which is external to the machine casing
- 9/12 • • wherein the cooling medium circulates freely within the casing

9/14	• wherein gaseous cooling medium circulates between the machine casing and a surrounding mantle	15/095	• • by laying conductors around salient poles
9/16	• • wherein the cooling medium circulates through ducts or tubes within the casing	15/10	• Applying solid insulation to windings, stators or rotors
9/18	• • wherein the external part of the closed circuit comprises a heat exchanger structurally associated with the machine casing	15/12	• Impregnating, heating or drying of windings, stators, rotors or machines
9/19	• for machines with closed casing and closed-circuit cooling using a liquid cooling medium, e.g. oil	15/14	• Casings; Enclosures; Supports
9/193	• • with provision for replenishing the cooling medium; with means for preventing leakage of the cooling medium	15/16	• Centering rotors within the stator; Balancing rotors
9/197	• • in which the rotor or stator space is fluid-tight, e.g. to provide for different cooling media for rotor and stator	<b>16/00</b>	<b>Machines with more than one rotor or stator [2]</b>
9/20	• • wherein the cooling medium vaporises within the machine casing	16/02	• Machines with one stator and two rotors [2]
9/22	• by solid heat conducting material embedded in, or arranged in contact with, the stator or rotor, e.g. heat bridges	16/04	• Machines with one rotor and two stators [2]
9/24	• Protection against failure of cooling arrangements, e.g. due to loss of cooling medium or due to interruption of the circulation of cooling medium	<b>Note(s)</b>	
9/26	• Structural association of machines with devices for cleaning or drying cooling medium, e.g. with filters	Group H02K 16/00 takes precedence over groups H02K 17/00-H02K 53/00.	
9/28	• Cooling of commutators, slip-rings or brushes, e.g. by ventilating	<b>17/00</b>	<b>Asynchronous induction motors; Asynchronous induction generators</b>
<b>11/00</b>	<b>Structural association of dynamo-electric machines with measuring or protective devices or electric components, e.g. with resistors or switches</b>	17/02	• Asynchronous induction motors
11/02	• for suppression of radio interference [6]	17/04	• • for single phase current
11/04	• for rectification [6]	17/06	• • • having windings arranged for permitting pole-changing
<b>13/00</b>	<b>Structural associations of current collectors with motors or generators, e.g. brush mounting plates or connections to windings (supporting or protecting brushes or brush holders in motor casings or enclosures H02K 5/14); Disposition of current collectors in motors or generators; Arrangements for improving commutation</b>	17/08	• • • Motors with auxiliary phase obtained by externally fed auxiliary windings, e.g. capacitor motors
13/02	• Connections between slip-rings and windings	17/10	• • • Motors with auxiliary phase obtained by split-pole carrying short-circuited windings
13/04	• Connections between commutator segments and windings	17/12	• • for multi-phase current
13/06	• • Resistive connections, e.g. by high-resistance chokes or by transistors	17/14	• • • having windings arranged for permitting pole-changing
13/08	• • Segments formed by extensions of the winding	17/16	• • having rotors with internally short-circuited windings, e.g. cage rotors
13/10	• Arrangements of brushes or commutators specially adapted for improving commutation	17/18	• • • having double-cage or multiple-cage rotors
13/12	• Arrangements for producing an axial reciprocation of the rotor and its associated current collector part, e.g. for polishing commutator surfaces	17/20	• • • having deep-bar rotors
13/14	• Circuit arrangements for improvement of commutation, e.g. by use of unidirectionally conductive elements	17/22	• • having rotors with windings connected to slip-rings
<b>15/00</b>	<b>Methods or apparatus specially adapted for manufacturing, assembling, maintaining or repairing of dynamo-electric machines</b>	17/24	• • • in which both stator and rotor are fed with AC
15/02	• of stator or rotor bodies	17/26	• • having rotors or stators designed to permit synchronous operation
15/03	• • having permanent magnets [5]	17/28	• • having compensating winding for improving phase angle
15/04	• of windings, prior to mounting into machines (insulating windings H02K 15/10, H02K 15/12)	17/30	• • Structural association of asynchronous induction motors with auxiliary electric devices influencing the characteristics of the motor or controlling the motor, e.g. with impedances or switches
15/06	• Embedding prefabricated windings in machines	17/32	• • Structural association of asynchronous induction motors with auxiliary mechanical devices, e.g. with clutches or brakes
15/08	• Forming windings by laying conductors into or around core parts	17/34	• • Cascade arrangement of an asynchronous motor with another dynamo-electric motor or converter
15/085	• • by laying conductors into slotted stators	17/36	• • • with another asynchronous induction motor
15/09	• • by laying conductors into slotted rotors	17/38	• • • with a commutator machine
		17/40	• • • with a rotary AC/DC converter
		17/42	• Asynchronous induction generators (H02K 17/02 takes precedence) [4]
		17/44	• • Structural association with exciting machines
		<b>19/00</b>	<b>Synchronous motors or generators (having permanent magnets H02K 21/00)</b>
		19/02	• Synchronous motors
		19/04	• • for single-phase current
		19/06	• • • Motors having windings on the stator and a variable-reluctance soft-iron rotor without windings, e.g. inductor motors
		19/08	• • • Motors having windings on the stator and a smooth rotor without windings of material with large hysteresis, e.g. hysteresis motors

- 19/10 • • for multi-phase current
- 19/12 • • • characterised by the arrangement of exciting windings, e.g. for self-excitation, compounding or pole-changing
- 19/14 • • having additional short-circuited windings for starting as asynchronous motors
- 19/16 • Synchronous generators
- 19/18 • • having windings each turn of which co-operates only with poles of one polarity, e.g. homopolar generators
- 19/20 • • • with variable-reluctance soft-iron rotors without winding
- 19/22 • • having windings each turn of which co-operates alternately with poles of opposite polarity, e.g. heteropolar generators
- 19/24 • • • with variable-reluctance soft-iron rotors without winding
- 19/26 • • characterised by the arrangement of exciting windings
- 19/28 • • • for self-excitation
- 19/30 • • • for compounding
- 19/32 • • • for pole-changing
- 19/34 • • Generators with two or more outputs
- 19/36 • • Structural association of synchronous generators with auxiliary electric devices influencing the characteristic of the generator or controlling the generator, e.g. with impedances or switches
- 19/38 • • Structural association of synchronous generators with exciting machines
- 21/00 Synchronous motors having permanent magnets; Synchronous generators having permanent magnets**
- 21/02 • Details
- 21/04 • • Windings on magnets for additional excitation
- 21/10 • • Rotating armatures
- 21/12 • with stationary armatures and rotating magnets
- 21/14 • • with magnets rotating within the armatures
- 21/16 • • • having annular armature cores with salient poles (with homopolar co-operation H02K 21/20)
- 21/18 • • • having horse-shoe armature cores (with homopolar co-operation H02K 21/20)
- 21/20 • • • having windings each turn of which co-operates only with poles of one polarity, e.g. homopolar machine
- 21/22 • • with magnets rotating around the armatures, e.g. flywheel magnetos
- 21/24 • • with magnets axially facing the armatures, e.g. hub-type cycle dynamos
- 21/26 • with rotating armatures and stationary magnets
- 21/28 • • with armatures rotating within the magnets
- 21/30 • • • having annular armature cores with salient poles (with homopolar co-operation H02K 21/36)
- 21/32 • • • having horse-shoe magnets (with homopolar co-operation H02K 21/36)
- 21/34 • • • having bell-shaped or bar-shaped magnets, e.g. for cycle lighting (with homopolar co-operation H02K 21/36)
- 21/36 • • • with homopolar co-operation
- 21/38 • with rotating flux distributors, and armatures and magnets both stationary
- 21/40 • • with flux distributors rotating around the magnets and within the armatures
- 21/42 • • with flux distributors rotating around the armatures and within the magnets
- 21/44 • • with armature windings wound upon the magnets
- 21/46 • Motors having additional short-circuited winding for starting as an asynchronous motor
- 21/48 • Generators with two or more outputs
- 23/00 DC commutator motors or generators having mechanical commutator; Universal AC/DC commutator motors**
- 23/02 • characterised by arrangement for exciting
- 23/04 • • having permanent magnet excitation
- 23/06 • • having shunt connection of excitation windings
- 23/08 • • having series connection of excitation windings
- 23/10 • • having compound connection of excitation windings
- 23/12 • • having excitation produced by current sources independent of the armature circuit
- 23/14 • • having high-speed excitation or de-excitation, e.g. by neutralising the remanent excitation field
- 23/16 • • having angularly adjustable excitation field, e.g. by pole reversing or pole switching
- 23/18 • • having displaceable main or auxiliary brushes
- 23/20 • • having additional brushes spaced intermediately of the main brushes on the commutator, e.g. cross-field machines, metadynes, amplidynes or other armature-reaction excited machines
- 23/22 • • having compensating or damping windings
- 23/24 • • having commutating-pole windings
- 23/26 • characterised by the armature windings
- 23/28 • • having open windings, i.e. not closed within the armatures
- 23/30 • • having lap windings; having loop windings
- 23/32 • • having wave winding; having undulating winding
- 23/34 • • having mixed windings
- 23/36 • • having two or more windings; having two or more commutators; having two or more stators
- 23/38 • • having winding or connection for improving commutation, e.g. equipotential connection
- 23/40 • characterised by the arrangement of the magnet circuits
- 23/42 • • having split poles, i.e. zones for varying reluctance by gaps in poles or by poles with different spacing of the air gap
- 23/44 • • having movable, e.g. turnable, iron parts
- 23/46 • • having stationary shunts, i.e. magnetic cross flux
- 23/48 • • having adjustable armatures
- 23/50 • Generators with two or more outputs
- 23/52 • Motors acting also as generators, e.g. starting motors used as generators for ignition or lighting
- 23/54 • Disc armature motors or generators
- 23/56 • Motors or generators having iron cores separated from armature winding
- 23/58 • Motors or generators without iron cores
- 23/60 • Motors or generators having rotating armatures and rotating excitation field
- 23/62 • Motors or generators with stationary armatures and rotating excitation field
- 23/64 • Motors specially adapted for running on DC or AC by choice
- 23/66 • Structural association with auxiliary electric devices influencing the characteristic of, or controlling, the machine, e.g. with impedances or switches
- 23/68 • Structural association with auxiliary mechanical devices, e.g. with clutches or brakes

24/00	<b>Machines adapted for the instantaneous transmission or reception of the angular displacement of rotating parts, e.g. synchro, selsyn</b>	33/10	• • wherein the alternate energisation and de-energisation of the single coil system is effected or controlled by movement of the armatures
25/00	<b>DC interrupter motors or generators</b>	33/12	• with armatures moving in alternate directions by alternate energisation of two coil systems
26/00	<b>Machines adapted to function as torque motors, i.e. to exert a torque when stalled</b>	33/14	• • wherein the alternate energisation and de-energisation of the two coil systems are effected or controlled by movement of the armatures
27/00	<b>AC commutator motors or generators having mechanical commutator</b>	33/16	• with polarised armatures moving in alternate directions by reversal or energisation of a single coil system
27/02	• characterised by the armature winding	33/18	• with coil systems moving upon intermittent or reversed energisation thereof by interaction with a fixed field system, e.g. permanent magnets
27/04	• having single-phase operation in series or shunt connection	35/00	<b>Generators with reciprocating, oscillating or vibrating coil system, magnet, armature or other part of the magnetic circuit</b> (arrangements for handling mechanical energy structurally associated with generators H02K 7/00, e.g. H02K 7/06)
27/06	• • with a single or multiple short-circuited commutator, e.g. repulsion motor	35/02	• with moving magnets and stationary coil systems
27/08	• • with multiple-fed armature	35/04	• with moving coil systems and stationary magnets
27/10	• • with switching devices for different modes of operation, e.g. repulsion-induction motor	35/06	• with moving flux distributors, and both coil systems and magnets stationary
27/12	• having multi-phase operation	37/00	<b>Motors with rotor rotating step by step and without interrupter or commutator driven by the rotor, e.g. stepping motors</b>
27/14	• • in series connection	37/02	• of variable reluctance type [4]
27/16	• • in shunt connection with stator feeding	37/04	• • with rotors situated within the stators [4]
27/18	• • in shunt connection with rotor feeding	37/06	• • with rotors situated around the stators [4]
27/20	• Structural association with a speed regulating device	37/08	• • with rotors axially facing the stators [4]
27/22	• having means for improving commutation, e.g. auxiliary fields, double windings, double brushes	37/10	• of permanent magnet type (H02K 37/02 takes precedence) [4]
27/24	• having two or more commutators	37/12	• • with stationary armatures and rotating magnets [4]
27/26	• having disc armature	37/14	• • • with magnets rotating within the armatures [4]
27/28	• Structural association with auxiliary electric devices influencing the characteristic of the machine or controlling the machine	37/16	• • • • having horseshoe armature cores [4]
27/30	• Structural association with auxiliary mechanical devices, e.g. with clutches or brakes	37/18	• • • • of homopolar type [4]
29/00	<b>Motors or generators having non-mechanical commutating devices, e.g. discharge tubes or semiconductor devices</b>	37/20	• • with rotating flux distributors, the armatures and magnets both being stationary [4]
29/03	• with a magnetic circuit specially adapted for avoiding torque ripples or self-starting problems [6]	37/22	• Damping units [4]
29/06	• with position sensing devices (H02K 29/03 takes precedence) [4, 6]	37/24	• Structural association with auxiliary mechanical devices [4]
29/08	• • using magnetic effect devices, e.g. Hall-plates or magneto-resistors (H02K 29/12 takes precedence) [4]	39/00	<b>Generators specially adapted for producing a desired non-sinusoidal waveform</b>
29/10	• • using light effect devices [4]	41/00	<b>Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path</b>
29/12	• • using detecting coils [4]	41/02	• Linear motors; Sectional motors [3]
29/14	• with speed sensing devices (H02K 29/03 takes precedence) [4, 6]	41/025	• • Asynchronous motors [3]
31/00	<b>Acyclic motors or generators, i.e. DC machines having drum or disc armatures with continuous current collectors</b>	41/03	• • Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3]
31/02	• with solid-contact collectors	41/035	• • DC motors; Unipolar motors [3]
31/04	• with at least one liquid-contact collector	41/06	• Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator
33/00	<b>Motors with reciprocating, oscillating or vibrating magnet, armature or coil system</b> (arrangements for handling mechanical energy structurally associated with motors H02K 7/00, e.g. H02K 7/06)	44/00	<b>Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of fluid-borne conductive or magnetic particles and a coil system or magnetic field converts energy of mass flow into electrical energy or vice versa</b> [3]
33/02	• with armatures moved one way by energisation of a single coil system and returned by mechanical force, e.g. by springs	44/02	• Electrodynamic pumps [3]
33/04	• • wherein the frequency of operation is determined by the frequency of uninterrupted AC energisation		
33/06	• • • with polarised armatures		
33/08	• • • with DC energisation superimposed on AC energisation		

- 44/04 • • Conduction pumps [3]
- 44/06 • • Induction pumps [3]
- 44/08 • Magnetohydrodynamic [MHD] generators [3]
- 44/10 • • Constructional details of electrodes [3]
- 44/12 • • Constructional details of fluid channels [3]
- 44/14 • • • Circular or screw-shaped channels [3]
- 44/16 • • Constructional details of the magnetic circuits [3]
- 44/18 • • for generating AC power [3]
- 44/20 • • • by changing the polarity of the magnetic field [3]
- 44/22 • • • by changing the conductivity of the fluid [3]
- 44/24 • • • by reversing the direction of fluid [3]
- 44/26 • • • by creating a travelling magnetic field [3]
- 44/28 • Association of MHD generators with conventional generators (nuclear power plants including a MHD generator G21D 7/02) [3]

#### 47/00 **Dynamo-electric converters**

- 47/02 • AC/DC converters or vice versa
- 47/04 • • Motor/generators
- 47/06 • • Cascade converters
- 47/08 • • Single-armature converters
- 47/10 • • • with booster machines on the AC side
- 47/12 • DC/DC converters
- 47/14 • • Motor/generators
- 47/16 • • Single-armature converters, e.g. metadyne
- 47/18 • AC/AC converters
- 47/20 • • Motor/generators
- 47/22 • • Single-armature frequency converters with or without phase-number conversion

- 47/24 • • • having windings for different numbers of poles
- 47/26 • • • operating as under- or over-synchronously running asynchronous induction machines, e.g. cascade arrangement of asynchronous and synchronous machines
- 47/28 • • • operating as commutator machines with added slip-rings
- 47/30 • • Single-armature phase-number converters without frequency conversion

#### 49/00 **Dynamo-electric clutches; Dynamo-electric brakes**

- 49/02 • of the asynchronous induction type
- 49/04 • • of the eddy-current hysteresis type
- 49/06 • of the synchronous type
- 49/08 • of the collector armature type
- 49/10 • of the permanent-magnet type
- 49/12 • of the acyclic type

#### 51/00 **Dynamo-electric gears, i.e. dynamo-electric means for transmitting mechanical power from a driving shaft to a driven shaft and comprising structurally interrelated motor and generator parts**

#### 53/00 **Alleged dynamo-electric perpetua mobilia**

#### 55/00 **Dynamo-electric machines having windings operating at cryogenic temperatures [3]**

- 55/02 • of the synchronous type [3]
- 55/04 • • with rotating field windings [3]
- 55/06 • of the homopolar type [3]

#### 99/00 ***Subject matter not provided for in other groups of this subclass [2014.01]***