SECTION H — ELECTRICITY

H02 **GENERATION, CONVERSION, OR DISTRIBUTION OF ELECTRIC POWER**

H02B BOARDS, SUBSTATIONS, OR SWITCHING ARRANGEMENTS FOR THE SUPPLY OR DISTRIBUTION OF ELECTRIC POWER (basic electric elements, their assembly, including the mounting in enclosures or on bases, or the mounting of covers thereon, see the subclasses for such elements, e.g. transformers H01F, switches, fuses H01H, line connectors H01R; installation of electric cables or lines, or of combined optical and electric cables or lines, or other conductors for supply or distribution H02G)

Note(s)

This subclass covers boards, switchyards, switchgear or their installation, or the association of switching devices with each other or with other devices, e.g. transformers, fuses, meters or distribution boards; such associations constitute substations or distribution points.

Subclass index

BOARDS, OR DETAILS OF SUBSTATIONS OR SWITCHING ARRANGEMENTS	1/00
SUBSTATIONS	5/00, 7/00
SWITCHGEAR	11/00, 13/00
SUPERVISORY DESKS OR PANELS	15/00
MANUFACTURE	

1/00	Frameworks, boards, panels, desks, casings; Details		<u>Note(s)</u>
1/01 1/015 1/03	 of substations or switching arrangements [5] Frameworks [5] Boards, panels, desks; Parts thereof or accessories therefor [5] for energy meters [5] 	1/26	 In groups H02B 1/26-H02B 1/56, in the absence of an indication to the contrary, classification is made in the last appropriate place. Casings; Parts thereof or accessories therefor (adapted for a single switch H01H; enclosures for
1/04	 Mounting thereon of switches or of other devices in general, the switch or device having, or being without, casing 		cables, lines or bus-bars H02G; distribution, connection or junction boxes H02G 3/08; casings in general H05K) [5]
1/044 1/048	 • • Mounting through openings [5] • • • Snap mounting [5] 	1/28	• dustproof, splashproof, drip-proof, waterproof or flameproof [5]
1/052 1/056	 • • Mounting on rails [5] • • Mounting on plugboards [5] 	1/30	Cabinet-type casings; Parts thereof or accessories therefor [5]
1/056	 Mounting on plugboards [5] having associated enclosures, e.g. for preventing access to live parts (shutters or guards for contacts H02B 1/14) 	1/32 1/34 1/36	 Mounting of devices therein [5] Racks [5] with withdrawable units [5]
1/14	 Shutters or guards for preventing access to contacts (shielding of isolating-contacts in withdrawable switchgear H02B 11/24) 	1/38 1/40	 Hinged covers or doors [5] Wall-mounted casings; Parts thereof or accessories therefor [5]
1/16	 Earthing arrangements (earthing arrangements for substations H02B 5/01, for switchgear H02B 11/28, H02B 13/075; earth plates, pins, or other contacts H01R 4/66) [5] 	1/42 1/44 1/46	 Mounting of devices therein [5] Hinged covers or doors [5] Boxes; Parts thereof or accessories therefor [5]
1/18	 Disposition or arrangement of fuses (for switchgear having a withdrawable carriage H02B 11/26) [5] 	1/48 1/50	 Mounting of devices therein [5] Pedestal- or pad-mounted casings; Parts thereof or
1/20	• Bus-bar or other wiring layouts, e.g. in cubicles, in switchyards (installations of bus-bars H02G 5/00)	1/52	 accessories therefor [5] Mobile units, e.g. for work sites [5]
1/21	• • Bus-bar arrangements for rack-mounted devices with withdrawable units [5]	1/54	 Anti-seismic devices or installations (for buildings in general E04B 1/98) [5]
1/22	Layouts for duplicate bus-bar selection	1/56	Cooling; Ventilation [5]
1/24	 Circuit arrangements for boards or switchyards (devices for displaying diagrams H02B 15/00; service supply H02J 11/00) 	3/00	Apparatus specially adapted for the manufacture, assembly, or maintenance of boards or switchgear
		5/00	Non-enclosed substations; Substations with enclosed and non-enclosed equipment

H02B

5/01 5/02	Earthing arrangements, e.g. earthing rods [5]mounted on pole, e.g. pole transformer substation	11/26	• Arrangement of fuses, resistors, voltage arresters or the like [5]
5/02	 gas-insulated [5] 	11/28	• Earthing arrangements [5]
7/00 7/01 7/06 7/08	 Enclosed substations, e.g. compact substations [5] gas-insulated [5] Distribution substations, e.g. for urban network (H02B 7/01 takes precedence) [5] 	13/00	Arrangement of switchgear in which switches are enclosed in, or structurally associated with, a casing e.g. cubicle (in association with main transformer H02B 5/00, H02B 7/00; switchgear having carriage withdrawable for isolation H02B 11/00) [5]
//00	Underground substations	13/01	• with resin casing [5]
11/00	Switchgear having carriage withdrawable for	13/02	with metal casing
11/02 11/04	 isolation Details Isolating-contacts, e.g. mountings, shieldings (shutters or guards for isolating contacts H02B 1/14, H02B 11/24; switch contacts H01H; line connectors in general H01R) [5] 	13/025	 Safety arrangements, e.g. in case of excessive pressure or fire due to electrical defect (for buildings in general E04B 1/94; devices for opening or closing safety wings E05F 1/00; emergency protective circuit arrangements for distribution gear, e.g. bus-bar systems, or for
11/06	• • Means for duplicate bus-bar selection (layouts for	10 (005	switching devices H02H 7/22) [5]
	duplicate bus-bar selection H02B 1/22)		• • Gas-insulated switchgear [5]
11/08	Oil-tank lowering means associated with withdrawal mechanism		• • Details of casing, e.g. gas tightness (gas reservoirs for switches H01H 33/56) [5]
11/10	 Indicating electrical condition of gear; Arrangement of test sockets 	13/055	• • Features relating to the gas (selection of fluids for switches H01H 33/22) [5]
11/12 11/127	with isolation by horizontal withdrawalWithdrawal mechanism [5]	13/065	 Means for detecting or reacting to mechanical or electrical defects (for switches H01H 9/50, H01H 33/26, H01H 33/53) [5]
11/133	• • with interlock (interlock for switches in general H01H) [5]	13/075	• • • Earthing arrangements [5]
11/167	 truck type (H02B 11/127 takes precedence) [5] 	13/08	• with stone, brick, or concrete casing
11/173	• • drawer type (H02B 11/127 takes precedence) [5]	15/00	Supervisory desks or panels for centralised control
11/18	 with isolation by vertical withdrawal 		or display (desks in general A47B)
11/20	having an enclosure	15/02	with mimic diagrams
11/22	 wherein front of enclosure moves with carriage upon horizontal withdrawal subsequent to 	15/04	• • consisting of building blocks
11/24	isolationShutters or guards [5]	99/00	Subject matter not provided for in other groups of this subclass [2009.01]

H02G INSTALLATION OF ELECTRIC CABLES OR LINES, OR OF COMBINED OPTICAL AND ELECTRIC CABLES OR LINES (insulated conductors or cables with arrangements for facilitating mounting or securing H01B 7/40; distribution points incorporating switches H02B; guiding telephone cords H04M 1/15; cable ducts or mountings for telephone or telegraph exchange installations H04Q 1/06)

<u>Note(s)</u>

- 1. This subclass <u>covers</u> installation of communication cables or lines, including those comprising a combination of optical and electrical conductors, or of lightning conductors as well as installation of power cables or lines.
- 2. This subclass <u>does not cover</u> installation of purely optical cables, which is covered by group G02B 6/46.
- 3. In this subclass, the following expression is used with the meaning indicated:
- "electric cable" includes cables comprising optical conductors, e.g. fibres, in combination with electrical conductors.

Subclass index

PRINCIPAL TYPES OF INSTALLATIONS	
Inside; overhead; underground or underwater	
SPECIAL INSTALLATIONS	
Of bus-bars; of lightning conductors; of movable parts	5/00, 13/00, 11/00
CABLE FITTINGS.	15/00
INSTALLING, MAINTAINING, REPAIRING	1/00

1/00	Methods or apparatus specially adapted for installing, maintaining, repairing, or dismantling electric cables or lines	 for laying cables, e.g. laying apparatus on vehicle (combined with trench digging or back-filling machines or dredgers E02F 5/00)
1/02 1/04	 for overhead lines or cables for mounting or stretching (wire stretchers in general B25B 25/00) 	 1/08 • through tubing or conduit, e.g. rod or draw wire for pushing or pulling 1/10 • in or under water

1/12	 for removing insulation or armouring from cables,
	e.g. from the end thereof (pliers in general B25B;
	cutters in general B26B; insulated conductors or
	cables with arrangements for facilitating removal of
1/14	insulation H01B 7/38)for joining or terminating cables (joining electric
1/14	 for joining or terminating cables (joining electric conductors H01R 43/00)
1/16	 for repairing insulation or armouring of cables
3/00	Installations of electric cables or lines or protective
	tubing therefor in or on buildings, equivalent
	structures or vehicles (installations of bus-bars
	H02G 5/00; overhead installations H02G 7/00; installations in or on the ground H02G 9/00; channels or
	vertical ducts for receiving utility lines E04F 17/08;
	wiring of electric apparatus in general H05K)
3/02	• Details
3/03	• • Cooling [2]
3/04	• • Protective tubing or conduits, e.g. cable ladders,
	cable troughs (pipes or tubing in general F16L)
3/06	• • Joints for connecting lengths of protective tubing
	to each other or to casings, e.g. to distribution box;
3/08	Ensuring electrical continuity in the jointDistribution boxes; Connection or junction boxes
5/00	(cable terminations H02G 15/02)
3/10	 • for surface mounting on a wall
3/12	• • • for flush mounting
3/14	• • • Fastening of cover or lid to box
3/16	• • • structurally associated with support for line-
	connecting terminals within the box (terminals
D (40	H01R 9/00)
3/18	• • • providing line outlets
3/20 3/22	• • • • Ceiling roses
5/22	• Installations of cables or lines through walls, floors, or ceilings, e.g. into buildings (devices for use where
	pipes or cables pass through walls or partitions
	F16L 5/00; lead-in or lead-through insulators
	H01B 17/26; insulating tubes or sleeves H01B 17/58)
3/30	• Installations of cables or lines on walls, floors or
	ceilings (supports for pipes, cables or protective tubing F16L 3/00; hose-clips F16L 33/02) [7]
3/32	 using mounting clamps [7]
3/34	 using inounting champs [7] using separate protective tubing [7]
3/36	 Installations of cables or lines in walls, floors or
	ceilings (H02G 3/22 takes precedence) [7]
3/38	• • the cables or lines being installed in preestablished
	conduits or ducts [7]
3/40	• • using separate protective tubing in the conduits or ducts [7]
	or ducts [7]
5/00	Installations of bus-bars
5/02	Open installations
5/04	Partially-enclosed installations, e.g. in ducts and
	adapted for sliding or rolling current collection (non-
E /06	rotary current collectors H01R 41/00)
5/06 5/08	 Totally-enclosed installations, e.g. in metal casings Connection boxes therefor
5/08	Cooling [2]
5/10	
7/00	Overhead installations of electric lines or cables
	(installations of bus-bars H02G 5/00; trolley wires or contact lines for electric railways B60M; fastening
	conductors to insulators H01B 17/00, e.g. H01B 17/06,
	H01B 17/16, H01B 17/22; protection against abnormal
	electric conditions H01H; hook contacts for temporary
	connections to overhead lines H01R 11/14)
7/02	Devices for adjusting or maintaining mechanical

7/02 Devices for adjusting or maintaining mechanical tension, e.g. take-up device

- 7/04 Arrangements or devices for relieving mechanical tension
- 7/05 Suspension arrangements or devices for electric cables or lines **[3]**
- 5. Suspensions for lines or cables along a separate supporting wire, e.g. S-hook [3]
- 7/08 • Members clamped to the supporting wire or to the line or cable **[3]**
- 7/10 • Flexible members or lashings wrapped around both the supporting wire and the line or cable [3]
- 7/12 Devices for maintaining distance between parallel conductors, e.g. spacer
- 7/14 Arrangements or devices for damping mechanical oscillations of lines, e.g. for reducing production of sound
- 7/16 Devices for removing snow or ice from lines or cables (from insulators H01B 17/52)
- 7/18 Devices affording mechanical protection in the event of breakage of a line or cable, e.g. net for catching broken lines
- 7/20 Spatial arrangements or dispositions of lines or cables on poles, posts, or towers (construction of poles, posts, or towers E04H 12/22)
- 7/22 Arrangements of earthing wires suspended between mastheads
- **9/00** Installations of electric cables or lines in or on the ground or water (cathodic protection C23F 13/02; detection of buried cables G01V)
- 9/02 laid directly in or on the ground, river-bed or seabottom; Coverings therefor, e.g. tile
- 9/04 in surface ducts; Ducts or covers therefor
- 9/06 in underground tubes or conduits; Tubes or conduits therefor
- 9/08 in tunnels
- 9/10 in cable chambers, e.g. in manhole, in handhole (building aspects of cable chambers section E, e.g. E04H 5/06)
- 9/12 supported on or from floats, e.g. in water (floating cables H01B 7/12)
- 11/00 Arrangements of electric cables or lines between relatively-movable parts (current collectors H01R)
- 11/02 using take-up reel or drum
- 13/00 Installations of lightning conductors; Fastening thereof to supporting structure (indicating, counting or recording lightning strokes G01; lightning arrestors H01C 7/12, H01C 8/04, H01G 9/18, H01T; earth plates, pins or other contacts H01R)

15/00 Cable fittings

15/007	 Devices for relieving mechanical stress [3]
15/013	• Sealing means for cable inlets (inlets for cables filled
	with, or surrounded by, gas or oil H02G 15/32) [3]
15/02	Cable terminations (for gas- or oil-filled cables
	H02G 15/22)
15/04	Cable-end sealings
15/06	• • Cable terminating boxes, frames, or other
	structures (terminal blocks H01R 9/00)
15/064	• • • with devices for relieving electrical stress [3]
15/068	• • • connected to the cable shield only
	(H02G 15/072 takes precedence) [3]
15/072	• • • • of the condenser type [3]
15/076	• • • for multi-conductor cables [3]

H02G

 Cable junctions (for gas or oil filled cables H02G 15/24; disconnectable junctions, electrical connections H01R) 	 15/18 • protected by sleeves, e.g. for communication cable (two-part covers H02G 15/10) 15/184 • • with devices for relieving electrical stress [3]
 15/10 • protected by boxes, e.g. by distribution, connection or junction boxes (terminal blocks H01R 9/00) 15/103 • • with devices for relieving electrical stress [3] 	 15/188 • • • • connected to cable shield only [3] 15/192 • • with support means for ends of the sleeves [3] 15/196 • • having lapped insulation [3] 15/20 • Cable fittings for cables filled with or surrounded by
 15/105 • • • • connected to the cable shield only (H02G 15/107 takes precedence) [3] 15/107 • • • • of the condenser type [3] 15/113 • • • Boxes split longitudinally in main cable 	gas or oil (H02G 15/34 takes precedence) [3] 15/22 • Cable terminations 15/23 • Cable-end sealings [3] 15/24 • Cable junctions
direction [3] 15/115 • • • Boxes split perpendicularly to main cable direction [3] 15/117 • • • for multiconductor cables [3]	 15/25 • • Stop junctions [3] 15/26 • Expansion vessels; Locking heads; Auxiliary pipelines
 15/12 • • • for incorporating transformers, loading coils or amplifiers 15/14 • • • specially adapted for submarine cables 15/16 • • • structurally associated with support for line-connecting terminals within the box 	 15/28 • structurally associated with devices for indicating the presence or location of non-electric faults (combined with electric protective means H02H) 15/30 • with devices for relieving electrical stress [3] 15/32 • Cable inlets [3] 15/34 • Cable fittings for cryogenic cables [3]

H02H EMERGENCY PROTECTIVE CIRCUIT ARRANGEMENTS (indicating or signalling undesired working conditions G01R, e.g. G01R 31/00, G08B; locating faults along lines G01R 31/08; emergency protective devices H01H)

<u>Note(s)</u>

This subclass <u>covers</u> only circuit arrangements for the automatic protection of electric lines or electric machines or apparatus in the event of an undesired change from normal working conditions.

Subclass index

EMERGENCY PROTECTIVE CIRCUIT ARRANGEMENTS	
For automatic disconnection or switching responsive to variation of conditions:	
electric; sensed non-electric; simulated non-electric	
adapted for specific machines or for sectionalised protection of cables or lines	7/00
For limiting excess current or voltage	
For preventing switching-on in case of undesired conditions	
DETAILS	

1/04	 Details of emergency protective circuit arrangements Arrangements for preventing response to transient abnormal conditions, e.g. to lightning Arrangements for supplying operative power [3] 	 3/07 • • • and with permanent disconnection after a predetermined number of reconnection cycles [3] 3/08 • responsive to excess current (responsive to abnormal temperature caused by excess current H02H 5/04)
3/02 3/027 3/033 3/04	 Emergency protective circuit arrangements for automatic disconnection directly responsive to an undesired change from normal electric working condition, with or without subsequent reconnection (specially adapted for specific types of electric machines or apparatus or for sectionalised protection of cable or line systems H02H 7/00; systems for change-over to standby supply H02J 9/00) Details with automatic disconnection after a predetermined time (H02H 3/033, H02H 3/06 take precedence) [3] with several disconnections in a preferential order (H02H 3/06 takes precedence) [3] with warning or supervision in addition to disconnection, e.g. for indicating that protective apparatus has functioned with means for increasing reliability, e.g. redundancy arrangements [3] with automatic reconnection 	 3/087 • for dc applications [3] 3/093 • with timing means [3] 3/10 • additionally responsive to some other abnormal electrical conditions 3/12 • responsive to underload or no-load 3/13 • for multiphase applications, e.g. phase interruption [3] 3/14 • responsive to occurrence of voltage on parts normally at earth potential 3/16 • responsive to fault current to earth, frame or mass (with balanced or differential arrangement H02H 3/26) 3/17 • by means of an auxiliary voltage injected into the installation to be protected [3] 3/18 • responsive to reversal of direct current 3/20 • responsive to excess voltage 3/22 • of short duration, e.g. lightning 3/24 • responsive to undervoltage or no-voltage 3/247 • having timing means [3]

3/253	• • for multiphase applications, e.g. phase
D (04	interruption [3]
3/26	 responsive to difference between voltages or between currents; responsive to phase angle between voltages or between currents
3/28	 involving comparison of the voltage or current
	values at two spaced portions of a single system, e.g. at opposite ends of one line, at input and output of apparatus
3/30	• • using pilot wires or other signalling channel
3/32	• • involving comparison of the voltage or current
	values at corresponding points in different
	conductors of a single system, e.g. of currents in
3/33	go and return conductors
3/33	• • • using summation current transformers (H02H 3/347 takes precedence) [3]
3/34	 of a three-phase system
3/347	• • • using summation current transformers [3]
3/353	• • • • involving comparison of phase voltages [3]
3/36	 involving comparison of the voltage or current values at corresponding points of different systems, e.g. of parallel feeder systems
3/38	 responsive to both voltage and current; responsive to
	phase angle between voltage and current
3/40	 responsive to ratio of voltage and current
3/42	 responsive to product of voltage and current
3/44	responsive to the rate of change of electrical
2/46	quantities [3]
3/46	 responsive to frequency deviations [3] responsive to loss of sumphropium [2]
3/48 3/50	responsive to loss of synchronism [3]responsive to the appearance of abnormal wave
3/30	 responsive to the appearance of abnormal wave forms, e.g. ac in dc installations [3]
3/52	• responsive to the appearance of harmonics [3]
5/00	For any second state strength and state strength for
5/00	Emergency protective circuit arrangements for automatic disconnection directly responsive to an undesired change from normal non-electric working conditions with or without subsequent reconnection (using simulators of the apparatus being protected H02H 6/00; specially adapted for specific types of electric machines or apparatus or for sectionalised
	protection of cable or line systems H02H 7/00) [3]
5/04 5/06	 responsive to abnormal temperature in oil filled electric apparatus
5/06	 in oil-filled electric apparatus responsive to abnormal fluid pressure, liquid level or
5700	liquid displacement, e.g. Buchholz relays
5/10	• responsive to mechanical injury, e.g. rupture of line,
	breakage of earth connection
5/12	 responsive to undesired approach to, or touching of, live parts by living beings
6/00	Emergency protective circuit arrangements responsive to undesired changes from normal non- electric working conditions using simulators of the apparatus being protected, e.g. using thermal images [3]
7/00	Emergency protective circuit arrangements specially adapted for specific types of electric machines or apparatus or for sectionalised protection of cable or line systems, and effecting automatic switching in the event of an undesired change from normal working conditions (structural association of protective devices with specific machines or apparatus and their protection without automatic disconnection, <u>see</u> the relevant subclass for the machine or apparatus)

7/04	• for transformers
7/045	• • Differential protection of transformers [3]
7/05	 for capacitive voltage transformers, e.g. against resonant conditions [3]
7/055	 for tapped transformers or tap-changing means thereof [3]
7/06	 for dynamo-electric generators; for synchronous capacitors
7/08	for dynamo-electric motors
7/085	• against excessive load
7/09	 against over-voltage; against reduction of voltage; against phase interruption
7/093	 against increase beyond, or decrease below, a predetermined level of rotational speed (centrifugal switches H01H 35/10)
7/097	 against wrong direction of rotation
7/10	 for converters; for rectifiers
7/12	• • for static converters or rectifiers
7/122	• • • for inverters, i.e. dc/ac converters [2]
7/125	• • • for rectifiers [2]
7/127	• • • having auxiliary control electrode to which blocking control voltages or currents are applied in case of emergency [2]
7/16	 for capacitors (for synchronous capacitors H02H 7/06)
7/18	 for batteries; for accumulators
7/20	 for electronic equipment (for converters H02H 7/10; for electric measuring instruments G01R 1/36; for dc voltage or current semiconductor regulators G05F 1/569; for amplifiers H03F 1/52; for electronic switching circuits H03K 17/08)
7/22	 for distribution gear, e.g. bus-bar systems; for switching devices
7/24	for spark-gap arresters
7/26	• Sectionalised protection of cable or line systems, e.g.
	for disconnecting a section on which a short-circuit, earth fault, or arc discharge has occurred (locating faults in cables G01R 31/08)
7/28	 for meshed systems
7/30	Staggered disconnection [3]
9/00	Emergency protective circuit arrangements for limiting excess current or voltage without disconnection (structural association of protective devices with specific machines or apparatus, <u>see</u> the relevant subclass for the machine or apparatus)
9/02	 responsive to excess current
9/04	 responsive to excess voltage (lightning arrestors H01C 7/12, H01C 8/04, H01G 9/18, H01T)
9/06	 using spark-gap arresters
9/08	• Limitation or suppression of earth fault currents, e.g. Petersen coil [3]
11/00	Emergency protective circuit arrangements for preventing the switching-on in case an undesired electric working condition might result
99/00	Subject matter not provided for in other groups of

99/00 Subject matter not provided for in other groups of this subclass [2009.01]

H02J CIRCUIT ARRANGEMENTS OR SYSTEMS FOR SUPPLYING OR DISTRIBUTING ELECTRIC POWER; SYSTEMS FOR STORING ELECTRIC ENERGY (power supply circuits for apparatus for measuring X-radiation, gamma radiation, corpuscular radiation or cosmic radiation G01T 1/175; electric power supply circuits specially adapted for use in electronic time-pieces with no moving parts G04G 19/00; for digital computers G06F 1/18; for discharge tubes H01J 37/248; circuits or apparatus for the conversion of electric power, arrangements for control or regulation of such circuits or apparatus H02M; interrelated control of several motors, control of a prime-mover/generator combination H02P; control of high-frequency power H03L; additional use of power line or power network for transmission of information H04B)

<u>Note(s)</u>

- 1. This subclass <u>covers</u>:
 - ac or dc mains or distribution networks;
 - circuit arrangements for battery supplies, including charging or control thereof, or co-ordinated supply from two or more sources of any kind;
 - systems for supplying or distributing electric power by electromagnetic waves.
- 2. This subclass <u>does not cover</u>:
 - control of a single motor, generator or dynamo-electric converter, of the types covered by subclass H01F or H02K, which is covered by subclass H02P;
 - control of a single motor or generator, of the types covered by subclass H02N, which is covered by that subclass.

Subclass index

CIRCUIT ARRANGEMENTS

For distribution networks:

direct current; alternative current	
combined; not specified	
For batteries	7/00
For emergency or stand-by power supply	
For power supply to auxiliaries of stations	
For providing remote indication of network conditions	
SYSTEMS FOR STORING ELECTRICAL ENERGY	
SYSTEMS FOR POWER DISTRIBUTION BY ELECTROMAGNETIC WAVES	

1/00	Circuit arrangements for dc mains or dc distribution
	networks

- 1/02 Arrangements for reducing harmonics or ripples (in converters H02M 1/14)
- 1/04 Constant-current supply systems
- 1/06 Two-wire systems
- 1/08 Three-wire systems; Systems having more than three wires
- 1/10 Parallel operation of dc sources (involving batteries H02J 7/34)
- 1/12 Parallel operation of dc generators with converters, e.g. with mercury-arc rectifier
- 1/14 Balancing the load in a network (by batteries H02J 7/34)
- 1/16 using dynamo-electric machines coupled to flywheels

3/00 Circuit arrangements for ac mains or ac distribution networks

- 3/01 Arrangements for reducing harmonics or ripples (in converters H02M 1/12) [3]
- using a single network for simultaneous distribution of power at different frequencies; using a single network for simultaneous distribution of ac power and of dc power
- 3/04 for connecting networks of the same frequency but supplied from different sources
- 3/06 Controlling transfer of power between connected networks; Controlling sharing of load between connected networks
- 3/08 • Synchronising of networks
- 3/10 Constant-current supply systems

- 3/12 for adjusting voltage in ac networks by changing a characteristic of the network load
- 3/14 by switching loads on to, or off from, network, e.g. progressively balanced loading
- 3/16 • by adjustment of reactive power
- 3/18 Arrangements for adjusting, eliminating, or compensating reactive power in networks (for adjustment of voltage H02J 3/12; use of Petersen coils H02H 9/08)
- 3/20 in long overhead lines
- 3/22 • in cables
- 3/24 Arrangements for preventing or reducing oscillations of power in networks (by control effected upon a single generator H02P 9/00)
- 3/26 Arrangements for eliminating or reducing asymmetry in polyphase networks
- 3/28 Arrangements for balancing the load in a network by storage of energy
- 3/30 using dynamo-electric machines coupled to flywheels
- 3/32 • using batteries with converting means
- 3/34 Arrangements for transfer of electric power between networks of substantially different frequency (frequency converters H02M)
- 3/36 Arrangements for transfer of electric power between ac networks <u>via</u> a high-tension dc link
- 3/38 Arrangements for parallelly feeding a single network by two or more generators, converters, or transformers
- 3/40 Synchronising a generator for connection to a network or to another generator

3/42	• • • with automatic parallel connection when synchronism is achieved	7/28	• • • using magnetic devices with controllable degree of saturation in combination with
3/44	• • • with means for ensuring correct phase sequence		controlled discharge tube or controlled
3/46	• • Controlling the sharing of output between the		semiconductor device
	generators, converters, or transformers	7/30	• • using armature-reaction-excited machines
3/48	Controlling the sharing of the in-phase component	7/32	 for charging batteries from a charging set comprising a non-electric prime mover
3/50	Controlling the sharing of the out-of-phase component	7/34	• Parallel operation in networks using both storage and other dc sources, e.g. providing buffering (H02J 7/14 takes precedence) [4]
4/00	Circuit arrangements for mains or distribution	7/35	• • with light sensitive cells [4]
	networks not specified as ac or dc [2]	7/36	Arrangements using end-cell switching
5/00	Circuit arrangements for transfer of electric power between ac networks and dc networks (H02J 3/36 takes precedence)	9/00	Circuit arrangements for emergency or stand-by power supply, e.g. for emergency lighting (with provision for charging standby battery H02J 7/00)
7/00	Circuit arrangements for charging or depolarising batteries or for supplying loads from batteries	9/02	 in which an auxiliary distribution system and its associated lamps are brought into service
7/02	 for charging batteries from ac mains by converters 	9/04	• in which the distribution system is disconnected from
7/04	 Regulation of the charging current or voltage 	0 / 0 0	the normal source and connected to a standby source
7/06	 • using discharge tubes or semiconductor devices 	9/06	• • with automatic change-over
7/08	• • • • using discharge tubes only	9/08	• • • requiring starting of a prime-mover
7/10	• • • • using semiconductor devices only	11/00	Circuit arrangements for providing service supply to
7/12	 • using magnetic devices having controllable degree of saturation, i.e. transductors 		auxiliaries of stations in which electric power is generated, distributed, or converted (emergency or
7/14	 for charging batteries from dynamo-electric 		standby arrangements H02J 9/00)
	generators driven at varying speed, e.g. on vehicle	40.00	
7/16	Regulation of the charging current or voltage by variation of field	13/00	Circuit arrangements for providing remote indication of network conditions, e.g. an
7/18	 • due to variation of ohmic resistance in field circuit, using resistance switching in or out of circuit step by step 		instantaneous record of the open or closed condition of each circuitbreaker in the network; Circuit arrangements for providing remote control of
7/20	• • • due to variation of continuously-variable ohmic resistor		switching means in a power distribution network, e.g. switching in and out of current consumers by using a pulse code signal carried by the network
7/22	• • • due to variation of make-to-break ratio of	4 = (00	
	intermittently-operating contacts, e.g. using Tirrill regulator	15/00	Systems for storing electric energy (mechanical systems therefor F01-F04; in chemical form H01M) [2]
7/24	• • • using discharge tubes or semiconductor devices	17/00	Systems for supplying or distributing electric nower
			Systems for subniving or distributing electric nower

- 17/00 Systems for supplying or distributing electric power by electromagnetic waves [3]
- H02K DYNAMO-ELECTRIC MACHINES (dynamo-electric relays H01H 53/00; conversion of DC or AC input power into surge output power H02M 9/00)

Note(s)

7/26

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1. This subclass <u>covers</u> the structural adaptation of dynamo-electric machines for the purpose of their control.

using magnetic devices with controllable

degree of saturation

- 2. This subclass <u>does not cover</u> starting, regulating, electronically commutating, braking, or otherwise controlling motors, generators or dynamo-electric converters, in general, which is covered by subclass H02P.
- 3. Attention is drawn to the Notes following the titles of class B81 and subclass B81B relating to "micro-structural devices" and "microstructural systems".

Subclass index

GENERATORS OR MOTORS

Continuously rotating

AC machines: asynchronous; synchronous; with mechanical commutators	17/00,	19/00, 21/00, 27/00
DC machines or universal AC/DC motors: with mechanical commutators; with interrupters	23/00,	25/00
with non-mechanical commutating devices	29/00	
Acyclic machines; oscillating machines; motors rotating step by step	31/00,	33/00, 35/00, 37/00
Generators producing a non-sinusoidal waveform	39/00	
Machines with more than one rotor or stator	16/00	
SPECIAL DYNAMO-ELECTRIC APPARATUS		
Machines for transmitting angular displacements; torque motors	24/00,	26/00
Machines involving dynamo-electric interaction with a plasma or a flow of conductive liquid or of		
fluid-borne conductive or magnetic particles	44/00	

Systems for propulsing a rigid body along a path	
Converters	
Dynamo-electric clutches or brakes; dynamo-electric gears	
Alleged perpetua mobilia	
Machines operating at cryogenic temperatures	
Other machines	
DETAILS	
Magnetic circuits; windings; casings	
Arrangements structurally associated with the machine for handling mechanical energy; cooling;	
measuring or protective devices; current collection or commutation	
MANUFACTURE	

1/00	Details of the magnetic circuit (magnetic circuits for relays H01H 50/16)
1/02	 characterised by the magnetic material
1/04	 characterised by the material used for insulating the
	magnetic circuit or parts thereof
1/06	 characterised by the shape, form or construction
1/08	Salient poles
1/10	• • Commutating poles
1/12	Stationary parts of the magnetic circuit
1/14	• • Stator cores with salient poles
1/16	• • Stator cores with slots for windings
1/17	• • • Stator cores with permanent magnets [5]
1/18	• • Means for mounting or fastening magnetic stationary parts on to, or to, the stator structures
1/20	• • with channels or ducts for flow of cooling medium
1/22	Rotating parts of the magnetic circuit
1/24	• • • Rotor cores with salient poles
1/26	• • Rotor cores with slots for windings
1/27	• • • Rotor cores with permanent magnets [5]
1/28	• • • Means for mounting or fastening rotating magnetic parts on to, or to, the rotor structures
1/30	• • • • using intermediate parts, e.g. spiders
1/32	• • • with channels or ducts for flow of cooling medium
1/34	• • Reciprocating, oscillating or vibrating parts of the magnetic circuit
3/00	Details of windings
3/02	 Windings characterised by the conductor material
3/04	• Windings characterised by the conductor shape, form
	or construction, e.g. with bar conductors
3/12	arranged in slots
3/14	• • with transposed conductors, e.g. twisted conductors
3/16	 for auxiliary purposes, e.g. damping or commutating
3/18	Windings for salient poles
3/20	 for auxiliary purposes, e.g. damping or commutating
3/22	consisting of hollow conductors
3/24	 with channels or ducts for cooling medium between the conductors
3/26	consisting of printed conductors
3/28	 Layout of windings or of connections between
	windings (windings for pole-changing H02K 17/06, H02K 17/14, H02K 19/12, H02K 19/32)
3/30	• Windings characterised by the insulating material
3/32	• Windings characterised by the shape, form or construction of the insulation

3/34	•	 between conductors or between conductor and core, e.g. slot insulation [3]
3/38	•	• around winding heads, equalising connectors, or connections thereto
3/40	•	• for high voltage, e.g. affording protection against corona discharges
3/42	•	Means for preventing or reducing eddy-current losses in the winding heads, e.g. by shielding [2]
3/44	•	Protection against moisture or chemical attack; Windings specially adapted for operation in liquid or
		gas
3/46	•	5 5
3/47	•	 Air-gap windings, i.e. iron-free windings [3]
3/48	•	• in slots
3/487	•	Slot-closing devices [3]
3/493	•	• • • magnetic [3]
3/50	•	• Fastening of winding heads, equalising
		connectors, or connections thereto
3/51	•	• • applicable to rotors only [3]
3/52	•	 Fastening salient pole windings or connections
0,01		thereto
5/00	С	asings; Enclosures; Supports
5/02	•	Casings or enclosures characterised by the material
		thereof
5/04	•	Casings or enclosures characterised by the shape,
= /0.0		form or construction thereof
5/06	•	Cast metal casings
5/08	•	Insulating casings
5/10	•	• with arrangements for protection from ingress, e.g. of water or fingers
5/12	•	• specially adapted for operating in liquid or gas (combined with cooling arrangements H02K 9/00)
5/124	•	 Sealing of shafts [3]
5/128	•	• • using air-gap sleeves or air-gap discs [3]
5/132	•	• • Submersible electric motors (H02K 5/128 takes precedence) [3]
5/136	•	• • explosion-proof [3]
5/14	•	 Means for supporting or protecting brushes or brush holders [3]
5/15	•	 Mounting arrangements for bearing-shields or end plates [3]
5/16	•	• Means for supporting bearings, e.g. insulating
		supports or means for fitting bearings in the bearing-shields (magnetic bearings H02K 7/09)
5/167	•	 using sliding-contact or spherical cap bearings [3]
5/173	•	• • using bearings with rolling contact, e.g. ball bearings [3]
5/18	•	• with ribs or fins for improving heat transfer
5/20	•	• with channels or ducts for flow of cooling medium
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H02K

5/22	• • Auxiliary parts of casings not covered by groups
	H02K 5/06-H02K 5/20, e.g. shaped to form
E /0.4	connection boxes or terminal boxes
5/24	 specially adapted for suppression or reduction of noise or vibrations
5/26	 Means for adjusting casings relative to their supports
7/00	Arrangements for handling mechanical energy
1,00	structurally associated with dynamo-electric
	machines, e.g. structural association with mechanical
	driving motors or auxiliary dynamo-electric machines
7/02	 Additional mass for increasing inertia, e.g. flywheels
7/02	 Balancing means
7/04	Means for converting reciprocating motion into
	rotary motion or <u>vice versa</u>
7/065	Electromechanical oscillators; Vibrating magnetic
	drives [3]
7/07	• using pawls and ratchet wheels [3]
7/075	• using crankshafts or eccentrics [3]
7/08 7/09	 Structural association with bearings with magnetic bearings [3]
7/10	 Structural association with clutches, brakes, gears,
//10	pulleys or mechanical starters
7/102	with friction brakes
7/104	• • with eddy-current brakes
7/106	with dynamo-electric brakes
7/108	with friction clutches
7/11	• • with dynamo-electric clutches
7/112	• with friction clutches in combination with brakes
7/114	 with dynamo-electric clutches in combination with brakes
7/116	• • with gears
7/118	with starting devices
7/12	• with auxiliary limited movement of stators, rotors
	or core parts, e.g. rotors axially movable for the purpose of clutching or braking
7/14	 Structural association with mechanical loads, e.g.
	with hand-held machine tools or fans (with fan or
	impeller for cooling the machine H02K 9/06)
7/16	 for operation above the critical speed of vibration of the rotating parts
7/18	Structural association of electric generators with
7/20	mechanical driving motors, e.g. with turbines
7/20	• Structural association with auxiliary dynamo-electric machines, e.g. with electric starter motors or exciters
9/00	Arrangements for cooling or ventilating (channels or
	ducts in parts of the magnetic circuit H02K 1/20,
	H02K 1/32; channels or ducts in or between conductors
9/02	H02K 3/22, H02K 3/24)
9/02 9/04	 by ambient air flowing through the machine having means for generating a flow of cooling
5704	medium
9/06	• • • with fans or impellers driven by the machine
0.100	shaft
9/08	 by gaseous cooling medium circulating wholly within the machine casing (H02K 9/10 takes precedence)
9/10	 by gaseous cooling medium flowing in closed circuit, a part of which is external to the machine casing
9/12	• • wherein the cooling medium circulates freely
	within the casing
9/14	 wherein gaseous cooling medium circulates between the machine casing and a surrounding mentle
9/16	the machine casing and a surrounding mantlewherein the cooling medium circulates through
01 / E	 wherein the cooling medium circulates through ducts or tubes within the casing

9/18	 wherein the external part of the closed circuit comprises a heat exchanger structurally associated with the machine casing
9/19	 for machines with closed casing and closed-circuit cooling using a liquid cooling medium, e.g. oil
9/193	 with provision for replenishing the cooling medium; with means for preventing leakage of the cooling medium
9/197	 in which the rotor or stator space is fluid-tight, e.g. to provide for different cooling media for rotor and stator
9/20	 wherein the cooling medium vaporises within the machine casing
9/22	 by solid heat conducting material embedded in, or arranged in contact with, the stator or rotor, e.g. heat bridges
9/24	• Protection against failure of cooling arrangements, e.g. due to loss of cooling medium or due to interruption of the circulation of cooling medium
9/26	• Structural association of machines with devices for cleaning or drying cooling medium, e.g. with filters
9/28	 Cooling of commutators, slip-rings or brushes, e.g. by ventilating
11/00	Structural association of dynamo-electric machines with measuring or protective devices or electric components, e.g. with resistors or switches
11/02	 for suppression of radio interference [6]
11/04	• for rectification [6]
13/00	Structural associations of current collectors with motors or generators, e.g. brush mounting plates or connections to windings (supporting or protecting brushes or brush holders in motor casings or enclosures H02K 5/14); Disposition of current collectors in motors or generators; Arrangements for improving commutation
13/02	 Connections between slip-rings and windings
13/02	 Connections between commutator segments and windings
13/06	Resistive connections, e.g. by high-resistance chokes or by transistors
13/08	• • Segments formed by extensions of the winding
13/10	• Arrangements of brushes or commutators specially adapted for improving commutation
13/12	• Arrangements for producing an axial reciprocation of the rotor and its associated current collector part, e.g. for polishing commutator surfaces
13/14	• Circuit arrangements for improvement of commutation, e.g. by use of unidirectionally conductive elements
15/00	Methods or apparatus specially adapted for
	manufacturing, assembling, maintaining or repairing
	of dynamo-electric machines
15/02	 of stator or rotor bodies
15/03	 having permanent magnets [5]
15/04	• of windings, prior to mounting into machines (insulating windings H02K 15/10, H02K 15/12)
15/06	Embedding prefabricated windings in machines
15/08	 Forming windings by laying conductors into or around core parts
15/085	• • by laying conductors into slotted stators
15/09	 by laying conductors into slotted rotors
15/095	
15/10	

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15/12	 Impregnating, heating or drying of windings, stators,
15/14	rotors or machinesCasings; Enclosures; Supports
15/16	Centering rotors within the stator; Balancing rotors
16/00	Machines with more than one rotor or stator [2]
16/02	Machines with one stator and two rotors [2]
16/04	 Machines with one rotor and two stators [2]
	<u>Note(s)</u>
	Group H02K 16/00 takes precedence over groups H02K 17/00-H02K 53/00.
	H02K 17/00-H02K 55/00.
17/00	Asynchronous induction motors; Asynchronous
17/00	induction generators
17/02	Asynchronous induction motors
17/04	for single phase current
17/06	• • having windings arranged for permitting pole- changing
17/08	• • • Motors with auxiliary phase obtained by
17700	externally fed auxiliary windings, e.g. capacitor
	motors
17/10	• • • Motors with auxiliary phase obtained by split-
17,10	pole carrying short-circuited windings
17/12	for multi-phase current
17/14	• • • having windings arranged for permitting pole-
	changing
17/16	 having rotors with internally short-circuited
	windings, e.g. cage rotors
17/18	 having double-cage or multiple-cage rotors
17/20	• • • having deep-bar rotors
17/22	 having rotors with windings connected to slip-
	rings
17/24	• • • in which both stator and rotor are fed with AC
17/26	 having rotors or stators designed to permit
4 - 100	synchronous operation
17/28	having compensating winding for improving phase angle
17/30	 Structural association of asynchronous induction
17700	motors with auxiliary electric devices influencing
	the characteristics of the motor or controlling the
	motor, e.g. with impedances or switches
17/32	Structural association of asynchronous induction
	motors with auxiliary mechanical devices, e.g.
	with clutches or brakes
17/34	Cascade arrangement of an asynchronous motor with another dynamo-electric motor or converter
17/36	 • with another asynchronous induction motor
17/38	• • • with a commutator machine
17/40	 • with a rotary AC/DC converter
17/40	 Asynchronous induction generators (H02K 17/02
1//44	takes precedence) [4]
17/44	 Structural association with exciting machines
	U U
19/00	Synchronous motors or generators (having permanent
	magnets H02K 21/00)
19/02	Synchronous motors
19/04	for single-phase current
19/06	• • Motors having windings on the stator and a
	variable-reluctance soft-iron rotor without
10/00	windings, e.g. inductor motors
19/08	 Motors having windings on the stator and a smooth rotor without windings of material with
	large hysteresis, e.g. hysteresis motors
19/10	 for multi-phase current
10/10	

19/12	•	•	 characterised by the arrangement of exciting windings, e.g. for self-excitation, compounding or pole changing
19/14	•	•	or pole-changing having additional short-circuited windings for
		~	starting as asynchronous motors
19/16	•	Sy	ynchronous generators
19/18	•	•	having windings each turn of which co-operates only with poles of one polarity, e.g. homopolar generators
19/20	•	•	 with variable-reluctance soft-iron rotors without winding
19/22	•	•	having windings each turn of which co-operates alternately with poles of opposite polarity, e.g. heteropolar generators
19/24	•	•	 with variable-reluctance soft-iron rotors without winding
19/26	•	•	characterised by the arrangement of exciting windings
19/28	•	•	for self-excitation
19/30	•	•	for compounding
19/32	•	•	
19/34	•	•	
19/36	•	•	Structural association of synchronous generators
10/00			with auxiliary electric devices influencing the
			characteristic of the generator or controlling the generator, e.g. with impedances or switches
19/38	•	•	Structural association of synchronous generators
			with exciting machines
24 (00	~		
21/00			hronous motors having permanent magnets;
21 (02	-		chronous generators having permanent magnets
21/02	•	D	etails
21/04	•	•	Windings on magnets for additional excitation
21/10	•	•	Rotating armatures
21/12	•	W	ith stationary armatures and rotating magnets
21/14	•	•	with magnets rotating within the armatures
21/16	•	•	 having annular armature cores with salient poles (with homopolar co-operation H02K 21/20)
21/18	•	•	 having horse-shoe armature cores (with homopolar co-operation H02K 21/20)
21/20	•	•	• having windings each turn of which co-operates only with poles of one polarity, e.g. homopolar machine
21/22	•	•	with magnets rotating around the armatures, e.g. flywheel magnetos
21/24	•	•	with magnets axially facing the armatures, e.g. hub-type cycle dynamos
21/26		347	ith rotating armatures and stationary magnets
21/28		•	with armatures rotating within the magnets
21/20			 having annular armature cores with salient
21/30	•	•	poles (with homopolar co-operation H02K 21/36)
21/32	•	•	 having horse-shoe magnets (with homopolar co-operation H02K 21/36)
21/34	•	•	 having bell-shaped or bar-shaped magnets, e.g. for cycle lighting (with homopolar co-operation H02K 21/36)
21/36	•	•	• with homopolar co-operation
21/38	•	w	ith rotating flux distributors, and armatures and
			agnets both stationary
21/40	•	•	with flux distributors rotating around the magnets and within the armatures
21/42	•	•	with flux distributors rotating around the armatures and within the magnets
			with armature windings wound upon the magnets

21/44 • • with armature windings wound upon the magnets

21/46	 Motors having additional short-circuited winding for starting as an asynchronous motor 	25/00	DC interrupter motors or generators
21/48	Generators with two or more outputs	26/00	Machines adapted to function as torque motors, i.e. to exert a torque when stalled
23/00	DC commutator motors or generators having mechanical commutator; Universal AC/DC commutator motors	27/00	AC commutator motors or generators having mechanical commutator
23/02	 characterised by arrangement for exciting 	27/02	 characterised by the armature winding
23/02	 having permanent magnet excitation 	27/04	 having single-phase operation in series or shunt
	 having permanent magnet excitation having shunt connection of excitation windings 		connection
23/06		27/06	• • with a single or multiple short-circuited
23/08	• having series connection of excitation windings		commutator, e.g. repulsion motor
23/10	 having compound connection of excitation windings 	27/08	with multiple-fed armature
23/12	 having excitation produced by current sources independent of the armature circuit 	27/10	• • with switching devices for different modes of operation, e.g. repulsion-induction motor
23/14	 having high-speed excitation or de-excitation, e.g. 	27/12	 having multi-phase operation
20/11	by neutralising the remanent excitation field	27/14	• • in series connection
23/16	 having angularly adjustable excitation field, e.g. 	27/16	• • in shunt connection with stator feeding
	by pole reversing or pole switching	27/18	• • in shunt connection with rotor feeding
23/18	having displaceable main or auxiliary brushes	27/20	• Structural association with a speed regulating device
23/20	• • having additional brushes spaced intermediately of	27/22	 having means for improving commutation, e.g. auxiliary fields, double windings, double brushes
	the main brushes on the commutator, e.g. cross- field machines, metadynes, amplidynes or other	27/24	 having two or more commutators
	armature-reaction excited machines	27/24	
23/22	 having compensating or damping windings 	27/28	 having disc armature Structural association with auxiliary electric devices
23/24	 having compensating or admiping windings having commutating-pole windings 	27720	influencing the characteristic of the machine or
23/24	 characterised by the armature windings 		controlling the machine
23/28	 having open windings, i.e. not closed within the 	27/30	Structural association with auxiliary mechanical
	armatures	27730	devices, e.g. with clutches or brakes
23/30	having lap windings; having loop windings	29/00	Motors or generators having non-mechanical
23/32	• • having wave winding; having undulating winding	20/00	commutating devices, e.g. discharge tubes or
23/34	having mixed windings		semiconductor devices
23/36	 having two or more windings; having two or more commutators; having two or more stators 	29/03	• with a magnetic circuit specially adapted for avoiding torque ripples or self-starting problems [6]
23/38	 having winding or connection for improving commutation, e.g. equipotential connection 	29/06	 with position sensing devices (H02K 29/03 takes precedence) [4, 6]
23/40	 characterised by the arrangement of the magnet circuits 	29/08	 using magnetic effect devices, e.g. Hall-plates or magneto-resistors (H02K 29/12 takes
23/42	• • having split poles, i.e. zones for varying reluctance		precedence) [4]
	by gaps in poles or by poles with different spacing	29/10	 • using light effect devices [4]
	of the air gap	29/12	 using detecting coils [4]
23/44	 having movable, e.g. turnable, iron parts 	29/14	 with speed sensing devices (H02K 29/03 takes
23/46	• • having stationary shunts, i.e. magnetic cross flux	-0/11	precedence) [4, 6]
23/48	 having adjustable armatures 		
23/50	 Generators with two or more outputs 	31/00	Acyclic motors or generators, i.e. DC machines
23/52	Motors acting also as generators, e.g. starting motors		having drum or disc armatures with continuous
	used as generators for ignition or lighting	24 (22	current collectors
23/54	 Disc armature motors or generators 	31/02	with solid-contact collectors
23/56	• Motors or generators having iron cores separated from armature winding	31/04	• with at least one liquid-contact collector
23/58	Motors or generators without iron cores	33/00	Motors with reciprocating, oscillating or vibrating
23/60	 Motors or generators having rotating armatures and rotating excitation field 		magnet, armature or coil system (arrangements for handling mechanical energy structurally associated with
23/62	 Motors or generators with stationary armatures and rotating excitation field 	33/02	 motors H02K 7/00, e.g. H02K 7/06) with armatures moved one way by energisation of a visible relation of the reaction of the
23/64	 Motors specially adapted for running on DC or AC by choice 		single coil system and returned by mechanical force, e.g. by springs
23/66	Structural association with auxiliary electric devices	33/04	• • wherein the frequency of operation is determined
• •	influencing the characteristic of, or controlling, the	22/02	by the frequency of uninterrupted AC energisation
	machine, e.g. with impedances or switches	33/06	• • • with polarised armatures
23/68	Structural association with auxiliary mechanical	33/08	• • • with DC energisation superimposed on AC
	devices, e.g. with clutches or brakes	77/10	energisation
B 4 / 2 2		33/10	 wherein the alternate energisation and de- energisation of the single coil system is effected or
24/00	Machines adapted for the instantaneous transmission		controlled by movement of the armatures
	or reception of the angular displacement of rotating parts, e.g. synchro, selsyn	33/12	 with armatures moving in alternate directions by alternate energisation of two coil systems

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33/14	• • wherein the alternate energisation and de-
	energisation of the two coil systems are effected or
	controlled by movement of the armatures
33/16	 with polarised armatures moving in alternate
	directions by reversal or energisation of a single coil
22/10	system
33/18	 with coil systems moving upon intermittent or reversed energisation thereof by interaction with a
	fixed field system, e.g. permanent magnets
	ince field bysterii, e.g. permanent mugnets
35/00	Generators with reciprocating, oscillating or
	vibrating coil system, magnet, armature or other
	part of the magnetic circuit (arrangements for handling mechanical energy structurally associated with
	generators H02K 7/00, e.g. H02K 7/06)
35/02	 with moving magnets and stationary coil systems
35/04	 with moving coil systems and stationary magnets
35/04	 with moving flux distributors, and both coil systems
33/00	and magnets stationary
37/00	Motors with rotor rotating step by step and without
	interrupter or commutator driven by the rotor, e.g. stepping motors
37/02	 of variable reluctance type [4]
37/04	 with rotors situated within the stators [4]
37/04	 with rotors situated within the stators [4] with rotors situated around the stators [4]
37/08	 with rotors axially facing the stators [4]
37/00	• of permanent magnet type (H02K 37/02 takes
57710	precedence) [4]
37/12	 with stationary armatures and rotating magnets [4]
37/14	• • • with magnets rotating within the armatures [4]
37/16	• • • having horseshoe armature cores [4]
37/18	• • • • of homopolar type [4]
37/20	• • with rotating flux distributors, the armatures and
0.,_0	magnets both being stationary [4]
37/22	Damping units [4]
37/24	Structural association with auxiliary mechanical
	devices [4]
39/00	Generators specially adapted for producing a desired
	non-sinusoidal waveform
	non-sinusolual waveloi m
<i>41/00</i>	
41/00	Propulsion systems in which a rigid body is moved
41/00	
41/00	Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction
41/00 41/02	Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling
	Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path
41/02	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors; Motors moving step by step;
41/02 41/025	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes
41/02 41/025 41/03	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors; [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3]
41/02 41/025 41/03 41/035	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3]
41/02 41/025 41/03	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis
41/02 41/025 41/03 41/035	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular
41/02 41/025 41/03 41/035	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of
41/02 41/025 41/03 41/035 41/06	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator
41/02 41/025 41/03 41/035	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction
41/02 41/025 41/03 41/035 41/06	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of
41/02 41/025 41/03 41/035 41/06	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of fluid-borne conductive or magnetic particles and a
41/02 41/025 41/03 41/035 41/06	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of fluid-borne conductive or magnetic particles and a coil system or magnetic field converts energy of mass
41/02 41/025 41/03 41/035 41/06	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of fluid-borne conductive or magnetic particles and a coil system or magnetic field converts energy of mass flow into electrical energy or vice versa [3]
41/02 41/025 41/03 41/035 41/06 44/00	 Propulsion systems in which a rigid body is moved along a path due to dynamo-electric interaction between the body and a magnetic field travelling along the path Linear motors; Sectional motors [3] Asynchronous motors [3] Synchronous motors; Motors moving step by step; Reluctance motors (H02K 41/035 takes precedence) [3] DC motors; Unipolar motors [3] Rolling motors, i.e. motors having the rotor axis parallel to the stator axis and following a circular path as the rotor rolls around the inside or outside of the stator Machines in which the dynamo-electric interaction between a plasma or flow of conductive liquid or of fluid-borne conductive or magnetic particles and a coil system or magnetic field converts energy of mass

44/06	• • Induction pumps [3]
44/08	Magnetohydrodynamic [MHD] generators [3]
44/10	• • Constructional details of electrodes [3]
44/12	• • Constructional details of fluid channels [3]
44/14	• • • Circular or screw-shaped channels [3]
44/16	• • Constructional details of the magnetic circuits [3]
44/18	• • for generating AC power [3]
44/20	• • • by changing the polarity of the magnetic field [3]
44/22	• • • by changing the conductivity of the fluid [3]
44/24	• • • by reversing the direction of fluid [3]
44/26	• • • by creating a travelling magnetic field [3]
44/28	 Association of MHD generators with conventional generators (nuclear power plants including a MHD generator G21D 7/02) [3]
47/00	Dynamo-electric converters
47/02	• AC/DC converters or <u>vice versa</u>
47/04	Motor/generators
47/06	Cascade converters
47/08	Single-armature converters
47/10	• • • with booster machines on the AC side
47/12	DC/DC converters
47/14	Motor/generators
47/16	• Single-armature converters, e.g. metadyne
47/18	AC/AC converters
47/20	Motor/generators
47/22	Single-armature frequency converters with or without phase-number conversion
47/24	• • having windings for different numbers of poles
47/26	 operating as under- or over-synchronously running asynchronous induction machines, e.g. cascade arrangement of asynchronous and synchronous machines
47/28	• • • operating as commutator machines with added slip-rings
47/30	• • Single-armature phase-number converters without frequency conversion
49/00	Dynamo-electric clutches; Dynamo-electric brakes
49/02	 of the asynchronous induction type
49/04	 of the eddy-current hysteresis type
49/06	• of the synchronous type
49/08	• of the collector armature type
49/10	• of the permanent-magnet type
49/12	• of the acyclic type
51/00	Dynamo-electric gears, i.e. dynamo-electric means for transmitting mechanical power from a driving shaft to a driven shaft and comprising structurally interrelated motor and generator parts
53/00	Alleged dynamo-electric <u>perpetua mobilia</u>
55/00	Dynamo-electric machines having windings operating at cryogenic temperatures [3]
55/02	• of the synchronous type [3]
55/04	• • with rotating field windings [3]
55/06	• of the homopolar type [3]
99/00	Subject matter not provided for in other groups of this subclass [2014.01]

H02M APPARATUS FOR CONVERSION BETWEEN AC AND AC, BETWEEN AC AND DC, OR BETWEEN DC AND DC, AND FOR USE WITH MAINS OR SIMILAR POWER SUPPLY SYSTEMS; CONVERSION OF DC OR AC INPUT POWER INTO SURGE OUTPUT POWER; CONTROL OR REGULATION THEREOF (conversion of current or voltage specially adapted for use in electronic time-pieces with no moving parts G04G 19/02; systems for regulating electric or magnetic variables in general, e.g. using transformers, reactors or choke coils, combination of such systems with static converters G05F; for digital computers G06F 1/00; transformers H01F; connection or control of one converter with regard to conjoint operation with a similar or other source of supply H02J; dynamo-electric converters H02K 47/00; controlling transformers, reactors or choke coils, control or regulation of electric motors, generators or dynamo-electric converters H02P; pulse generators H03K) **[4, 5]**

Note(s)

- 1. This subclass <u>covers</u> only circuits or apparatus for the conversion of electric power, or arrangements for control or regulation of such circuits or apparatus.
- 2. This subclass <u>does not cover</u> the individual electro-technical devices employed when converting electric power. Such devices are covered by the relevant subclasses, e.g. inductors, transformers H01F, capacitors, electrolytic rectifiers H01G, mercury-vapour rectifying or other discharge tubes H01J, semiconductor devices H01L, impedance networks or resonant circuits not primarily concerned with the transfer of electric power H03H.
- 3. In this subclass, the following term is used with the meaning indicated:
 - "conversion", in respect of an electric variable, e.g. voltage or current, means the change of one or more of the parameters of the variable, e.g. amplitude, frequency, phase, polarity.

Subclass index

DETAILS	
TYPES OF CONVERSION	
dc to dc	
ac to ac	
ac to dc and <u>vice versa</u>	7/00
dc or ac to surge output power	
other power conversion systems	

1/00	Details of apparatus for conversion [1, 2007.01]	1/28	• • incorporating electromagnetically-operated
1/02	 Circuits specially adapted for the generation of grid- control or igniter-control voltages for discharge tubes 	1/20	vibrating contacts
	incorporated in static converters	1/30 1/32	 incorporating liquid contacts Means for protecting converters other than by
1/04	 for tubes with grid control 	1/32	automatic disconnection (emergency protective
1/06	Circuits specially adapted for rendering non-		circuit arrangements specially adapted for converters
	conductive gas discharge tubes or equivalent	4 /0.4	with automatic disconnection H02H 7/10) [2007.01]
	semiconductor devices, e.g. thyratrons, thyristors [2]	1/34	Snubber circuits [2007.01]
1/08	Circuits specially adapted for the generation of	1/36	• Means for starting or stopping converters [2007.01]
	control voltages for semiconductor devices incorporated in static converters	1/38	 Means for preventing simultaneous conduction of switches [2007.01]
1/084	 using a control circuit common to several phases 	1/40	• Means for preventing magnetic saturation [2007.01]
	of a multi-phase system [4]	1/42	Circuits or arrangements for compensating for or
1/088	• • for the simultaneous control of series or parallel connected semiconductor devices [4]		adjusting power factor in converters or inverters [2007.01]
1/092	0 0	1/44	Circuits or arrangements for compensating for
	optically [4]		electromagnetic interference in converters or
1/096			inverters [2007.01]
	connected in parallel to the main switching	2 /00	Conversion of dc power input into dc power output
1/10	element (H02M 1/092 takes precedence) [4]	3/00	
1/10	Arrangements incorporating converting means for	3/02	without intermediate conversion into ac
1/10	 Arrangements incorporating converting means for enabling loads to be operated at will from different 	3/02 3/04	without intermediate conversion into acby static converters
1/10 1/12	Arrangements incorporating converting means for	3/02	without intermediate conversion into ac
	• Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc	3/02 3/04	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider
	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or 	3/02 3/04 3/06	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with
1/12	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output 	3/02 3/04 3/06	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4]
1/12 1/14	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or output 	3/02 3/04 3/06 3/07	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4]
1/12 1/14 1/15	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or output using active elements [4] Means for providing current step on switching, e.g. 	3/02 3/04 3/06 3/07	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4] using discharge tubes without control electrode or semiconductor devices without control electrode using discharge tubes with control electrode or semiconductor devices without control electrode
1/12 1/14 1/15 1/16	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or output using active elements [4] Means for providing current step on switching, e.g. with saturable reactor Contact mechanisms of dynamic converters 	3/02 3/04 3/06 3/07 3/08	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4] using discharge tubes without control electrode or semiconductor devices without control electrode using discharge tubes with control electrode or semiconductor devices with control electrode
1/12 1/14 1/15 1/16 1/20	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or output using active elements [4] Means for providing current step on switching, e.g. with saturable reactor 	3/02 3/04 3/06 3/07 3/08	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4] using discharge tubes without control electrode or semiconductor devices without control electrode using discharge tubes with control electrode or semiconductor devices without control electrode
1/12 1/14 1/15 1/16 1/20 1/22	 Arrangements incorporating converting means for enabling loads to be operated at will from different kinds of power supplies, e.g. from ac or dc Arrangements for reducing harmonics from ac input or output Arrangements for reducing ripples from dc input or output using active elements [4] Means for providing current step on switching, e.g. with saturable reactor Contact mechanisms of dynamic converters incorporating collectors and brushes 	3/02 3/04 3/06 3/07 3/08	 without intermediate conversion into ac by static converters using resistors or capacitors, e.g. potential divider using capacitors charged and discharged alternately by semiconductor devices with control electrode [4] using discharge tubes without control electrode or semiconductor devices without control electrode using discharge tubes with control electrode or semiconductor devices with control electrode

H02M

3/125	•	•	• • using devices of a thyratron or thyristor type	
			requiring extinguishing means [2]	
3/13	•	•	• • • using discharge tubes only [2]	
3/135	•	•	• • • using semiconductor devices only [2]	
3/137	•	•	• • • with automatic control of output	
			voltage or current, e.g. switching	
D /1 DO			regulators [4]	
3/139	•	•	• • • • with digital control [4]	
3/142	•	•	• • • • including plural semiconductor devices as final control devices for	
			a single load [4]	
3/145			 using devices of a triode or transistor type 	
5/145			requiring continuous application of a control	
			signal [2]	
3/15	•	•	• • • using discharge tubes only [2]	
3/155	•	•	• • • using semiconductor devices only [2]	
3/156	•	•	• • • • with automatic control of output	
			voltage or current, e.g. switching	
			regulators [4]	
3/157	•	•	• • • • with digital control [4]	
3/158	•	•	• • • • including plural semiconductor	
			devices as final control devices for a single load [4]	
3/16	•		by dynamic converters	
3/18	•		 using capacitors or batteries which are 	
5/10	-	-	alternately charged and discharged, e.g. charged	1
			in parallel and discharged in series	-
3/20	•	•	by combination of static with dynamic converters;	
			by combination of dynamo-electric with other	
			dynamic or static converters	
3/22	•	W	th intermediate conversion into ac	
3/24	•	•	by static converters	
3/26	•	•	• using discharge tubes without control electrode	
			or semiconductor devices without control	
3/28			electrode to produce the intermediate acusing discharge tubes with control electrode or	
3/20	•	•	semiconductor devices with control electrode of	h
			produce the intermediate ac	,
3/305	•	•	 using devices of a thyratron or thyristor type 	
			requiring extinguishing means [2]	
3/31	•	•	• • • using discharge tubes only [2]	
3/315	•	•	• • • using semiconductor devices only [2]	
3/325	•	•	• • using devices of a triode or a transistor type	
			requiring continuous application of a control	
2 / 22			signal [2]	
3/33	•	•	• • using discharge tubes only [2]	
3/335	•	•	• • using semiconductor devices only [2]	
3/337 3/338	•		 • • • in push-pull configuration [4] • • • in a self-oscillating arrangement 	
3/330	•	•	(H02M 3/337 takes precedence) [4]	
3/34	•	•	by dynamic converters	
3/34	•	•	 using mechanical parts to select progressively 	
5/50			or to vary continuously the input potential	
3/38	•	•	• using mechanical contact-making and -breaking	ž
			parts to interrupt a single potential	,
3/40	•	•	• • wherein the parts are rotating and collectors	
			co-operate with brushes or rollers	
3/42	•	•	• • with electromagnetically-operated vibrating	
			contacts, e.g. chopper (self-interrupters in	
			general H01H 51/34)	
3/44	•	•	by combination of static with dynamic converters;	
			by combination of dynamo-electric with other dynamic or static converters	
5/00	Co	n	version of ac power input into ac power output,	

e.g. for change of voltage, for change of frequency, for change of number of phases

5/02	•	vithout intermediate conversion into dc	
5/04	•	by static converters (controlling transformers,	
		reactors or choke coils, e.g. by tap changing,	
		H02P 13/00) [4]	
5/06	•	using impedances	
5/08	•	 using capacitors only 	
5/10	•	• using transformers	
5/12	•	 for conversion of voltage or current 	
		amplitude only	
5/14	•	• • for conversion between circuits of different	
		phase number	
5/16	•	 for conversion of frequency 	
5/18	•	 for conversion of waveform 	
5/20	•	• using discharge tubes without control electrode	5
		or semiconductor devices without control	
		electrode	
5/22	•	 using discharge tubes with control electrode or 	
		semiconductor devices with control electrode	
5/25	•	using devices of a thyratron or thyristor typ	е
		requiring extinguishing means (H02M 5/27	
		takes precedence) [2]	
5/253	•	• • • using discharge tubes only [2]	
5/257	•	• • • using semiconductor devices only [2]	
5/27	•	• • • for conversion of frequency [2]	
5/275	•	• • using devices of a triode or transistor type	
		requiring continuous application of a control	4
E (20		signal (H02M 5/297 takes precedence) [2]	
5/29	•	• • • using discharge tubes only [2]	
5/293	•	• • • using semiconductor devices only [2]	
5/297	•	• • • for conversion of frequency [2]	
5/32	•	by dynamic converters	
5/34	•	 using mechanical contact-making and -breaking 	g
- /0.0		parts	
5/36	•	 wherein the parts are rotating and collectors 	•
5/38		co-operate with brushes or rollers	
5/30	•	by combination of static with dynamic converters by combination of dynamo-electric with other	,
		dynamic or static converters	
5/40	•	vith intermediate conversion into dc	
5/42	•	by static converters	
5/44	•	 using discharge tubes or semiconductor device 	s
5/ 44		to convert the intermediate dc into ac	3
5/443	•	 using devices of a thyratron or thyristor typ 	е
		requiring extinguishing means [2]	-
5/447	•	• • • using discharge tubes only [2]	
5/45	•	• • • using semiconductor devices only [2]	
5/451	•	• • • • with automatic control of output	
		voltage or frequency [4]	
5/452	•	• • • • with automatic control of output	
		waveform [4]	
5/453	•	• • using devices of a triode or transistor type	
		requiring continuous application of a contro	l
		signal [2]	
5/456	•	 • • using discharge tubes only [2] 	
5/458	•	• • • using semiconductor devices only [2]	
5/46	•	by dynamic converters	
5/48	•	by combination of static with dynamic converters	;
		by combination of dynamo-electric with other	
		dynamic or static converters	
7/00	Ce	version of ac power input into dc power output;	
.,		iversion of dc power input into ac power output,	
7/02	•	Conversion of ac power input into dc power output	
		vithout possibility of reversal	
7/04	•	hy static converters	

7/04 • • by static converters

 7/08 • • • • arranged for operation in parallel 7/10 • • • arranged for operation in series, e.g. for multiplication of voltage 7/12 • • using discharge tubes with control electrode or semiconductor devices with control electrode 7/145 • • • • using discharge tubes only [2] 7/155 • • • • using semiconductor devices only [2] 7/162 • • • • in a bridge configuration [4] 7/17 • • • • • arranged for operation in parallel [2, 4] 7/19 • • • • arranged for operation in series, e.g. for voltage multiplication of a control signal [2, 4] 7/21 • • • • using discharge tubes only [2] 7/213 • • • • using discharge tubes only [2] 7/217 • • • • using discharge tubes only [2] 7/217 • • • using discharge tubes only [2] 7/213 • • • using discharge tubes only [2] 7/217 • • • using discharge tubes only [2] 7/217 • • • • using discharge tubes only [2] 7/217 • • • • using discharge tubes only [2] 7/217 • • • • arranged for operation in parallel [2, 4] 7/23 • • • • arranged for operation in parallel [2, 4] 7/25 • • • • arranged for operation in parallel [2, 4] 7/26 • • using open-spark devices, e.g. Marx rectifier 7/30 • by dynamic converters 7/34 • • • wherein the parts are rotating and -breaking parts 7/34 • • wherein the parts are rotating and collectors co-operate with brushes or rollers rodicate, e.g., chopper (self-interrupters in general H01H 51/34) • with electromagnetically-operated vibrating contacts, e.g., chopper (self-interrupters in general H01H 51/34) • by combination of static with dynamic converters; by combination of static with dynamic converters; by combination of static with dynamic	7/06	•	•	•	or ser electr	
7/12 • • • using discharge tubes with control electrode or semiconductor devices with control electrode 7/145 • • • • using devices of a thyratron or thyristor type requiring extinguishing means [2, 4] 7/15 • • • • using semiconductor devices only [2] 7/162 • • • • • in a bridge configuration [4] 7/17 • • • • • arranged for operation in parallel [2, 4] 7/19 • • • • • arranged for operation in series, e.g. for voltage multiplication [2, 4] 7/21 • • • • • using devices of a triode or transistor type requiring continuous application of a control signal [2, 4] 7/21 • • • • using descharge tubes only [2] 7/217 • • • • using discharge tubes only [2] 7/218 • • • • • using decrease only configuration [4] 7/219 • • • • • using decrease only [2] 7/219 • • • • • using decrease only [2] 7/219 • • • • • using decrease only [2] 7/219 • • • • • arranged for operation in series, e.g. for multiplication of voltage [2, 4] 7/22 • • • • using decredition in parallel [2, 4] 7/23 • • • • arranged for operation in series, e.g. for multiplication of voltage [2, 4] 7/26 • • • using decredition in series, e.g. for multiplication of voltage [2, 4] 7/28 • • using dechanical co	7/08	•	•	•	• arr	anged for operation in parallel
 7/12 • • • using discharge tubes with control electrode or semiconductor devices with control electrode 7/145 • • • using devices of a thyratron or thyristor type requiring extinguishing means [2, 4] 7/15 • • • • using discharge tubes only [2] 7/162 • • • • using discharge tubes only [2] 7/162 • • • • in a bridge configuration [4] 7/17 • • • • • arranged for operation in parallel [2, 4] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • arranged for operation in series, e.g. for voltage multiplication [2, 4] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • using discharge tubes only [2] 7/21 • • • • arranged for operation in series, e.g. for multiplication of voltage [2, 4] 7/23 • • • • • arranged for operation in series, e.g. for multiplication of voltage [2, 4] 7/26 • • using open-spark devices, e.g. Marx rectifier 7/30 • by dynamic converters 7/32 • • • wherein the parts are rotating and collectors co-operate with brushes or rollers 7/34 • • wherein the parts are rotating and collectors co-operate with brushes or rollers 7/36 • • • using one or more sparking electrodes rotating over counterelectrodes 7/40 • by combination of static with dynamic converters; by combination of dynamo-electric with other dynamic or static converters 7/42 • Convertion of dynamo-electric with other dynamic or static converters 7/44 • by static converters 7/45 • • using discharge tubes with control electrode or semiconductor devices with con	7/10	•	•	•		
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 7/42 • Conversion of dc power input into ac power output without possibility of reversal 7/44 • by static converters 7/46 • • using discharge tubes without control electrode or semiconductor devices without control electrode 7/48 • • using discharge tubes with control electrode or semiconductor devices with outputs that each can have more than two voltage levels [2007.01] 7/493 • • • Combination of several voltages being obtained by combination of several pulse-voltages having different amplitude and width [2007.01] 7/505 • • • using devices of a thyratron or thyristor type 	7/40	•	•	by	7 comb	ination of dynamo-electric with other
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 more than two voltage levels [2007.01] 7/487 • • • • • Neutral point clamped inverters [2007.01] 7/49 • • • • • Combination of the output voltage waveforms of a plurality of converters [2007.01] 7/493 • • • • • the static converters being arranged for operation in parallel [2007.01] 7/497 • • • • sinusoidal output voltages being obtained by combination of several voltages being out of phase [2007.01] 7/501 • • • • sinusoidal output voltages being obtained by the combination of several pulse-voltages having different amplitude and width [2007.01] 7/505 • • • • using devices of a thyratron or thyristor type 	7/483		•			
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 7/501 • • • sinusoidal output voltages being obtained by the combination of several pulse-voltages having different amplitude and width [2007.01] 7/505 • • • • using devices of a thyratron or thyristor type 	//49/	•	•	•	CO	mbination of several voltages being out of
 the combination of several pulse-voltages having different amplitude and width [2007.01] 7/505 • • • • using devices of a thyratron or thyristor type 	7/501	•	•	•		
having different amplitude and width [2007.01]7/505 • • • • using devices of a thyratron or thyristor type	,,501					
7/505 • • • • using devices of a thyratron or thyristor type					ha	ving different amplitude and
requiring extinguishing means [2]	7/505	•	•	•		

7/51 •	•			• 11	sing discharge tubes only [2]
7/515 •	•	•	•		sing semiconductor devices
7/516	_				nly [2, 2007.01]
7/516 •	•	•	•	••	Self-oscillating arrangements [2007.01]
7/517 •	•	•	•	•••	with special starting equipment [4]
7/519 •	•	•	•	••	in a push-pull configuration (H02M 7/517 takes precedence) [4]
7/521 •	•	•	•	•••	in a bridge configuration [4]
7/523 •	•	•	•	•••	with LC-resonance circuit in the main
					circuit [4]
7/525 •	•	•	•	••	with automatic control of output waveform or frequency (H02M 7/517- H02M 7/523 take precedence) [4]
7/527 •	•	•	•	•••	• by pulse width modulation [4]
7/529 •	•	•	•	•••	using digital control [4]
7/53 •	•	•	•	requ	g devices of a triode or transistor type hiring continuous application of a control al [2]
7/533 •	•	•	•	-	sing discharge tubes only [2]
7/537 •	•	•	•		sing semiconductor devices only, e.g.
				S	ingle switched pulse inverters [2]
7/5375 •	•	•	•	•••	with special starting equipment [4]
7/538 •	•	•	•	•••	in a push-pull configuration (H02M 7/5375 takes
					precedence) [4, 2007.01]
7/5381 •	•	•	•	•••	• Parallel type [2007.01]
7/5383 •	•	•	•	•••	in a self-oscillating arrangement
					(H02M 7/538 takes precedence) [4, 2007.01]
7/53838•	•	•			 using a single commutation
1100000					path [2007.01]
7/53846•	•	•	•	•••	Control circuits [2007.01]
7/53854•	•	•	•	••	 using thyristor type converters [2007.01]
7/53862•	•	•	•	••	 using transistor type converters [2007.01]
7/5387 •	•	•	•	•••	in a bridge configuration [4, 2007.01]
7/5388 •	•	•	•	••	• with asymmetrical configuration of switches [2007.01]
7/539 •	•	•	•	••	with automatic control of output wave form or frequency (H02M 7/5375-
					H02M 7/5387 take precedence) [4]
7/5395 •	•	•	•	•••	• by pulse-width modulation [4]
7/54 • 7/56 •	•	Dy			ic converters nechanical parts to select progressively,
//30	•	•			ary continuously, the input potential
7/58 •	•	•	usi	ing n	nechanical contact-making and -breaking o interrupt a single potential
7/60 •	•	•	•	whe	rein the parts are rotating and collectors operate with brushes or rollers
7/62 •	•				electromagnetically-operated vibrating
,,,,,				cont gene	tacts, e.g. chopper (self-interrupters in eral H01H 51/34)
7/64 •	•	by	г со	mbiı	nation of static with dynamic converters; nation of dynamo-electric with other or static converters
7/66 •	W	-			ity of reversal
7/68 •	•				converters
7/70 •	•	•			lischarge tubes without control electrode
			-	semi ectro	iconductor devices without control
7/72 •	•				ae lischarge tubes with control electrode or
					nductor devices with control electrode

H02M

7/75	• • • using devices of a thyratron or thyristor type requiring extinguishing means (H02M 7/77 takes precedence) [2]
7/753	• • • • • using discharge tubes only [2]
7/757	• • • • • using semiconductor devices only [2]
7/758	••••• with automatic control of output waveform or frequency [4]
7/77	• • • • • arranged for operation in parallel [2]
7/79	 • using devices of a triode or transistor type requiring continuous application of a control signal (H02M 7/81 takes precedence) [2]
7/793	• • • • using discharge tubes only [2]
7/797	• • • • • using semiconductor devices only [2]
7/81	• • • • • arranged for operation in parallel [2]
7/82	• • • using open-spark devices, e.g. Marx rectifier
7/84	• • using electrolytic rectifiers
7/86	by dynamic converters
7/88	• • using mechanical parts to select progressively or to vary continuously the input potential
7/90	• • using mechanical contact-making and -breaking parts to interrupt a single potential

7/92	• • • wherein the parts are rotating and collectors co-operate with brushes or rollers
7/94	• • • wherein the parts are operated by rotating cams or cam-like devices
7/95	• • • with electromagnetically-operated vibrating contacts, e.g. chopper (self-interrupters in general H01H 51/34)
7/96	• • • • with moving liquid contacts
7/98	• • by combination of static with dynamic converters; by combination of dynamo-electric with other dynamic or static converters
9/00	Conversion of dc or ac input power into surge output
	power [2]
9/02	• with dc input power [2]
9/04	• • using capacitative stores [2]
9/06	• with ac input power [2]

11/00 Power conversion systems not covered by the other groups of this subclass [4]

H02N ELECTRIC MACHINES NOT OTHERWISE PROVIDED FOR

Note(s)

•

1.	This subclass <u>covers</u> :
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- electrostatic generators, motors, clutches, or holding devices;
- other non-dynamo-electric generators or motors;
- holding or levitation devices using magnetic attraction or repulsion;
- arrangements for starting, regulating, braking, or otherwise controlling such machines unless in conjoint operation with a second machine.
- 2. Attention is drawn to the Notes following the titles of class B81 and subclass B81B relating to "micro-structural devices" and "microstructural systems".
- 3. Specific provision for generators, motors, or other means for converting between electric and other forms of energy also exists in other subclasses, e.g. in subclasses H01L, H01M, H02K, H04R.

Subclass index

GENERATORS, MOTORS With electrostatic effect	1/00
Generators using thermal ionisation and removal of charge; electric motors using thermal effects	
Others	11/00
ELECTRIC MACHINES IN GENERAL USING PIEZO-ELECTRIC EFFECT, ELECTROSTRICTION	
OR MAGNETOSTRICTION	2/00
ELECTROSTATIC CLUTCHES OR HOLDING DEVICES	13/00
MAGNETIC HOLDING OR LEVITATING DEVICES	15/00
SUBJECT MATTER NOT PROVIDED FOR IN OTHER GROUPS OF THIS SUBCLASS	99/00

1 (00		
1/00	Electrostatic generators or motors using a solid moving electrostatic charge carrier	 2/02 • producing linear motion, e.g. actuators; Linear positioners [6]
1/04	Friction generators	2/04 • Constructional details [6]
1/06	Influence generators	2/06 • • Drive circuits; Control arrangements [6]
1/08	• • with conductive charge carrier, i.e. capacitor	2/08 • • using travelling waves, e.g. linear motors [6]
	machines	2/10 • producing rotary motion, e.g. rotary motors [6]
1/10	 with non-conductive charge carrier 	2/12 • • Constructional details [6]
1/12	• • • in the form of a conveyor belt, e.g. van de	2/14 • • Drive circuits; Control arrangements [6]
	Graaff machine	2/16 • • using travelling waves [6]
2/00	Electric machines in general using piezo-electric effect, electrostriction or magnetostriction (generating mechanical vibrations in general B06B; piezo-electric, electrostrictive or magnetostrictive elements in general	 producing electrical output from mechanical input, e.g. generators (for measurement devices G01) [6]

H01L 41/00) [4]

- 3/00 Generators in which thermal or kinetic energy is converted into electrical energy by ionisation of a fluid and removal of the charge therefrom (discharge tubes functioning as thermionic generators H01J 45/00) [3]
- 10/00 Electric motors using thermal effects [3]
- 11/00 Generators or motors not provided for elsewhere; Alleged <u>perpetua mobilia</u> obtained by electric or magnetic means (by hydrostatic pressure F03B 17/04; by dynamo-electric means H02K 53/00)
- 13/00 Clutches or holding devices using electrostatic attraction, e.g. using Johnson-Rahbek effect
- 15/00 Holding or levitation devices using magnetic attraction or repulsion, not otherwise provided for (electric or magnetic devices for holding work on machine tools B23Q 3/15; sliding or levitation devices for railway systems B61B 13/08; material handling devices associated with conveyors incorporating devices with electrostatic or magnetic grippers B65G 47/92; separating thin or filamentary articles from piles using magnetic force B65H 3/16; delivering thin or filamentary articles from magnetic holders by air blast or suction B65H 29/24; bearings using magnetic or electric supporting means F16C 32/04; relieving bearing loads using magnetic means F16C 39/06; magnets H01F 7/00; dynamo-electric clutches or brakes H02K 49/00) [3]
- 15/02 by Foucault currents [3]
- 15/04 Repulsion by the Meissner effect (superconductors or hyperconductors in general H01L 39/00) [3]
- 99/00 Subject matter not provided for in other groups of this subclass [2006.01]

H02P CONTROL OR REGULATION OF ELECTRIC MOTORS, GENERATORS, OR DYNAMO-ELECTRIC CONVERTERS; CONTROLLING TRANSFORMERS OR REACTORS OR CHOKE COILS [4]

Note(s)

- 1. This subclass <u>covers</u> arrangements for starting, regulating, electronically commutating, braking, or otherwise controlling motors, generators, dynamo-electric converters, clutches, brakes, gears, transformers, reactors or choke coils, of the types classified in the relevant subclasses, e.g. H01F, H02K.
- 2. This subclass <u>does not cover</u> similar arrangements for the apparatus of the types classified in subclass H02N, which arrangements are covered by that subclass.
- 3. In this subclass, the following terms or expressions are used with the meanings indicated:
 - "control" means influencing a variable in any way, e.g. changing its direction or its value (including changing it to or from zero), maintaining it constant, limiting its range of variation;
 - "regulation" means maintaining a variable at a desired value, or within a desired range of values, by comparison of the actual value with the desired value.

Subclass index

ARRANGEMENTS FOR STARTING; FOR SLOWING, STOPPING	1/00, 3/00
ARRANGEMENTS FOR CONTROLLING ELECTRIC MOTORS THAT CAN BE CONNECTED TO	
DIFFERENT POWER SUPPLIES	4/00
ARRANGEMENTS FOR CONTROLLING TWO OR MORE ELECTRIC MOTORS	5/00
ARRANGEMENTS FOR CONTROLLING SYNCHRONOUS MOTORS OR OTHER DYNAMO-	
ELECTRIC MOTORS WITH ELECTRONIC COMMUTATORS IN DEPENDENCE ON THE ROTOR	
POSITION	6/00
ARRANGEMENTS FOR CONTROLLING DC MOTORS	7/00
ARRANGEMENTS FOR CONTROLLING DYNAMO-ELECTRIC MOTORS ROTATING STEP BY	
STEP	8/00
ARRANGEMENTS FOR OBTAINING DESIRED OUTPUT OF GENERATOR	9/00
ARRANGEMENTS FOR OBTAINING DESIRED OUTPUT OF CONVERTERS: DYNAMO-	
ELECTRIC; STATIC	11/00, 13/00
ARRANGEMENTS FOR CONTROLLING BRAKES OR CLUTCHES	15/00
ARRANGEMENTS FOR CONTROLLING DYNAMO-ELECTRIC GEARS	17/00
ARRANGEMENTS FOR CONTROLLING ELECTRIC MACHINES BY VECTOR CONTROL	21/00
ARRANGEMENTS FOR CONTROLLING AC MOTORS BY METHODS OTHER THAN VECTOR	
CONTROL	23/00
CHARACTERISED BY THE KIND OF AC MOTORS OR BY STRUCTURAL DETAILS	25/00
CHARACTERISED BY THE KIND OF SUPPLY VOLTAGE	27/00
ARRANGEMENTS FOR CONTROLLING APPROPRIATE FOR BOTH AC AND DC MOTORS	
ADDANCENENTS FOR CONTROLLING NOT OTHERWISE PROVIDED FOR	
ARRANGEMENTS FOR CONTROLLING NOT OTHERWISE PROVIDED FOR	

1/00 Arrangements for starting electric motors or dynamo-electric converters (starting of synchronous motors with electronic commutators H02P 6/20, H02P 6/22; starting dynamo-electric motors rotating step by step H02P 8/04; vector control H02P 21/00) **[4, 2006.01]**

H02P

1 /0 4	
1/04	Means for controlling progress of starting sequence in dependence upon time or upon
	current, speed, or other motor parameter
1/06	 • • Manually-operated multi-position starters
1/08	 Manually-operated multi-position staters Manually-operated on/off switch controlling
1700	power-operated multi-position switch or
	impedances for starting a motor
1/10	• • • Manually-operated on/off switch controlling
	relays or contactors operating sequentially for
	starting a motor
1/12	• • • Switching devices centrifugally operated by the
	motor
1/14	• • • Pressure-sensitive resistors centrifugally
	operated by the motor
1/16	• for starting dynamo-electric motors or dynamo-
1/10	electric converters
1/18	• • for starting an individual dc motor
1/20	• • • by progressive reduction of resistance in series
1/22	with armature winding
1/22	• • in either direction of rotation
1/24	• for starting an individual ac commutator motor (starting of ac/dc commutator motors H02P 1/18)
1/26	 for starting on individual polyphase induction
1/20	motor
1/28	 • by progressive increase of voltage applied to
1/20	primary circuit of motor
1/30	 • • by progressive increase of frequency of supply
1,00	to primary circuit of motor
1/32	• • • by star/delta switching
1/34	• • • by progressive reduction of impedance in
	secondary circuit
1/36	• • • • the impedance being a liquid resistance
1/38	• • • by pole-changing
1/40	• • • in either direction of rotation
1/42	• • for starting an individual single-phase induction
	motor
1/44	 • • by phase-splitting with a capacitor
1/46	for starting an individual synchronous motor
1/48	• • • by pole-changing
1/50	• • • by changing over from asynchronous to
	synchronous operation (H02P 1/48 takes
4 (50	precedence)
1/52	• • • by progressive increase of frequency of supply
1 / 🗆 4	to motor
1/54	• for starting two or more dynamo-electric motors
1/56	• • • simultaneously
1/58	• • • sequentially
3/00	Arrangements for stopping or slowing electric
.,	motors, generators, or dynamo-electric converters
	(stopping of synchronous motors with electronic
	commutators H02P 6/24; stopping dynamo-electric
	motors rotating step by step H02P 8/24; vector control
B / 8B	H02P 21/00) [2, 4, 2006.01]
3/02	• Details
3/04	• • Means for stopping or slowing by a separate
2/06	brake, e.g. friction brake or eddy-current brake [2]
3/06	• for stopping or slowing an individual dynamo- electric motor or dynamo-electric converter [2]
2/00	
3/08	 for stopping or slowing a dc motor [2] by reversal of supply connections
3/10	by reversal of supply connections
3/12 3/14	 • by short-circuit or resistive braking • by regenerative braking
3/14	 • • by regenerative braking • • • by combined electrical and mechanical braking
3/16	 by combined electrical and mechanical braking for stopping or slowing an ac motor [2]
J/ 10	· · · IOI Stopping of Stowing an ac motor [2]

3/20	• • • by reversal of phase sequence of connections to the motor
3/22	 • • by short-circuit or resistive braking
3/24	• • • by applying dc to the motor
3/26	• • • by combined electrical and mechanical braking
4/00	Arrangements specially adapted for regulating or controlling the speed or torque of electric motors that can be connected to two or more different voltage or current supplies (vector control H02P 21/00) [2006.01]
5/00	Arrangements specially adapted for regulating or controlling the speed or torque of two or more electric motors [1, 2006.01]
5/46	• for speed regulation of two or more dynamo-electric motors in relation to one another
5/48	 by comparing mechanical values representing the speeds
5/50	 by comparing electrical values representing the speeds
5/52	 additionally providing control of relative angular displacement
5/60	 controlling combinations of dc and ac dynamo- electric motors (H02P 5/46 takes precedence) [2006.01]
5/68	• controlling two or more dc dynamo-electric motors (H02P 5/46, H02P 5/60 take precedence) [2006.01]
5/685	• electrically connected in series, i.e. carrying the same current [2006.01]
5/69	• • mechanically coupled by gearing [2006.01]
5/695	• • • Differential gearing [2006.01]
5/74	 controlling two or more ac dynamo-electric motors (H02P 5/46, H02P 5/60 take precedence) [2006.01]
5/747	• • mechanically coupled by gearing [2006.01]
5/753	• • • Differential gearing [2006.01]
6/00	Arrangements for controlling synchronous motors or other dynamo-electric motors with electronic commutators in dependence on the rotor position; Electronic commutators therefor (vector control H02P 21/00) [3, 4, 6]
6/04	• Arrangements for controlling or regulating speed or torque of more than one motor [6]
6/06	 Arrangements for speed regulation of a single motor wherein the motor speed is measured and compared with a given physical value so as to adjust the motor speed [6]
6/08	• Arrangements for controlling the speed or torque of a single motor [6]
6/10	• • providing reduced torque ripple; controlling torque ripple [6]
6/12	• Monitoring commutation; Providing indication of commutation failure [6]
6/14	Electronic commutators [6]
6/16	• • Circuit arrangements for detecting position [6]
6/18	• • • without separate position detecting element, e.g. using back-emf in windings [6]
6/20	• Arrangements for starting (H02P 6/08, H02P 6/22 take precedence) [6]
	•
6/22	• Arrangements for starting in a selected direction of rotation [6]

7/00 Arrangements for regulating or controlling the speed or torque of electric dc-motors [2, 2006.01]

7/06		for regulating or controlling an individual dc
//00		dynamo-electric motor by varying field or armature
		current
7/08	•	• by manual control without auxiliary power
7/10	•	of motor field only
7/12	•	• • • Switching field from series to shunt
F (1.4		excitation or <u>vice versa</u>
7/14	•	 of voltage applied to the armature with or without control of field
7/18	•	 by master control with auxiliary power
7/20	•	• • using multi-position switch, e.g. drum,
		controlling motor circuit by means of relays
- /		(H02P 7/24, H02P 7/30 take precedence)
7/22	•	 using multi-position switch, e.g. drum, controlling motor circuit by means of pilot-
		motor-operated multi-position switch or pilot-
		motor-operated variable resistance (H02P 7/24,
		H02P 7/30 take precedence)
7/24	•	using discharge tubes or semiconductor devices
7/26	•	• • • using discharge tubes
7/28	•	• • using semiconductor devices
7/282	•	• • • • controlling field supply only [4]
7/285	•	• • • • controlling armature supply only [4]
7/288	•	• • • • using variable impedance [4]
7/29	•	• • • • using pulse modulation [4]
7/292 7/295	•	 ••••• using static converters, e.g. ac to dc [4] ••••• of the kind having one thyristor or
//293	•	the like in series with the power
		supply and the motor [4]
7/298	•	• • • • controlling armature and field supply [4]
7/30	•	using magnetic devices with controllable
		degree of saturation, i.e. transductors
7/32	•	• • using armature-reaction-excited machines, e.g.
7/24		metadyne, amplidyne, rototrol
7/34	•	metadyne, amplidyne, rototrolusing Ward-Leonard arrangements
7/34 8/00		• • using Ward-Leonard arrangements rrangements for controlling dynamo-electric
8/00		• • using Ward-Leonard arrangements rrangements for controlling dynamo-electric notors rotating step by step [2, 6, 2006.01]
		• using Ward-Leonard arrangements rrangements for controlling dynamo-electric notors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper
8/00 8/02		• • using Ward-Leonard arrangements rrangements for controlling dynamo-electric totors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6]
8/00 8/02 8/04		• • using Ward-Leonard arrangements rrangements for controlling dynamo-electric totors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6]
8/00 8/02		 • using Ward-Leonard arrangements rrangements for controlling dynamo-electric totors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] • in selected direction of rotation [6]
8/00 8/02 8/04 8/06		 • using Ward-Leonard arrangements • rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] • in selected direction of rotation [6] • Determining position before starting [6]
8/00 8/02 8/04 8/06 8/08		 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12		 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6]
8/00 8/02 8/04 8/06 8/08 8/10	m • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14	m • • •	 • using Ward-Leonard arrangements rrangements for controlling dynamo-electric totors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16	m • • •	 • using Ward-Leonard arrangements rrangements for controlling dynamo-electric totors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18	m • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20	m • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18	m • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g.
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20	m • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6]
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22	m • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g.
8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22	m • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 	m • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 	m • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/30 8/32 	m • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/30 	m • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/28 8/30 8/32 8/34 	m • • • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes precedence) [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/30 8/32 	m • • • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes precedence) [6] Protection against faults, e.g. against overheating or
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/28 8/30 8/32 8/34 8/36 	m • • • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes precedence) [6] Protection against faults, e.g. against overheating or step-out; Indicating faults [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/28 8/30 8/32 8/34 	m • • • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes precedence) [6] Protection against faults, e.g. against overheating or step-out; Indicating faults [6] the fault being step-out [6]
 8/00 8/02 8/04 8/06 8/08 8/10 8/12 8/14 8/16 8/18 8/20 8/22 8/24 8/26 8/28 8/30 8/32 8/34 8/36 8/38 	m • • • • • • • • • • • • • • •	 using Ward-Leonard arrangements rrangements for controlling dynamo-electric botors rotating step by step [2, 6, 2006.01] specially adapted for single-phase or bi-pole stepper motors, e.g. watch-motors, clock-motors [6] Arrangements for starting [6] in selected direction of rotation [6] Determining position before starting [6] Shaping pulses for starting; Boosting current during starting [6] Control or stabilisation of current [6] Arrangements for controlling speed or speed and torque (H02P 8/12, H02P 8/22 take precedence) [6] Reducing energy dissipated or supplied [6] Shaping of pulses, e.g. to reduce torque ripple [6] characterised by bidirectional operation [6] Control of step size; Intermediate stepping, e.g. micro-stepping [6] Arrangements for stopping (H02P 8/32 take precedence) [6] Memorising final pulse when stopping [6] Disconnecting power source when stopping [6] Holding position when stopped [6] Reducing overshoot or oscillation, e.g. damping [6] Monitoring operation (H02P 8/36 takes precedence) [6] Protection against faults, e.g. against overheating or step-out; Indicating faults [6]

0/ 42	step by step [6]
9/00	Arrangements for controlling electric generators for the purpose of obtaining a desired output [1, 2006.01]
9/02	• Details
9/04	• Control effected upon non-electric prime mover and dependent upon electric output value of the generator (effecting control of the prime mover in general, <u>see</u> the relevant class for such prime mover) [2]
9/06	 Control effected upon clutch or other mechanical power transmission means and dependent upon electric output value of the generator (effecting control of the power transmission means, see the relevant class for such means) [2]
9/08	 Control of generator circuit during starting or stopping of driving means, e.g. for initiating excitation [2]
9/10	• Control effected upon generator excitation circuit to reduce harmful effects of overloads or transients, e.g. sudden application of load, sudden removal of load, sudden change of load [2]
9/12	• • for demagnetising; for reducing effects of remanence; for preventing pole reversal [2]
9/14	 by variation of field (H02P 9/08, H02P 9/10 take precedence) [2]
9/16	• • due to variation of ohmic resistance in field circuit, using resistances switched in or out of circuit step by step
9/18	• • • the switching being caused by a servomotor, measuring instrument, or relay
9/20	due to variation of continuously-variable ohmic resistance
9/22	 comprising carbon pile resistance
9/24	 due to variation of make-to-break ratio of intermittently-operating contacts, e.g. using Tirrill regulator
9/26	 using discharge tubes or semiconductor devices (H02P 9/34 takes precedence) [2]
9/28	 • • using discharge tubes
9/30	 • • using semiconductor devices
9/32	• using magnetic devices with controllable degree of saturation (H02P 9/34 takes precedence) [2]
9/34	• • using magnetic devices with controllable degree of saturation in combination with controlled discharge tube or controlled semiconductor device
9/36	 using armature-reaction-excited machines
9/38	Self-excitation by current derived from rectification of both output voltage and output current of generator
9/40	 by variation of reluctance of magnetic circuit of generator
9/42	 to obtain desired frequency without varying speed of the generator
9/44	• Control of frequency and voltage in predetermined relation, e.g. constant ratio
9/46	Control of asynchronous generator by variation of capacitor
9/48	• Arrangements for obtaining a constant output value at varying speed of the generator, e.g. on vehicle (H02P 9/04-H02P 9/46 take precedence) [3]
11/00	Arrangements for controlling dynamo-electric converters [4, 2006.01]
11/04	 for controlling dynamo-electric converters having a dc output

8/42 $\hspace{0.1in} \bullet \hspace{0.1in}$ characterised by non-stepper motors being operated

H02P

11/06	 for controlling dynamo-electric converters having an ac output 	23
13/00	Arrangements for controlling transformers, reactors or choke coils, for the purpose of obtaining a desired output [4]	23
13/06	 by tap-changing; by rearranging interconnections of windings 	25
13/08	 by sliding current collector along winding 	
13/10	 by moving core, coil winding, or shield, e.g. by induction regulator 	
13/12	 by varying magnetic bias 	
15/00	Arrangements for controlling dynamo-electric	
	brakes or clutches (vector control	
15 (00	H02P 21/00) [1, 2006.01]	25
15/02	• Conjoint control of brakes and clutches [3]	25
17/00	Arrangements for controlling dynamo-electric gears (vector control H02P 21/00) [3, 2006.01]	25 25
21/00	Arrangements or methods for the control of electric machines by vector control, e.g. by control of field	25 25
	orientation [6, 2006.01]	25
	<u>Note(s) [2006.01]</u>	
	When classifying in this group, it is desirable to also	25
	classify in groups H02P 25/00-H02P 27/00 if the kind of ac-motor, structural details, or the kind of supply	25
	voltage are of interest.	20
21/02	 specially adapted for optimising the efficiency at low load [2006.01] 	25 25
21/04	• specially adapted for very low speeds [2006.01]	-
21/05	 specially adapted for damping motor oscillations, e.g. for reducing hunting [2006.01] 	25
21/06	Rotor flux based control [2006.01]	25
21/08	 Indirect field-oriented control, e.g. field phase angle calculation based on rotor voltage equation by adding slip frequency and speed proportional 	25
21/10	frequency [2006.01]Direct field-oriented control [2006.01]	25
21/10	Stator flux based control [2006.01]	25
21/13	Observer control, e.g. using Luenberger observers or	
	Kalman filters [2006.01]	27
21/14	 Estimation or adaptation of machine parameters, e.g. rotor time constant, flux, speed, current or voltage [2006.01] 	
23/00	Arrangements or methods for the control of ac- motors characterised by a control method other than vector control [2006.01]	
	<u>Note(s) [2006.01]</u>	
	When classifying in this group, it is desirable to also classify in groups H02P 25/00-H02P 27/00 if the kind of ac-motor, structural details, or the kind of supply	27
23/02	 voltage are of interest. specially adapted for optimising the efficiency at low load [2006.01] 	27
23/03	 specially adapted for very low speeds [2006.01] 	27
23/04	 specially adapted for damping motor oscillations, e.g. for reducing hunting [2006.01] 	
23/06	• Controlling the motor in four quadrants [2006.01]	27
23/08	Controlling based on slip frequency, e.g. adding slip	27
	frequency and speed proportional frequency [2006 01]	27 27
23/10	frequency [2006.01]Controlling by adding a dc current [2006.01]	27
20/10		_,

23/12	•	Observer control, e.g. using Luenberger observers or
		Kalman filters [2006.01]

- Estimation or adaptation of motor parameters, e.g. rotor time constant, flux, speed, current or voltage [2006.01]
- 25/00 Arrangements or methods for the control of acmotors characterised by the kind of ac-motor or by structural details [2006.01]

Note(s) [2006.01]

	<u>Note(s) [2006.01]</u>			
	When classifying in this group, it is desirable to also classify in groups H02P 21/00, H02P 23/00 or			
	H02P 27/00 if the control method or the kind of supply voltage are of interest.			
5/02	 characterised by the kind of motor [2006.01] 			
5/04	• • Single phase motors, e.g. capacitor			
	motors [2006.01]			
5/06	• • Linear motors [2006.01]			
5/08	Reluctance motors [2006.01]			
5/10	Commutator motors, e.g. repulsion motors [2006.01]			
5/12	• • with shiftable brushes [2006.01]			
5/14	• • • Universal motors (H02P 25/12 takes precedence) [2006.01]			
5/16	 characterised by the circuit arrangement or by the kind of wiring [2006.01] 			
5/18	• • with arrangements for switching the windings, e.g. with mechanical switches or relays [2006.01]			
5/20	• • • for pole-changing [2006.01]			
5/22	 Multiple windings; Windings for more than three phases [2006.01] 			
5/24	Variable impedance in stator or rotor circuit [2006.01]			
5/26	• • • with arrangements for controlling secondary impedance [2006.01]			
5/28	• using magnetic devices with controllable degree of saturation, e.g. transductors [2006.01]			
5/30	• • the motor being controlled by a control effected upon an ac generator supplying it [2006.01]			
5/32	• • using discharge tubes [2006.01]			
7/00	Arrangements or methods for the control of ac- motors characterised by the kind of supply voltage (of two or more motors H02P 5/00; of synchronous motors with electronic commutators H02P 6/00; of dc- motors H02P 7/00; of stepping motors H02P 8/00) [2006.01]			
	Note(s) [2006.01]			
	When classifying in this group, it is desirable to also classify in groups H02P 21/00, H02P 23/00 or H02P 25/00 if the control method, the kind of the acmotor or structural details are of interest.			
7/02	 using supply voltage with constant frequency and variable amplitude [2006.01] 			
7/04	• using variable-frequency supply voltage, e.g. inverter or converter supply voltage [2006.01]			
7/05	 using ac supply for both rotor and stator circuits, the frequency of supply to at least one circuit being variable [2006.01] 			
7/06	 using dc to ac converters or inverters (H02P 27/05 takes precedence) [2006.01] 			
7/08	• • • with pulse width modulation [2006.01]			
7/10	• • • using bang-bang controllers [2006.01]			
7/12	• • • pulsing by guiding the flux-, current-, or voltage-vector on a circle or a closed curve,			
	e.g. direct torque control [2006.01]			

- 27/14 • • with three or more levels of voltage [2006.01]
 27/16 • using ac to ac converters without intermediate conversion to dc (H02P 27/05 takes precedence) [2006.01]
 27/18 • varying the frequency by omitting half waves [2006.01]
- 29/00 Arrangements for regulating or controlling electric motors, appropriate for both ac- and dc-motors (control of motors that can be connected to two or more different voltage or current supplies H02P 4/00; vector control H02P 21/00) [2006.01]
- Providing protection against overload without automatic interruption of supply, e.g. monitoring [2006.01]

• by means of a separate brake [2006.01]

- 31/00 Arrangements for regulating or controlling electric motors not provided for in groups H02P 1/00-H02P 5/00, H02P 7/00 or H02P 21/00-H02P 29/00 [2006.01]
- H02S Generation of electric power by conversion of infra-red radiation, visible light or ultraviolet light, e.g. using photovoltaic [PV] modules (solar heat collectors F24J 2/00; obtaining electrical energy from radioactive sources G21H 1/12; light sensitive inorganic semiconductor devices H01L 31/00; thermoelectric devices H01L 35/00; pyroelectric devices H01L 37/00; light sensitive organic semiconductor devices H01L 51/42) [2014.01]

10/00	PV power plants; Combinations of PV energy systems with other systems for the generation of electric	30/10 30/20	 Frame structures [2014.01] Collapsible or foldable PV modules [2014.01]
	power [2014.01]		
10/10	 including a supplementary source of electric power, e.g. hybrid diesel-PV energy systems (combinations with gas-turbine plants F02C 6/00) [2014.01] 	40/00	Components or accessories in combination with PV modules, not provided for in groups H02S 10/00- H02S 30/00 [2014.01]
10/12	• • Hybrid wind-PV energy systems [2014.01]	40/10	 Cleaning arrangements [2014.01]
10/20	• Systems characterised by their energy storage means	40/12	• • Means for removing snow [2014.01]
	(H02S 40/38 takes precedence) [2014.01]	40/20	Optical components [2014.01]
10/30	 Thermophotovoltaic systems (photovoltaic cells specially adapted for conversion or sensing of infra- red [IR] radiation H01L 31/00; thermoelectric devices H01L 35/00) [2014.01] 	40/22	• Light-reflecting or light-concentrating means (directly associated with the PV cell or integrated with the PV cell H01L 31/054) [2014.01]
10/40		40/30	Electrical components [2014.01]
10/40	Mobile PV generator systems [2014.01]	40/32	• comprising DC/AC inverter means associated with the DV medule itself a configuration of the DV medules [2014.01]
20/00	Supporting structures for PV modules [2014.01]	40/34	 the PV module itself, e.g. AC modules [2014.01] comprising specially adapted electrical connection means to be structurally associated
	<u>Note(s) [2014.01]</u>		with the PV module, e.g. junction boxes [2014.01]
	Supporting structures also intended for use with solar heat collectors should also be classified in groups F24J 2/38 or F24J 2/52.	40/36	 characterised by special electrical interconnection means between two or more PV modules, e.g. electrical module-to-module connection [2014.01]
20/10	 Supporting structures directly fixed to the ground (H02S 20/30 takes precedence) [2014.01] 	40/38	 Energy storage means, e.g. batteries, structurally associated with PV modules [2014.01]
20/20	 Supporting structures directly fixed to an immovable object (H02S 20/30 takes precedence) [2014.01] 	40/40	 Thermal components (H02S 10/30 takes precedence) [2014.01]
20/21	 specially adapted for motorways, e.g. integrated with sound barriers [2014.01] 	40/42	 Cooling means (cooling means directly associated or integrated with the PV cell
20/22	 specially adapted for buildings [2014.01] 		H01L 31/052) [2014.01]
20/23	 specially adapted for roof structures (roof covering aspects of energy collecting devices E04D 13/18) [2014.01] 	40/44	• Means to utilise heat energy, e.g. hybrid systems producing warm water and electricity at the same time (directly associated with the PV cell or
20/24	• • • • specially adapted for flat roofs [2014.01]		integrated with the PV cell
20/25	• • • • Roof tile elements [2014.01]		H01L 31/0525) [2014.01]
20/26	 Building materials integrated with PV modules, e.g. façade elements (H02S 20/25 takes precedence) [2014.01] 	50/00	Monitoring or testing of PV systems, e.g. load balancing or fault identification [2014.01]
20/30	• Supporting structures being movable or adjustable, e.g. for angle adjustment [2014.01]	50/10	• Testing of PV devices, e.g. of PV modules or single PV cells (testing of semiconductor devices during
20/32	 specially adapted for solar tracking [2014.01] 		manufacturing H01L 21/66) [2014.01]
30/00	Structural details of PV modules other than those	50/15	• • using optical means, e.g. using electroluminescence [2014.01]
	<i>related to light conversion</i> (semiconductor device aspects of modules of electrolytic light sensitive devices H01G 9/20, of inorganic PV modules H01L 31/00, of	99/00	Subject matter not provided for in other groups of this subclass [2014.01]

organic PV modules H01L 51/42) [2014.01]