SECTION G — PHYSICS

G01 MEASURING; TESTING

Note(s)

- 1. This class <u>covers</u>, in addition to "true" measuring instruments, other indicating or recording devices of analogous construction, and also signalling or control devices insofar as they are concerned with measurement (as defined in Note 2 below) and are not specially adapted to the particular purpose of signalling or control.
- 2. In this class, the following term is used with the meaning indicated:
 - "measuring" is used to cover considerably more than its primary or basic meaning. In this primary sense, it means finding a numerical expression of the value of a variable in relation to a unit or datum or to another variable of the same nature, e.g. expressing a length in terms of another length as in measuring a length with a scale; the value may be obtained directly (as just suggested) or by measuring some other variable of which the value can be related to the value of the required variable, as in measuring a change in temperature by measuring a resultant change in the length of a column of mercury. However, since the same device or instrument may, instead of giving an immediate indication, be used to produce a record or to initiate a signal to produce an indication or control effect, or may be used in combination with other devices or instruments to give a conjoint result from measurement of two or more variables of the same or different kinds, it is necessary to interpret "measuring" as including also any operation that would make it possible to obtain such a numerical expression by the additional use of some way of converting a value into figures. Thus the expression in figures may be actually made by a digital presentation or by reading a scale, or an indication of it may be given without the use of figures, e.g. by some perceptible feature (variable) of the entity (e.g. object, substance, beam of light) of which the variable being measured is a property or condition or by an analogue of such a feature (e.g. the corresponding position of a member without any scale, a corresponding voltage generated in some way). In many cases there is no such value indication but only an indication of difference or equality in relation to a standard or datum (of which the value may or may not be known in figures); the standard or datum may be the value of another variable of the same nature but of a different entity (e.g. a standard measure) or of the same entity at a different time.
 - In its simplest form, measurement may give merely an indication of presence or absence of a certain condition or quality, e.g. movement (in any direction or in a particular direction), or whether a variable exceeds a predetermined value.
- 3. Attention is drawn to the Notes following the titles of class B81 and subclass B81B relating to "micro-structural devices" and "micro-structural systems" and the Notes following the title of subclass B82B relating to "nano-structures".
- 4. Attention is drawn to the Notes following the title of section G, especially as regards the definition of the term "variable".
- 5. In many measuring arrangements, a first variable to be measured is transformed into a second, or further, variables. The second, or further, variables may be (a) a condition related to the first variable and produced in a member, or (b) a displacement of a member. Further transformation may be needed.
 - When classifying such an arrangement, (i) the transformation step, or each transformation step, that is of interest is classified, or (ii) if interest lies only in the system as a whole, the first variable is classified in the appropriate place.
 - This is particularly important where two or more conversions take place, for instance where a first variable, for example pressure, is transformed into a second variable, for example an optical property of a sensing body, and that second variable is expressed by means of a third variable, for example an electric effect. In such a case, the following classification places should be considered: the place for the transformation of the first variable, that for sensing the condition caused by that variable, subclass G01D for expression of the measurement, and finally the place for the overall system, if any.
- 6. The measurement of change in the value of a physical property is classified in the same subclass as the measurement of that physical property, e.g. measurement of expansion of length is classified in subclass G01B.

G01B MEASURING LENGTH, THICKNESS OR SIMILAR LINEAR DIMENSIONS; MEASURING ANGLES; MEASURING AREAS; MEASURING IRREGULARITIES OF SURFACES OR CONTOURS

Note(s)

- 1. This subclass <u>covers</u> measuring of position or displacement in terms of linear or angular dimensions.
- 2. In this subclass, the groups are distinguished by the means of measurement which is of major importance. Thus the mere application of other means for giving a final indication does not affect the classification.
- 3. Attention is drawn to the Notes following the title of class G01.
- 4. Machines operated on similar principles to the hand-held devices specified in this subclass are classified with these devices.
- 5. Measuring arrangements or details thereof covered by two or more of groups G01B 3/00-G01B 17/00 are classified in group G01B 21/00 if no single other group can be selected as being predominantly applicable.

Subclass index

2

	ic or magnetic		
	iids		
	th waves; by other electro-magnetic waves or radiation nic waves		
	MEASURING ARRANGEMENTS		
OTTIER	VILAGORING ARRAINGLINENTS	••••••	21/00
1/00	Measuring instruments characterised by the selection of material therefor	5/02	• for measuring length, width, or thickness (G01B 5/004, G01B 5/08 take precedence) [6]
D (00	Y	5/04	• • specially adapted for measuring length or width of
3/00	Instruments as specified in the subgroups and		objects while moving
	characterised by the use of mechanical measuring means (arrangements for measuring particular	5/06	 for measuring thickness
	parameters G01B 5/00; devices of general interest	5/08	 for measuring diameters
	specially adapted or mounted for storing and repeatedly	5/10	 of objects while moving
	paying-out and re-storing lengths of material	5/12	 internal diameters
	B65H 75/34) [2]	5/14	 for measuring distance or clearance between spaced
3/02	 Rulers or tapes with scales or marks for direct reading 		objects or spaced apertures (G01B 5/24 takes precedence)
3/04	• • rigid	5/16	between a succession of regularly spaced objects
3/06	• • • folding		or regularly spaced apertures
3/08	• • • extensible	5/18	 for measuring depth
3/10	• • flexible	5/20	 for measuring contours or curvatures
3/11	Chains for measuring length	5/207	 using a plurality of fixed, simultaneously
3/12	Measuring wheels		operating transducers (G01B 5/213-G01B 5/22
3/14	Templates for checking contours		take precedence) [6]
3/16	Compasses, i.e. with a pair of pivoted arms	5/213	• • for measuring radius of curvature [6]
3/18	Micrometers	5/22	• • Spherometers
3/20	Slide gauges	5/24	 for measuring angles or tapers; for testing the
3/20	Feeler-pin gauges, e.g. dial gauges (for measuring)		alignment of axes
3/22	contours or curvatures G01B 5/20)	5/245	• • for testing perpendicularity [6]
3/24	with open yoke, i.e. calipers	5/25	 for testing the alignment of axes
3/24	• Plug gauges	5/252	 for measuring eccentricity, i.e. lateral shift
3/28			between two parallel axes [6]
	• Depth gauges	5/255	 for testing wheel alignment
3/30	 Bars, blocks, or strips in which the distance between a pair of faces is fixed, although it may be preadjustable, e.g. end measure, feeler strip 	5/26	 for measuring areas, e.g. planimeter (integrators in general G06G)
3/32	Holders therefor	5/28	 for measuring roughness or irregularity of surfaces
3/34	Ring or other apertured gauges, e.g. "go/no-go"	5/30	 for measuring the deformation in a solid, e.g.
3/34	gauge		mechanical strain gauge
3/36	for external screw threads	7/00	Measuring arrangements characterised by the use of
3/38	Gauges with an open yoke and opposed faces, i.e.	7700	electric or magnetic means
5750	calipers, in which the internal distance between the	7/004	• for measuring coordinates of points [6]
	faces is fixed, although it may be preadjustable	7/004	 using coordinate measuring machines [6]
3/40	for external screw threads	7/000	Contact-making feeler heads therefor [6]
3/42	• • of limit-gauge type, i.e. "go/no-go" (G01B 3/40	7/012	• • • Constructional details of contacts [6]
	takes precedence)	7/010	• for measuring length, width, or thickness
3/44	• • preadjustable for wear or tolerance	7/02	(G01B 7/004, G01B 7/12 takes precedence) [6]
3/46	Plug gauges for internal dimensions with engaging	7/04	• specially adapted for measuring length or width of
	surfaces which are at a fixed distance, although they	7704	objects while moving
	may be preadjustable	7/06	for measuring thickness
3/48	 for internal screw threads 	7/00	for measuring diameters
3/50	• • of limit-gauge type, i.e. "go/no-go" (G01B 3/48	7/12	Internal diameters [6]
	takes precedence)	7/13	for measuring distance or clearance between spaced
3/52	 • preadjustable for wear or tolerance 	//14	objects or spaced apertures (G01B 7/30 takes
3/56	 Gauges for measuring angles or tapers, e.g. conical 		precedence)
	calipers	7/15	being regularly spaced [6]
		7/16	• for measuring the deformation in a solid, e.g. by
5/00	Measuring arrangements characterised by the use of	//10	resistance strain gauge
	mechanical means (instruments of the types covered by	7/24	using change in magnetic properties
E /004	group G01B 3/00 per se G01B 3/00) [2]	7/24	for measuring depth
5/004	• for measuring coordinates of points [6]	7/28	for measuring contours or curvatures
5/008	• • using coordinate measuring machines [6]	7/28 7/287	using a plurality of fixed, simultaneously
5/012 5/016	Contact-making feeler heads therefor [6]Constructional details of contacts [6]	//20/	operating transducers (G01B 7/293 takes precedence) [6]

7/293	• • for measuring radius of curvature [6]	13/03	 by measuring coordinates of points [3]
7/30	 for measuring angles or tapers; for testing the alignment of axes 	13/04	 specially adapted for measuring length or width of objects while moving
7/305	• • for testing perpendicularity [6]	13/06	 for measuring thickness
7/31	 for testing the alignment of axes 	13/08	 for measuring diameters
7/312	• • • for measuring eccentricity, i.e. lateral shift	13/10	 internal diameters
	between two parallel axes [6]	13/12	 for measuring distance or clearance between spaced
7/315	 for testing wheel alignment 		objects or spaced apertures (G01B 13/18 takes
7/32	• for measuring areas (integrators in general G06G)		precedence)
7/34	 for measuring roughness or irregularity of surfaces 	13/14	 for measuring depth
0.400		13/16	 for measuring contours or curvatures
9/00	Instruments as specified in the subgroups and characterised by the use of optical measuring means	13/18	 for measuring angles or tapers; for testing the alignment of axes
	(arrangements for measuring particular parameters	13/19	 for testing the alignment of axes
9/02	G01B 11/00) [2] • Interferometers	13/195	 for testing wheel alignment
9/021	 using holographic techniques [2] 	13/20	 for measuring areas, e.g. pneumatic planimeter
	• • • for contour producing (G01B 9/025-		(integrators in general G06G)
9/023	G01B 9/029 take precedence) [2]	13/22	• for measuring roughness or irregularity of surfaces
9/025	• • Double-exposure technique [2]	13/24	 for measuring the deformation in a solid [3]
9/023	• • • in real time [2]	15 /00	Mary days a second of the second second second
9/029	• • • by time averaging [2]	15/00	Measuring arrangements characterised by the use of wave or particle radiation (G01B 9/00, G01B 11/00
9/029			take precedence) [4]
9/04	Measuring microscopesMeasuring telescopes	15/02	for measuring thickness
9/08		15/04	for measuring contours or curvatures
	Optical projection comparators	15/04	for measuring contours of curvatures for measuring the deformation in a solid
9/10	Goniometers for measuring angles between surfaces	15/08	for measuring the deformation in a solid for measuring roughness or irregularity of
11/00	Measuring arrangements characterised by the use of	13/00	surfaces [6]
	optical means (instruments of the types covered by		surfaces [v]
	group G01B 9/00 per se G01B 9/00) [2]	17/00	Measuring arrangements characterised by the use of
11/02	 for measuring length, width, or thickness 		infrasonic, sonic, or ultrasonic vibrations [4]
	(G01B 11/08 takes precedence)	17/02	 for measuring thickness
11/03	 by measuring coordinates of points [3] 	17/04	 for measuring the deformation in a solid, e.g. by
11/04	 specially adapted for measuring length or width of 		vibrating string
	objects while moving	17/06	 for measuring contours or curvatures [6]
11/06	 for measuring thickness 	17/08	 for measuring roughness or irregularity of
11/08	 for measuring diameters 		surfaces [6]
11/10	 of objects while moving 	21/00	Measuring arrangements or details thereof in so far
11/12	 internal diameters 	21/00	as they are not adapted to particular types of
11/14	 for measuring distance or clearance between spaced 		measuring means of the other groups of this
	objects or spaced apertures (G01B 11/26 takes		subclass [3]
	precedence; rangefinders G01C 3/00)	21/02	 for measuring length, width, or thickness
11/16	• for measuring the deformation in a solid, e.g. optical		(G01B 21/10 takes precedence) [3]
44 (00	strain gauge	21/04	 by measuring coordinates of points [3]
11/22	• for measuring depth	21/06	 specially adapted for measuring length or width of
11/24	for measuring contours or curvatures		objects while moving [3]
11/245	• • using a plurality of fixed, simultaneously	21/08	 for measuring thickness [3]
	operating transducers (G01B 11/255 takes	21/10	 for measuring diameters [3]
11/25	precedence) [7]	21/12	 of objects while moving [3]
11/25	• by projecting a pattern, e.g. moiré fringes, on the	21/14	• • internal diameters [3]
11/255	object (G01B 11/255 takes precedence) [7]• for measuring radius of curvature [7]	21/16	 for measuring distance or clearance between spaced
11/255 11/26	• for measuring angles or tapers; for testing the		objects [3]
11/20	alignment of axes	21/18	 for measuring depth [3]
11/27	 for testing the alignment of axes 	21/20	 for measuring contours or curvatures, e.g.
11/275	for testing wheel alignment		determining profile [3]
11/2/3	 for measuring areas (integrators in general G06G) 	21/22	 for measuring angles or tapers; for testing the
			alignment of axes [3]
11/30	for measuring roughness or irregularity of surfaces	21/24	 for testing the alignment of axes [3]
40 /00		21/26	f
13/00	Measuring arrangements characterised by the use of	21/26	 for testing wheel alignment [3]
13/00	Measuring arrangements characterised by the use of fluids	21/28	• for measuring areas (integrators in general G06G) [3]
13/00			for measuring areas (integrators in general G06G) [3]for measuring roughness or irregularity of
	fluids	21/28	• for measuring areas (integrators in general G06G) [3]

G01C MEASURING DISTANCES, LEVELS OR BEARINGS; SURVEYING; NAVIGATION; GYROSCOPIC INSTRUMENTS; PHOTOGRAMMETRY OR VIDEOGRAMMETRY (measuring liquid level G01F; radio navigation, determining distance or velocity by use of propagation effects, e.g. Doppler effect, propagation time, of radio waves, analogous arrangements using other waves G01S)

Note(s)

1. In this subclass, the following term is used with the meaning indicated:

base of variable length at, near, or formed by, the

object **[1, 2006.01]**

- · "navigation" means determining the position and course of land vehicles, ships, aircraft, and space vehicles.
- 2. Attention is drawn to the Notes following the title of class G01.

Subclass index

Subciass	<u>muex</u>		
MEASUI	RING INSTRUMENTS		
For m	neasuring angles; inclinations		1/00, 9/00
	neasuring distances; heights or levels		
	passes; gyroscopes; other navigation instruments		
	surveying instruments		
Comb	pined instruments		23/00
Manu	ıfacture, calibrating		25/00
TRACIN	G PROFILES		7/00
PHOTOC	GRAMMETRY OR VIDEOGRAMMETRY		11/00
SURVEY	TING OPEN WATER		13/00
1/00	Measuring angles	3/28	• • with provision for reduction of the distance into
1/02	 Theodolites 		the horizontal plane
1/04	 combined with cameras 	3/30	 • with adaptation to the measurement of the
1/06	 Arrangements for reading scales 		height of an object, e.g. tacheometers
1/08	• Sextants	3/32	 by focusing the object, e.g. on a ground glass screen
1/10	 including an artificial horizon (G01C 1/14 takes 		
1/10	precedence)	5/00	Measuring height; Measuring distances transverse to
1/12	• • with a stabilised mirror		line of sight; Levelling between separated points;
1/12			Surveyors' levels (G01C 3/20, G01C 3/30 take
1/14	Periscopic sextants		precedence)
3/00	Measuring distances in line of sight; Optical	5/02	 involving automatic stabilisation of the line of sight
3/00	rangefinders (tapes, chains, or wheels for measuring	5/04	 Hydrostatic levelling, i.e. by flexibly interconnected
	length G01B 3/00; active triangulation systems, i.e.		liquid containers at separated points
	using the transmission and reflection of electromagnetic	5/06	 by using barometric means
	waves other than radio waves, G01S 17/48) [1, 2006.01]		
3/02	• Details	7/00	Tracing profiles (by photogrammetry or
3/02			videogrammetry G01C 11/00)
3/04	 Adaptation of rangefinders for combination with telescopes or binoculars 	7/02	 of land surfaces
2/00	-	7/04	 involving a vehicle which moves along the profile
3/06	Use of electric means to obtain final indication		to be traced
3/08	• • Use of electric radiation detectors	7/06	 of cavities, e.g. tunnels
3/10	 using a parallactic triangle with variable angles and a 		
	base of fixed length in the observation station, e.g. in	9/00	Measuring inclination, e.g. by clinometers, by levels
	the instrument [1, 2006.01]	9/02	 Details
3/12	 with monocular observation at a single point, e.g. 	9/04	 Transmission means between sensing element and
	coincidence type (G01C 3/20 takes precedence)		final indicator for giving an enlarged reading
3/14	 with binocular observation at a single point, e.g. 	9/06	Electric or photoelectric indication or reading
	stereoscopic type (G01C 3/20 takes precedence)	3,00	means
3/16	• • Measuring marks	9/08	Means for compensating acceleration forces due to
3/18	 with one observation point at each end of the base 	3700	movement of instrument
	(G01C 3/20 takes precedence)	9/10	by using rolling bodies
3/20	 with adaptation to the measurement of the height 		• •
	of an object	9/12	• by using a single pendulum (plumb lines
3/22	using a parallactic triangle with variable angles and a		G01C 15/10)
	base of fixed length at, near, or formed by, the	9/14	 movable in more than one direction
	object [1, 2006.01]	9/16	 by using more than one pendulum
3/24	 using a parallactic triangle with fixed angles and a 	9/18	 by using liquids
3, 2 .	base of variable length in the observation station, e.g.	9/20	 the indication being based on the inclination of the
	in the instrument [1, 2006.01]		surface of a liquid relative to its container
3/26	 using a parallactic triangle with fixed angles and a 	9/22	 • with interconnected containers in fixed relation
5/20	base of variable length at pear or formed by the		to each other

9/24	 in closed containers partially filled with liquid so as to leave a gas bubble 	17/04	 with north-seeking magnetic elements, e.g. needles
9/26	• • • Details	17/06	 Suspending magnetic elements
9/28	• • • Mountings	17/08	• • • by flotation
9/30	 • • • Means for adjusting dimensions of bubble 	17/10	 Comparing observed direction with north
9/32	• • • Means for facilitating the observation of the		indication
	position of the bubble, e.g. illuminating means	17/12	• • • by sighting means, e.g. for surveyors' compasses
9/34	 • of the tubular type, i.e. for indicating the level 	17/14	• • • by reference marks, e.g. for ships' compasses
	in one direction only	17/16	 • • by clinometers, e.g. for determining dip or
9/36	• • • of the spherical type, i.e. for indicating the level in all directions	17/18	strike of geological strata • • • Supporting or suspending compasses, e.g. by
11/00	Photogrammetry or videogrammetry, e.g.		gimbal, by flotation
11/00	stereogrammetry; Photographic	17/20	Observing the compass card or needle
	surveying [1, 2006.01]	17/22	• • • by projection
11/02	Picture-taking arrangements specially adapted for	17/24	• • • • Illumination
	photogrammetry or photographic surveying, e.g.	17/26	• • • using electric pick-offs for transmission to
	controlling overlapping of pictures	17/20	final indicator, e.g. photocell
11/04	 Interpretation of pictures 	17/28	 Electromagnetic compasses (with north-seeking magnetic elements and having electric pick-offs
11/06	 by comparison of two or more pictures of the same area 	45.00	G01C 17/26)
11/08	 the pictures not being supported in the same 	17/30	• • • Earth-inductor compasses
	relative position as when they were taken	17/32	• • • Electron compasses
11/10	• • • using computers to control the position of	17/34	• Sun- or astro-compasses
	the pictures	17/36	Repeaters for remote indication of readings of a meeter compact.
11/12	• • • the pictures being supported in the same	17/38	master compassTesting, calibrating, or compensating of compasses
11/14	relative position as when they were taken • • • with optical projection (G01C 11/26 takes	19/00	Gyroscopes; Turn-sensitive devices using vibrating
	precedence)	15/00	masses; Turn-sensitive devices without moving
11/16	• • • • in a common plane		masses; Measuring angular rate using gyroscopic
11/18	• • • • • involving scanning means		effects [1, 2013.01]
11/20	• • • • in separate planes	19/02	 Rotary gyroscopes
11/22	• • • with mechanical projection (G01C 11/26	19/04	• • Details
11/04	takes precedence)	19/06	• • • Rotors
11/24	 • • with optical-mechanical projection 	19/08	• • • electrically driven (G01C 19/14 takes
44.00	(G01C 11/26 takes precedence)	13/00	precedence)
11/26	• • • using computers to control the position of	19/10	
	• • • using computers to control the position of the pictures		precedence)
11/26 11/28	• • using computers to control the position of the pictures• • Special adaptation for recording picture point	19/10	precedence) • • • • Power supply
11/28	 using computers to control the position of the pictures Special adaptation for recording picture point data, e.g. for profiles 	19/10 19/12	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence)
11/28 11/30	 • using computers to control the position of the pictures • Special adaptation for recording picture point data, e.g. for profiles • by triangulation 	19/10 19/12 19/14	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • • Fluid rotors • • Suspensions; Bearings • • providing movement of rotor with respect to
11/28 11/30 11/32	 • using computers to control the position of the pictures • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • Radial triangulation 	19/10 19/12 19/14 19/16	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • • Fluid rotors • • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24
11/28 11/30 11/32 11/34	 • using computers to control the position of the pictures • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • Radial triangulation • Aerial triangulation 	19/10 19/12 19/14 19/16 19/18	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • • Fluid rotors • • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence)
11/28 11/30 11/32	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video 	19/10 19/12 19/14 19/16 19/18	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • • in fluid
11/28 11/30 11/32 11/34	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or 	19/10 19/12 19/14 19/16 19/18	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • • in fluid • • • torsional
11/28 11/30 11/32 11/34 11/36	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24	precedence) • • • Power supply • • Iluid driven (G01C 19/14 takes precedence) • Fluid rotors • Suspensions; Bearings • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • in fluid • torsional • using magnetic or electrostatic fields
11/28 11/30 11/32 11/34	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • using magnetic or electrostatic fields • Caging, i.e. immobilising moving parts, e.g. for transport
11/28 11/30 11/32 11/34 11/36	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • using magnetic or electrostatic fields • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an
11/28 11/30 11/32 11/34 11/36	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis
11/28 11/30 11/32 11/34 11/36 13/00	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis • Erection devices, i.e. devices for restoring rotor
11/28 11/30 11/32 11/34 11/36 13/00 15/00	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis • Erection devices, i.e. devices for restoring rotor axis to a desired position (for instrument
11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/02 15/04	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • Permanent marks; Boundary markers 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26 19/28	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis • Erection devices, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46)
11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/02 15/04 15/06	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • Permanent marks; Boundary markers • Surveyors' staffs; Movable markers 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis • Erection devices, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46) • Indicating or recording means specially adapted
11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/02 15/04 15/06 15/08	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • Permanent marks; Boundary markers • Surveyors' staffs; Movable markers • Plumbing or registering staffs or markers over ground marks 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26 19/28	precedence) Power supply Pluid driven (G01C 19/14 takes precedence) Pluid rotors Suspensions; Bearings Providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Providing movement of the rotor avis to easing magnetic or electrostatic fields Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis Pick-offs, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46) Indicating or recording means specially adapted for rotary gyroscopes for indicating a direction in the horizontal plane,
11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/00 15/02 15/04 15/06 15/08 15/10	 • • • using computers to control the position of the pictures • • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • • Permanent marks; Boundary markers • • Surveyors' staffs; Movable markers • • Plumbing or registering staffs or markers over ground marks • Plumb lines 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26 19/28 19/30	precedence) Power supply Pluid driven (G01C 19/14 takes precedence) Pluid rotors Pluid rotors Pluid rotors Pluid rotors Providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Public torsional Public torsional Public Caging, i.e. immobilising moving parts, e.g. for transport Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis Perection devices, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46) Indicating or recording means specially adapted for rotary gyroscopes for indicating a direction in the horizontal plane, e.g. directional gyroscopes
11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/02 15/04 15/06 15/08	 • • • using computers to control the position of the pictures • • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • • Permanent marks; Boundary markers • • Surveyors' staffs; Movable markers • • Plumbing or registering staffs or markers over ground marks • Plumb lines • Instruments for setting out fixed angles, e.g. right 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26 19/28 19/30	precedence) Power supply Pluid driven (G01C 19/14 takes precedence) Pluid rotors Pluid rotors Pluid rotors providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) Public torsional Public torsional Pick-offs, i.e. immobilising moving parts, e.g. for transport Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis Percetion devices, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46) Indicating or recording means specially adapted for rotary gyroscopes for indicating a direction in the horizontal plane, e.g. directional gyroscopes
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11/28 11/30 11/32 11/34 11/36 13/00 15/00 15/02 15/04 15/06 15/08 15/10 15/12	 • • • using computers to control the position of the pictures • • Special adaptation for recording picture point data, e.g. for profiles • by triangulation • • Radial triangulation • • Aerial triangulation • Videogrammetry, i.e. electronic processing of video signals from different sources to give parallax or range information [2006.01] Surveying specially adapted to open water, e.g. sea, lake, river or canal (liquid level metering G01F) Surveying instruments or accessories not provided for in groups G01C 1/00-G01C 13/00 • Means for marking measuring points • Permanent marks; Boundary markers • Surveyors' staffs; Movable markers • Plumbing or registering staffs or markers over ground marks • Plumb lines • Instruments for setting out fixed angles, e.g. right angles • Artificial horizons 	19/10 19/12 19/14 19/16 19/18 19/20 19/22 19/24 19/26 19/30 19/32 19/34	precedence) • • • • Power supply • • • fluid driven (G01C 19/14 takes precedence) • • Fluid rotors • Suspensions; Bearings • • providing movement of rotor with respect to its rotational axes (G01C 19/20, G01C 19/24 take precedence) • • in fluid • • torsional • • using magnetic or electrostatic fields • Caging, i.e. immobilising moving parts, e.g. for transport • Pick-offs, i.e. devices for taking off an indication of the displacement of the rotor axis • Erection devices, i.e. devices for restoring rotor axis to a desired position (for instrument indicating the vertical G01C 19/46) • Indicating or recording means specially adapted for rotary gyroscopes • for indicating a direction in the horizontal plane, e.g. directional gyroscopes • with north-seeking action by magnetic means, e.g. gyromagnetic compasses
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17/02 • Magnetic compasses

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19/42	 for indicating rate of turn; for integrating rate of 	19/58	 Turn-sensitive devices without moving masses [3]
	turn	19/60	 Electronic or nuclear magnetic resonance
19/44 •	 for indicating the vertical 		gyrometers [3, 4]
19/46 •	 Erection devices for restoring rotor axis to a 	19/62	 • • with optical pumping [3]
	desired position	19/64	 Gyrometers using the Sagnac effect, i.e. rotation-
19/48 •	 operating by electrical means (G01C 19/54 		induced shifts between counter-rotating
	takes precedence)		electromagnetic beams [3]
19/50	 operating by mechanical means 	19/66	 Ring laser gyrometers [5]
	(G01C 19/54 takes precedence)	19/68	• • • Lock-in prevention [5]
19/52	 operating by fluid means (G01C 19/54 takes 	19/70	• • • • by mechanical means [5]
	precedence)	19/72	 • with counter-rotating light beams in a passive
19/54 •	 with correction for acceleration forces due to 		ring, e.g. fibre laser gyrometers [5]
	movement of instrument		
	Turn-sensitive devices using vibrating masses, e.g.	21/00	Navigation; Navigational instruments not provided
	vibratory angular rate sensors based on Coriolis		for in groups G01C 1/00-G01C 19/00 (measuring
	forces [1, 2012.01]		distance traversed on the ground by a vehicle G01C 22/00; control of position, course, altitude or
19/5607 •	• using vibrating tuning forks (double-ended tuning		attitude of vehicles G05D 1/00; traffic control systems
	forks using planar vibrating masses suspended at		for road vehicles involving transmission of navigation
10/5014	opposite ends G01C 19/5719) [2012.01]		instructions to the vehicle G08G 1/0968)
	• • Signal processing [2012.01]	21/02	 by astronomical means (G01C 21/24, G01C 21/26
19/5621 •	• the devices involving a micro-mechanical	-17 0-	take precedence) [1, 7]
10/500	structure [2012.01]	21/04	 by terrestrial means (G01C 21/24, G01C 21/26 take
19/5628 •	Manufacturing; Trimming; Mounting; Llaurings [2012 01]	, .	precedence) [1, 7]
10/505	Housings [2012.01]	21/06	 involving measuring of drift angle; involving
	• using vibrating wires or strings [2012.01]		correction for drift
	• using vibrating bars or beams [2012.01]	21/08	 involving use of the magnetic field of the earth
	• • Signal processing [2012.01]	21/10	 by using measurement of speed or acceleration
19/5656 •	the devices involving a micro-mechanical		(G01C 21/24, G01C 21/26 take precedence) [1, 7]
10/5000	structure [2012.01]	21/12	 executed aboard the object being navigated; Dead
19/5663 •	Manufacturing; Trimming; Mounting; Hayrings [2012 01]		reckoning
10/567	Housings [2012.01]	21/14	 • by recording the course traversed by the object
19/56/	 using the phase shift of a vibration node or antinode [2012.01] 		(G01C 21/16 takes precedence)
10/5677	 of essentially two-dimensional vibrators, e.g. 	21/16	• • by integrating acceleration or speed, i.e. inertial
13/30//	ring-shaped vibrators [2012.01]		navigation
19/5684 •	 the devices involving a micro-mechanical 	21/18	 • • • Stabilised platforms, e.g. by gyroscope
13/3004	structure [2012.01]	21/20	 Instruments for performing navigational calculations
19/5691 •	 of essentially three-dimensional vibrators, e.g. 		(G01C 21/24, G01C 21/26 take precedence) [1, 7]
15, 5051	wine glass-type vibrators [2012.01]	21/22	 Plotting boards
19/5698 •	using acoustic waves, e.g. surface acoustic wave	21/24	 specially adapted for cosmonautical navigation
	gyros [2012.01]	21/26	 specially adapted for navigation in a road network [7]
19/5705 •	 using masses driven in reciprocating rotary motion 	21/28	 with correlation of data from several navigational
	about an axis [2012.01]		instruments [7]
19/5712 •	 the devices involving a micro-mechanical 	21/30	 • • Map- or contour-matching [7]
	structure [2012.01]	21/32	 • • • Structuring or formatting of map data [7]
19/5719 •	 using planar vibrating masses driven in a 	21/34	 Route searching; Route guidance [7]
	translation vibration along an axis [2012.01]	21/36	 Input/output arrangements for on-board
19/5726 •	 • Signal processing [2012.01] 		computers [7]
19/5733 •	 Structural details or topology [2012.01] 	00/00	No. 1 . 11
19/574 •	 the devices having two sensing masses in 	22/00	Measuring distance traversed on the ground by vehicles, persons, animals or other moving solid
	anti-phase motion [2012.01]		bodies, e.g. using odometers or using pedometers
19/5747 •	 each sensing mass being connected to a 	22/02	 by conversion into electric waveforms and
	driving mass, e.g. driving	22/02	subsequent integration, e.g. using tachometer
	frames [2012.01]		generator
19/5755 •	• • • the devices having a single sensing		o .
	mass [2012.01]	23/00	Combined instruments indicating more than one
19/5762 •	• • • the sensing mass being connected to a		navigational value, e.g. for aircraft; Combined
	driving mass, e.g. driving		measuring devices for measuring two or more
10/5760 -	frames [2012.01]		variables of movement, e.g. distance, speed,
	• Manufacturing; Mounting; Housings [2012.01]		acceleration
19/5//6 •	• Signal processing not specific to any of the	25/00	Manufacturing, calibrating, cleaning, or repairing
	devices covered by groups G01C 19/5607- G01C 19/5719 [2012.01]	=0,00	instruments or devices referred to in the other
19/5783 •	 Mountings or housings not specific to any of the 		groups of this subclass (testing, calibrating, or
19/9/03	devices covered by groups G01C 19/5607-		compensating compasses G01C 17/38)
	G01C 19/5719 [2012.01]		
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G01D MEASURING NOT SPECIALLY ADAPTED FOR A SPECIFIC VARIABLE; ARRANGEMENTS FOR MEASURING TWO OR MORE VARIABLES NOT COVERED BY A SINGLE OTHER SUBCLASS; TARIFF METERING APPARATUS; TRANSFERRING OR TRANSDUCING ARRANGEMENTS NOT SPECIALLY ADAPTED FOR A SPECIFIC VARIABLE; MEASURING OR TESTING NOT OTHERWISE PROVIDED FOR

Note(s)

- 1. This subclass covers:
 - devices for indicating or recording the results of measurements, not peculiar to variables covered by a single other subclass;
 - analogous arrangements but in which the input is not a variable to be measured, e.g. a hand operation;
 - details of measuring instruments, which are of general interest;
 - measurement transducers not adapted solely for the measurement of a single specified variable and not provided for elsewhere, i.e. means for converting the output of a sensing member to another variable where the form or nature of the sensing member does not constrain the means for converting;
 - measuring or testing not otherwise provided for.
- 2. Attention is drawn to the Notes following the title of class G01.

Subclass index

MEASURING ARRANGEMENTS IN GENERAL	
With data restitution in other form than their instantaneous value	1/00
With provision for special purposes	3/00
Transferring or transducing arrangements not specially adapted for a specific variable	5/00
Component parts	11/00
INDICATING; COMPONENT PARTS OF INDICATORS	7/00, 13/00
RECORDING; COMPONENT PARTS OF RECORDERS	9/00, 15/00
TESTING OR CALIBRATING	18/00
MEASURING OR TESTING NOT OTHERWISE PROVIDED FOR	21/00
TARIFF METERING	4/00

- 1/00 Measuring arrangements giving results other than momentary value of variable, of general application (G01D 3/00 takes precedence; in tariff metering apparatus G01D 4/00; transducers not specially adapted for a specific variable G01D 5/00)
- giving mean values, e.g. root mean square values (measuring root mean square values of currents or voltages G01R 19/02)
- 1/04 giving integrated values (giving mean values G01D 1/02)
- 1/06 • by intermittent summation
- 1/08 • over fixed periods of time
- 1/10 giving differentiated values
- 1/12 giving a maximum or minimum of a value
- giving a distribution function of a value, i.e. number of times the value comes within specified ranges of amplitude
- giving a value which is a function of two or more values, e.g. product, ratio
- with arrangements for signalling that a predetermined value of an unspecified parameter has been exceeded (G01D 1/14 takes precedence) [3]
- 3/00 Measuring arrangements with provision for the special purposes referred to in the subgroups of this group
- with provision for altering or correcting the transfer function
- 3/024 • for range change; Arrangements for substituting one sensing member by another [6]
- 3/028 mitigating undesired influences, e.g. temperature, pressure [6]
- 3/032 • affecting incoming signal, e.g. by averaging; gating undesired signals [6]
- 3/036 • on measuring arrangements themselves [6]

- with provision for operation by a null method
- with provision for safeguarding the apparatus, e.g. against abnormal operation, against breakdown
- with provision for switching-in of additional or auxiliary indicators or recorders
- **4/00 Tariff metering apparatus** (in taximeters G07B 13/00; apparatus actuated by coins, cards or the like with meter-controlled dispensing of liquid, gas, or electricity G07F 15/00)
- 4/02 Details
- 4/04 Resetting-mechanisms, e.g. for indicating members
- 4/06
 Arrangement of clutches between driving and indicating member, e.g. of hysteresis clutch (G01D 4/04 takes precedence)
- 4/08 Transfer of indication from a counter into a summing counter
- 4/10 Maximum indicating or recording apparatus, i.e. where the tariff for a period is based on a maximum demand within that period
- 4/12 Apparatus for indicating or recording progressive maximum
- Fixed-demand indicating or recording apparatus,
 i.e. where indication is made when a
 predetermined quantity has been consumed during
 a time interval greater or less than a predetermined
 time interval
- 4/16 Apparatus for indicating or recording maximum or minimum load hours
- Apparatus for indicating or recording overconsumption with opposing torque which comes into effect when a predetermined level is exceeded, e.g. subtraction meters

5/00 Mechanical means for transferring the output of a sensing member; Means for converting the output of a sensing member to another variable where the form or nature of the sensing member does not constrain the means for converting; Transducers not specially adapted for a specific variable

(G01D 3/00 takes precedence; specially adapted for apparatus giving results other than momentary value of variable G01D 1/00) [6]

Note(s)

Groups G01D 5/02-G01D 5/54 are distinguished by the means which is of major importance. Thus the mere application of other means for giving a final indication does not affect the classification.

- 5/02 using mechanical means
- 5/04 • using levers; using cams; using gearing
- 5/06 acting through a wall or enclosure, e.g. by bellows, by magnetic coupling
- 5/08 Reducing the effects of friction, e.g. by applying vibrations
- 5/10 Applying external forces to increase force available for operation of indicating or recording part
- using electric or magnetic means (G01D 5/06 takes precedence) [3]
- 5/14 • influencing the magnitude of a current or voltage
- 5/16 • by varying resistance
- 5/165 • by relative movement of a point of contact and a resistive track **[6]**
- 5/18 • by varying effective impedance of discharge tubes or semiconductor devices
- 5/20 • by varying inductance, e.g. by a movable armature
- 5/22 • differentially influencing two coils
- 5/24 • by varying capacitance
- 5/241 • by relative movement of capacitor electrodes [6]
- 5/242 • by varying output of an electrodynamic device, e.g. of a tachodynamo
- 5/243 • influencing the phase or frequency of ac
- 5/244 • influencing characteristics of pulses or pulse trains; generating pulses or pulse trains [6]
- 5/245 • using a variable number of pulses in a train
- 5/246 • by varying the duration of individual pulses
- 5/247 • using time shifts of pulses
- 5/248 • by varying pulse repetition frequency
- 5/249 • using pulse code
- 5/25 Selecting one or more conductors or channels from a plurality of conductors or channels, e.g. by closing contacts
- 5/251 • one conductor or channel
- 5/252 • a combination of conductors or channels
- using optical means, i.e. using infra-red, visible or ultra-violet light
- 5/28 with deflection of beams of light, e.g. for direct optical indication (G01D 5/40 takes precedence)
- 5/30 • the beams of light being detected by photocells
- • with attenuation or whole or partial obturation of beams of light (G01D 5/40 takes precedence)
- 5/34 • the beams of light being detected by photocells
- 5/347 • using displacement encoding scales [6]
- 5/353 • • influencing the transmission properties of an optical fibre **[6]**
- 5/36 • Forming the light into pulses
- 5/38 • by diffraction gratings

- 5/39
 Scanning a visible indication of the measured value and reproducing this indication at a remote place, e.g. on the screen of a cathode-ray tube
- 5/40 • specially adapted for use with infra-red light
- 5/42 using fluid means
- 5/44 • using jets of fluid
- 5/46 • by deflecting or throttling the flow
- using wave or particle radiation means (G01D 5/26 takes precedence)
- 5/50 derived from a radioactive source
- 5/52 • detected by a counter tube
- 5/54 using means specified in two or more of groups G01D 5/02, G01D 5/12, G01D 5/26, G01D 5/42, and G01D 5/48

Note(s)

Classification is made in this group only if no other group can be selected as being predominantly applicable.

Note(s)

For a combination of two or more of the means specified, the first applicable one of subgroups G01D 5/56-G01D 5/62 takes precedence over any others of these groups.

- 5/56 • using electric or magnetic means
- 5/58 using optical means, i.e. using infra-red, visible or ultra-violet light
- 5/60 • using fluid means
- 5/62 using wave or particle radiation means not covered by group G01D 5/58

7/00 Indicating measured values

- 7/02 Indicating value of two or more variables simultaneously
- using a separate indicating element for each variable
- 7/06 • Luminous indications projected on a common screen
- 7/08 using a common indicating element for two or more variables
- 7/10 • giving indication in co-ordinate form
- 7/12 Audible indication of meter readings, e.g. for the blind [2]

9/00 Recording measured values

- 9/02 Producing one or more recordings of the values of a single variable
- 9/04 with provision for multiple or alternative recording
- 9/06 • Multiple recording, e.g. duplicating
- 9/08 • giving both graphical and numerical recording
- 9/10 the recording element, e.g. stylus, being controlled in accordance with the variable, and the recording medium, e.g. paper roll, being controlled in accordance with time
- 9/12 • recording occurring continuously
- 9/14 • with provision for altering speed of recording medium in accordance with the magnitude of the variable to be recorded
- 9/16 • recording occurring at separated intervals, e.g. by chopper bar
- 9/18 • recording element actuated only upon change in value of variable

0.400		10 (00	
9/20	• • the recording element, e.g. stylus, being controlled	13/02	• Scales; Dials
	in accordance with time and the recording	13/04	• • Construction
	medium, e.g. paper roll, being controlled in accordance with the variable	13/06	• • • Moving bands (G01D 13/10 takes precedence)
9/22	recording occurring continuously	13/08	• • Rotating drums (G01D 13/10 takes precedence)
9/24	recording occurring continuously recording occurring at separated intervals, e.g. by chopper bar	13/10	 • with adjustable scales; with auxiliary scales, e.g. vernier
0/26	* **	13/12	• • Graduation
9/26	 either the recording element, e.g. stylus, or the recording medium, e.g. paper roll, being 	13/14	 for rotations of more than 360°
	controlled in accordance with both time and the	13/16	 • • with staggered markings
	variable	13/18	 • with raised or recessed markings
9/28	Producing one or more recordings, each recording	13/20	 • • with luminescent markings
	being of the values of two or more different variables	13/22	 Pointers, e.g. settable pointer
	(G01D 9/38, G01D 9/40 take precedence)	13/24	 for indicating a maximum or minimum
9/30	 there being a separate recording element for each variable, e.g. multiple-pen recorder 	13/26	 adapted to perform a further operation, e.g. making electrical contact
9/32	 there being a common recording element for two or more variables 	13/28	• • with luminescent markings
9/34	• • • the variables being recorded in predetermined	15/00	Component parts of recorders for measuring
9/36	sequence • • • in separate columns		arrangements not specially adapted for a specific variable
9/38	Producing one or more recordings, each recording	15/02	 Styli or other recording elements acting to
3730	being produced by controlling the recording element,		mechanically deform or perforate the recording
	e.g. stylus, in accordance with one variable and		surface (printing recording elements G01D 15/20)
	controlling the recording medium, e.g. paper roll, in	15/04	acting to punch holes in the recording surface
	accordance with another variable	15/06	Electric recording elements, e.g. electrolytic
9/40	Producing one or more recordings, each recording	15/08	for spark erosion
	being produced by controlling either the recording element, e.g. stylus, or the recording medium, e.g.	15/10	 Heated recording elements acting on heat-sensitive layers
	paper roll, in accordance with two or more variables	15/12	 Magnetic recording elements
9/42	 Recording indications of measuring instruments by photographic means, e.g. of counters 	15/14	 Optical recording elements; Recording elements using X- or nuclear radiation
11/00	Component parts of measuring arrangements not	15/16	 Recording elements transferring recording material,
11/00	specially adapted for a specific variable (G01D 13/00,		e.g. ink, to the recording surface (printing recording
	G01D 15/00 take precedence)		elements G01D 15/20)
11/02	Bearings or suspensions for moving parts	15/18	Nozzles emitting recording material
11/04	Knive-edge bearings	15/20	Recording elements for printing with ink or for
11/06	Strip or thread suspensions, e.g. in tension		printing by deformation or perforation of the recording surface, e.g. embossing
11/08	Elements for balancing moving parts	15/22	Chopper bars for bringing recording element into
11/10	Elements for damping the movement of parts	13/22	contact with recording surface
11/12	using fluid damping	15/24	Drives for recording elements or surfaces, not
11/14	using magnetic induction damping	13/24	covered by group G01D 5/00
11/16	Elements for restraining or preventing the movement	15/26	operating by clockwork
11/10	of parts, e.g. for zeroising (caging of moving parts	15/28	 Holding means for recording surfaces; Guiding
	when not in use G01D 11/20)		means for recording surfaces; Exchanging means for
11/18	Springs (G01D 11/06 takes precedence)		recording surfaces
11/20	Caging devices for moving parts when not in use	15/30	 for foldable strip charts
11/22	automatically actuated	15/32	for circular charts
11/24	Housings	15/34	 Recording surfaces
11/26	Windows; Cover glasses; Sealings therefor		
11/28	Structurally-combined illuminating devices	18/00	Testing or calibrating apparatus or arrangements
11/30	Supports specially adapted for an instrument;		provided for in groups G01D 1/00-G01D 15/00
	Supports specially adapted for a set of instruments	21/00	Measuring or testing not otherwise provided for
40 (00		21/02	Measuring two or more variables by means not
13/00	Component parts of indicators for measuring arrangements not specially adapted for a specific variable	-1, \-	covered by a single other subclass

G01F MEASURING VOLUME, VOLUME FLOW, MASS FLOW, OR LIQUID LEVEL; METERING BY VOLUME [2, 5]

Note(s)

Attention is drawn to the Notes following the title of class G01.

Subclass index

MEASURING VOLUME	17/00, 19/00, 22/00
MEASURING VOLUME FLOW	
In continuous flow; in discontinuous flow; by proportion of flow	1/00, 3/00, 5/00
With multiple measuring ranges	7/00
By comparison with another value	
LEVEL INDICATORS	
METERING BY VOLUME	11/00, 13/00
DETAILS, ACCESSORIES	15/00
TESTING, CALIBRATING	25/00

Measuring volume flow

1/00 Measuring the volume flow or mass flow of fluid or fluent solid material wherein the fluid passes through the meter in a continuous flow (measuring a proportion of the volume flow G01F 5/00) [2]

Note(s)

Groups G01F 1/704-G01F 1/76 take precedence over groups G01F 1/05-G01F 1/68.

- 1/05 by using mechanical effects [2]
- 1/06 using rotating vanes with tangential admission [2]
- 1/07 • with mechanical coupling to the indicating device [2]
- 1/075 • with magnetic or electromagnetic coupling to the indicating device [2]
- 1/08 • Adjusting, correcting, or compensating means therefor [2]
- 1/10 • using rotating vanes with axial admission [2]
- 1/11 • with mechanical coupling to the indicating device [2]
- 1/115 • with magnetic or electromagnetic coupling to the indicating device [2]
- 1/12 • Adjusting, correcting, or compensating means
- 1/20 • by detection of dynamic effects of the fluid flow [2]
- 1/22 • by variable-area meters [2]
- 1/24 • with magnetic or electric coupling to the indicating device [2]
- 1/26 • of the valve type **[2]**
- 1/28 • by drag-force, e.g. vane type or impact flowmeter [2]
- 1/30 • for fluent solid material [2]
- 1/32 • by swirl flowmeter, e.g. using Karman vortices [2]
- 1/34 • by measuring pressure or differential pressure [2]
- 1/36 • the pressure or differential pressure being created by the use of flow constriction [2]
- 1/37 • • the pressure or differential pressure being measured by means of communicating tubes or reservoirs with movable fluid levels, e.g. by U-tubes [2]
- 1/38 • • the pressure or differential pressure being measured by means of a movable element, e.g. diaphragm, piston, Bourdon tube or flexible capsule [2]
- 1/40 • Details of construction of the flow constriction devices [2]
- 1/42 • • Orifices or nozzles **[2]**
- 1/44 • • Venturi tubes [2]
- 1/46 • • Pitot tubes **[2]**

- 1/48 • the pressure or differential pressure being created by a capillary element [2]
- 1/50 • Correcting or compensating means [2]
- 1/52 by measuring the height of the fluid level due to the lifting power of the fluid flow [2]
- 1/54 by means of chains, flexible bands, or wires introduced into, and moved by, the flow [2]
- 1/56 by using electric or magnetic effects (G01F 1/66 takes precedence) [2]
- 1/58 • by electromagnetic flowmeters [2]
- 1/60 • Circuits therefor [2]
- by measuring electrical currents passing through the fluid flow; by measuring electrical potential generated by the fluid flow, e.g. by electrochemical, contact, or friction effects (G01F 1/58 takes precedence) [2]
- by measuring frequency, phase shift, or propagation time of electromagnetic or other waves, e.g. ultrasonic flowmeters [2]
- 1/68 by using thermal effects [2]
- 1/684 Structural arrangements; Mounting of elements, e.g. in relation to fluid flow **[6]**
- 1/688 • using a particular type of heating, cooling or sensing element [6]
- 1/69 • of resistive type **[6]**
- 1/692 • • Thin-film arrangements [6]
- 1/696 Circuits therefor, e.g. constant-current flow meters **[6]**
- 1/698 • Feedback or rebalancing circuits, e.g. self heated constant temperature flowmeters **[6]**
- 1/699 • by control of a separate heating or cooling element **[6]**
- using marked regions or existing inhomogeneities within the fluid stream, e.g. statistically occurring variations in a fluid parameter (G01F 1/76, G01F 25/00 take precedence) [4]
- 1/708 Measuring the time taken to traverse a fixed distance [4]
- 1/712 • using auto-correlation or cross-correlation detection means [4]
- 1/716 • using electron paramagnetic resonance (EPR) or nuclear magnetic resonance (NMR) [4]
- 1/72 Devices for measuring pulsing fluid flows [2]
- 1/74 Devices for measuring flow of a fluid or flow of a fluent solid material in suspension in another fluid [2]
- Devices for measuring mass flow of a fluid or a fluent solid material [2]
- 1/78 • Direct mass flowmeters [2]
- operating by measuring pressure, force, momentum, or frequency of a fluid flow to which a rotational movement has been imparted [2]

1/82	• • • using a driven wheel as impeller and one or more other wheels or moving elements	11/06	• • with provision for varying the stroke of the piston
	which are angularly restrained by a resilient	11/08	 of the diaphragm or bellows type
	member, e.g. spring member, as the	11/10	 with measuring chambers moved during operation
1/84	measuring device [2]	11/12	• • of the valve type, i.e. the separating being effected
1/86	• • Coriolis or gyroscopic mass flowmeters [2]• Indirect mass flowmeters, e.g. measuring volume		by fluid-tight or powder-tight movements
1/00	flow and density, temperature, or pressure [2]		(involving the tilting or inverting of the supply vessel G01F 11/26)
1/88	• • with differential-pressure measurement to	11/14	• • wherein the measuring chamber reciprocates
	determine the volume flow [2]	11/16	• • • for liquid or semiliquid
1/90	 • with positive-displacement meter or turbine 	11/18	• • • for fluent solid material
	meter to determine the volume flow [2]	11/20	• • • wherein the measuring chamber rotates or
3/00	Measuring the volume flow of fluids or fluent solid		oscillates
	material wherein the fluid passes through the meter	11/22	• • • • for liquid or semiliquid
	in successive and more or less isolated quantities, the	11/24	• • • • for fluent solid material
	meter being driven by the flow (measuring a	11/26	 wherein the measuring chamber is filled and emptied by tilting or inverting the supply vessel,
3/02	proportion of the volume flow G01F 5/00) • with measuring chambers which expand or contract		e.g. bottle-emptying apparatus
3/02	during measurement	11/28	 with stationary measuring chambers having constant
3/04	having rigid movable walls		volume during measurement
3/06	• • comprising members rotating in a fluid-tight or	11/30	• • with supply and discharge valves of the lift or
	substantially fluid-tight manner in a housing		plug-lift type
3/08	 • • • Rotary-piston or ring-piston meters 	11/32	• • • for liquid or semiliquid
3/10	• • • Geared or lobed impeller meters	11/34	• • • for fluent solid material
3/12	• • • Meters with nutating members, e.g. discs	11/36	 with supply or discharge valves of the rectilinearly-moved slide type
3/14	• • • comprising reciprocating pistons, e.g.	11/38	• • for liquid or semiliquid
3/16	reciprocating in a rotating body • • • in stationary cylinders	11/40	• • for fluent or solid material
3/18	· · · · involving two or more cylinders	11/42	 with supply or discharge valves of the rotary or
3/20	having flexible movable walls, e.g. diaphragms,		oscillatory type
<i>5,</i> 2 ⁶	bellows	11/44	 for liquid or semiliquid
3/22	• • • for gases	11/46	• • for fluent solid material
3/24	with measuring chambers moved during operation	13/00	Apparatus for measuring by volume and delivering
2/20	(wet gas-meters G01F 3/30)		fluids or fluent solid materials, not provided for in
3/26 3/28	 Tilting-trap meters on carriers rotated by the weight of the liquid in		the preceding groups
3/20	the measuring chambers		
3/30	Wet gas-meters		
3/32	 comprising partitioned drums rotating or nutating 	15/00	Details of, or accessories for, apparatus of groups
	in a liquid		G01F 1/00-G01F 13/00 insofar as such details or
3/34	 comprising bells reciprocating in a liquid 		appliances are not adapted to particular types of
3/36	 with stationary measuring chambers having constant 	15/02	such apparatus
	volume during measurement (with measuring chambers which expand or contract during	15/02	 Compensating or correcting for variations in pressure, density, or temperature
	measurement G01F 3/02)	15/04	of gases to be measured
3/38	 having only one measuring chamber 	15/06	Indicating or recording devices, e.g. for remote
			indication
5/00	Measuring a proportion of the volume flow	15/07	• Integration to give total flow, e.g. using
7/00	Volume-flow measuring devices with two or more	15/075	mechanically-operated integrating mechanism [2]
	measuring ranges; Compound meters	15/075 15/08	using electrically-operated integrating means [2]Air or gas separators in combination with liquid
0 /00	Measuring valums flow relative to another variable	13/00	meters; Liquid separators in combination with gas-
9/00	Measuring volume flow relative to another variable, e.g. of liquid fuel for an engine		meters
9/02	 wherein the other variable is the speed of a vehicle 	15/10	• Preventing damage by freezing or excess pressure or
-			insufficient pressure
		15/12	Cleaning arrangements; Filters
Metering	<u>g by volume</u>	15/14 15/16	 Casings, e.g. of special material Diaphragms: Bellows: Mountings therefor
		15/16	• Diabilidenis, Denows, Monnines incretor

- 11/00 Apparatus requiring external operation adapted at each repeated and identical operation to measure and separate a predetermined volume of fluid or fluent solid material from a supply or container, without regard to weight, and to deliver it
- 11/02 • with measuring chambers which expand or contract during measurement
- 11/04 • • of the free-piston type

• Supports or connecting means for meters

Measurin	ng volume	23/284	• • • Electromagnetic waves [6]
17/00	Methods or apparatus for determining the capacity of containers or cavities, or the volume of solid bodies (measuring linear dimensions to determine volume G01B)	23/288 23/292 23/296 23/30 23/32	 • • • X-rays; Gamma rays [6] • • • Light [6] • • Acoustic waves [6] • by floats [4] • using rotatable arms or other pivotable
19/00	Calibrated capacity measures for fluids or fluent solid material, e.g. measuring cups	23/34	transmission elements [4] • • using mechanically actuated indicating
22/00	Methods or apparatus for measuring volume of fluids or fluent solid material, not otherwise provided for [5]	23/36 23/38	 means [4] using electrically actuated indicating means [4] using magnetically actuated indicating means [4]
22/02	involving measurement of pressure [5]	23/40 23/42	 using bands or wires as transmission elements [4] using mechanically actuated indicating
Level ind	icators		means [4]
23/00	Indicating or measuring liquid level, or level of fluent solid material, e.g. indicating in terms of volume,	23/44 23/46	 using electrically actuated indicating means [4] using magnetically actuated indicating means [4]
	indicating by means of an alarm	23/48	using twisted spindles as transmission elements [4]
23/02	by gauge glasses or other apparatus involving a window or transparent tube for directly observing the level to be measured or the level of a liquid column in free communication with the main body of the	23/50 23/52 23/54	 using mechanically actuated indicating means [4] using electrically actuated indicating means [4] using magnetically actuated indicating means [4]
23/04	liquid • by dip members, e.g. dip-sticks	23/56	• using elements rigidly fixed to, and rectilinearly
23/14	 by dip members, e.g. dip-stees by measurement of pressure 		moving with, the floats as transmission elements [4]
23/16	 Indicating, recording, or alarm devices being actuated by mechanical or fluid means, e.g. using 	23/58	• • using mechanically actuated indicating means [4]
	gas, mercury, or a diaphragm as transmitting element, or by a column of liquid	23/60 23/62	using electrically actuated indicating means [4]using magnetically actuated indicating
23/18	 Indicating, recording, or alarm devices actuated electrically 	23/64	means [4] • of the free float type [4]
23/20	 by measurement of weight, e.g. to determine the level of stored liquefied gas 	23/66	• • using mechanically actuated indicating means [4]
23/22	by measurement of physical variables, other than linear dimensions, pressure, or weight, dependent on the level to be measured, e.g. by difference of heat transfer of steam or water (involving the use of floats COLE 23(30)).	23/68 23/70 23/72	 using electrically actuated indicating means [4] for sensing changes in level only at discrete points [4] using magnetically actuated indicating
23/24	 G01F 23/30) by measuring variations of resistance of resistors due to contact with conductor fluid 	23/74	means [4]for sensing changes in level only at discrete
23/26	 by measuring variations of capacity or inductance of capacitors or inductors arising from the 	23/76	points [4] • characterised by the construction of the float [4]
23/28	 presence of liquid or fluent solid material in the electric or electromagnetic fields by measuring the variations of parameters of electromagnetic or acoustic waves applied directly to the liquid or fluent solid material [6] 	25/00	Testing or calibrating of apparatus for measuring volume, volume flow, or liquid level, or for metering by volume
G01G	WEIGHING		
Note(s)			
Attention	is drawn to the Notes following the title of class G01.		
<u>Subclass</u>	<u>index</u>		
Mech Fluidi	NG APPARATUS CHARACTERISED BY THE MEANS USED anical		5/00

WEIGHING APPARATUS CHARACTERISED BY, OR ADAPTED FOR, THE WEIGHING OF LOADS

DETAILS	21/00
AUXILIARY DEVICES	23/00

1/00	Weighing apparatus involving the use of a counterweight or other counterbalancing mass	3/16	• • measuring variations of frequency of oscillations of the body
1/02	Pendulum-weight apparatus	3/18	 Temperature-compensating arrangements
1/04	 the pendulum having a fixed pivot axis 	= /00	
1/06	 • with a plurality of pendulums 	5/00	Weighing apparatus wherein the balancing is
1/08	 the pendulum having a moving pivot axis, e.g. a floating pendulum 	5/02	 effected by fluid action with a float or other member variably immersed in
1/10	 • with a plurality of pendulums 	5/04	liquidwith means for measuring the pressure imposed by
1/12	 Constructional arrangements for obtaining equal indicative divisions 	5/04	the load on a liquid using electrical indicating means [3]
1/14	 Temperature-compensating arrangements 	3/00	using electrical indicating means [3]
1/16	 Means for correcting for obliquity of mounting 	7/00	Weighing apparatus wherein the balancing is
1/18	Balances involving the use of a pivoted beam, i.e. beam balances		effected by magnetic, electromagnetic, or electrostatic action, or by means not provided for in
1/20	 Beam balances having the pans carried below the beam, and for use with separate counterweights 	7/02	groups G01G 1/00-G01G 5/00
1/22	• • for precision weighing		by electromagnetic action
1/24	Platform-type scales, i.e. having the pans carried	7/04	with means for regulating the current to solenoids
	above the beam	7/06	by electrostatic action Methods of an apparatus for the determination of
1/26	 with associated counterweight or set of counterweights 	9/00	Methods of, or apparatus for, the determination of weight, not provided for in groups G01G 1/00-
1/28	• • involving means for automatically lifting		G01G 7/00
1/20	counterweights corresponding to the load		
1/29	• • • with electrical or electromechanical control means [3]	11/00	Apparatus for weighing a continuous stream of material during flow; Conveyor-belt weighers
1/30	• • • wherein the counterweight is in the form of a	11/02	 having mechanical weight-sensitive devices
	chain	11/04	 having electrical weight-sensitive devices
1/32	• • • wherein the counterweights are in the form of	11/06	 having fluid weight-sensitive devices
	rider-weights	11/08	 having means for controlling the rate of feed or
1/34	• • • involving a fixed counterweight, with poise-		discharge
	weights selectively added to the load side	11/10	• • by controlling the height of the material on the belt
1/36	 • wherein the counterweights are slidable along 	11/12	 by controlling the speed of the belt
	the beam, e.g. steelyards	11/14	 using totalising or integrating devices
1/38	• • • with automatically-driven counterweight	11/16	 being electric or electronic devices [3]
1/40	 specially adapted for weighing by substitution 	11/18	 using digital counting [3]
1/42	• • Temperature-compensating arrangements	11/20	 being mechanical devices [3]
3/00	Weighing apparatus characterised by the use of elastically-deformable members, e.g. spring balances	13/00	Weighing apparatus with automatic feed or discharge for weighing-out batches of material (for
3/02	wherein the weighing element is in the form of a helical spring		weighing a continuous stream G01G 11/00; checkweighing G01G 15/00; for fluids G01G 17/04;
3/04	using a plurality of springs		apportioning by weight materials to be mixed
3/06	 wherein the weighing element is in the form of a 		G01G 19/22; combinatorial weighing G01G 19/387) [5]
	spiral spring	13/02	Means for automatically loading weigh-pans or other
3/08	 wherein the weighing element is in the form of a leaf 		receptacles, e.g. disposable containers, under control
	spring	12/04	of the weighing mechanism
3/10	 wherein the torsional deformation of a weighing element is measured 	13/04	involving dribble-feed means controlled by the weighing mechanism to top up the receptacle to the toget veright.
3/12	 wherein the weighing element is in the form of a solid body stressed by pressure or tension during 	13/06	the target weight• wherein the main feed is effected by gravity
	weighing	12 /00	from a hopper or chute
3/13	 having piezo-electric or piezo-resistive properties [3] 	13/08	• • • wherein the main feed is effected by mechanical conveying means, e.g. by belt
3/14	 measuring variations of electrical resistance (G01G 3/13 takes precedence) [3] 	13/10	 conveyors or by vibratory conveyors wherein the main feed is effected by pneumatic
3/142	• • Circuits specially adapted therefor [3]		conveying means, e.g. by fluidised feed of granular material
3/145	• • • involving comparison with a reference value (G01G 3/147 takes precedence) [3]	13/12	Arrangements for compensating for material suspended at cut-off, i.e. for material which is still
3/147	• • • involving digital counting [3]		falling from the feeder when the weigher stops the
3/15	measuring variations of magnetic properties		feeder

13/14	Arrangements for determination of, or	19/28	• • having fluid weight-sensitive devices	
	compensation for, the tare weight of an unloaded	19/30	 having electrical weight-sensitive devices 	
10/16	container, e.g. of a disposable container	19/32	 using two or more weighing apparatus 	
13/16	 Means for automatically discharging weigh receptacles under control of the weighing mechanism 	19/34	 with electrical control means 	
13/18	 by valves or flaps in the container bottom 	19/36	 with mechanical control means 	
13/10	by varves of maps in the container bottom by screw conveyors in the weigh receptacle	19/38	 programme controlled, e.g. by perforated tape 	
13/20	 by screw conveyors in the weigh receptacle by tilting or rotating the receptacle 	19/387	for combinatorial weighing, i.e. selecting a	
13/24	Weighing mechanism control arrangements for		combination of articles whose total weight or number	3r
13/24	automatic feed or discharge	10/202	is closest to a desired value [5]	
13/26	involving fluid-pressure systems	19/393 19/40	• using two or more weighing units [5]	
13/28	 involving variation of an electrical variable which is used to control loading or discharge of the 	19/40	 with provisions for indicating, recording, or computing price or other quantities dependent on the weight (indicating means for weighing apparatus 	5
40.400=	receptacle		G01G 23/18; recording means for weighing	
13/285	• • involving comparison with a reference value	10/11	apparatus G01G 23/18)	
12/20	(G01G 13/29 takes precedence) [3]	19/41	using mechanical computing means	
13/29 13/295	• • involving digital counting [3]	19/413	• using electromechanical or electronic computing	
13/295	 • for controlling automatic loading of the receptacle [3] 	10/414	means	
13/30	involving limit switches or position-sensing		• • using electronic computing means only [5]	
13/30	switches	19/415 19/417	• • • combined with recording means [5]	
13/32	• • involving photoelectric devices	19/41/	 with provision for checking computing part of balance 	
13/34	involving photoelectric devices involving mechanical linkage motivated by the	19/42	 for counting by weighing (G01G 19/387 takes 	
15/51	weighing mechanism	13/42	precedence) [5]	
15/00	A consequents for a dead of a stable as of contracts.	19/44	 for weighing persons 	
15/00	Arrangements for check-weighing of materials dispensed into removable containers	19/46	• • Spring balances specially adapted for this purpose	e
15/02	with provision for adding or removing a make-up	19/48	 Pendulum balances specially adapted for this 	
13/02	quantity of material to obtain the desired net weight		purpose	
	(dribble-feed means for automatic batch-weighers G01G 13/04)	19/50	 having additional measuring devices, e.g. for height 	
15/04	• with provision for adding or removing a make-up	19/52	 Weighing apparatus combined with other objects, e., with furniture (with walking-sticks A45B 3/08) 	g.
	quantity of material to obtain the desired gross weight (dribble-feed means for automatic batch-	19/54	combined with writing implements or paper-knives	
	weighers G01G 13/04)	19/56	 combined with handles of tools or of household 	
17/00	Apparatus for, or methods of, weighing material of	15750	implements	
	special form or property (determining weight by	19/58	 combined with handles of suit-cases or trunks 	
	measuring volume G01F)	19/60	 combined with fishing equipment, e.g. with 	
17/02	 for weighing material of filamentary or sheet form 		fishing rods	
17/04	 for weighing fluids, e.g. gases, pastes 	19/62	 Over or under weighing apparatus [3] 	
17/06	 having means for controlling the supply or 	19/64	 Percentage-indicating weighing apparatus, i.e. for 	
	discharge		expressing the weight as a percentage of a	
17/08	 for weighing livestock 		predetermined or initial weight [3]	
19/00	Weighing apparatus or methods adapted for special	21/00	Details of weighing apparatus	
157 00	purposes not provided for in groups G01G 11/00-	21/02	Arrangements of bearings	
	G01G 17/00	21/04	 of knife-edge bearings 	
19/02	 for weighing wheeled or rolling bodies, e.g. vehicles 	21/06	 of ball or roller bearings 	
19/03	 for weighing during motion (G01G 19/04, 	21/07	 of flexure-plate bearings [3] 	
	G01G 19/07 take precedence) [3]	21/08	 Bearing mountings or adjusting means therefor 	
19/04	 for weighing railway vehicles 	21/10	 Floating suspensions; Arrangements of shock- 	
19/06	• • • on overhead rails	21/10	absorbers	
19/07	for weighing aircraft	21/12	 Devices for preventing derangement 	
19/08	 for incorporation in vehicles 	21/14	• Beams	
19/10	 having fluid weight-sensitive devices 	21/16	 of composite construction; Connections between 	
19/12	 having electrical weight-sensitive devices 		different beams	
19/14	 for weighing suspended loads (G01G 3/00 takes precedence) 	21/18	 Link connections between the beam and the weigh pan 	
19/16	 having fluid weight-sensitive devices 	21/20	for precision weighing apparatus	
19/18	having electrical weight-sensitive devices	21/22	 Weigh-pans or other weighing receptacles; Weighing 	g
19/20	for weighing unbalanced loads		platforms	J
19/22	for apportioning materials by weighing prior to mixing them	21/23	 Support or suspension of weighing platforms (G01G 21/24 takes precedence) [3] 	
19/24	using a single weighing apparatus	21/24	 Guides or linkages for ensuring parallel motion of the 	1e
19/26	• • associated with two or more counterweighted beams	2±/2 T	weigh-pans	

beams

21/26	 Counterweights; Poise-weights; Sets of weights; Holders for the reception of weights 	23/26	• • Drive for the indicating member, e.g. mechanical amplifiers
21/28	Frames; Housings	23/28	• • involving auxiliary or memory marks
21/30	 Means for preventing contamination by dust 	23/30	 • with means for illuminating the scale
23/00 23/01 23/02 23/04 23/06 23/08	 Auxiliary devices for weighing apparatus Testing or calibrating of weighing apparatus [3] Relieving mechanisms; Arrestment mechanisms for precision weighing apparatus Means for damping oscillations, e.g. of weigh-beams by fluid means 	23/32 23/34 23/35 23/36 23/365	(G01G 23/37 takes precedence) [3]
23/10	 by electric or magnetic means 	23/37	 • involving digital counting
23/12	 specially adapted for preventing oscillations due to movement of the load 	23/375 23/38	• • • during the movement of a coded element [3]• Recording or coding devices specially adapted for
23/14	 Devices for determining tare weight or for cancelling out the tare by zeroising, e.g. mechanically operated (in connection with automatic loading G01G 13/14) 	23/40 23/42	weighing apparatusmechanically operatedelectrically operated
23/16	 electrically or magnetically operated 	23/44	• • • Coding devices therefor [3]
23/18	 Indicating devices, e.g. for remote indication; Recording devices; Scales, e.g. graduated 	23/46	• • • Devices preventing recording until the weighing mechanism has come to rest [3]
23/20	Indicating the weight by mechanical means	23/48	Temperature-compensating arrangements
23/22	combined with price indicators		(G01G 1/14, G01G 1/42, G01G 3/18 take
23/24	• • • involving logarithmic scales		precedence) [3]

G01H MEASUREMENT OF MECHANICAL VIBRATIONS OR ULTRASONIC, SONIC OR INFRASONIC WAVES [4]

Note(s)

- 1. This subclass <u>covers</u> the combination of generation and measurement of mechanical vibrations.
- 2. Attention is drawn to the Notes following the title of class G01.

power; Measuring time integral of power [2]

Subclass index

PRINCIPLE OF THE MEASURING

Propagation velocity; reverberation time; resonant frequency; mechanical or acoustic impedance.........5/00, 7/00, 13/00, 15/00

1/00	Measuring vibrations in solids by using direct conduction to the detector (G01H 9/00, G01H 11/00 take precedence)	5/00	Measuring propagation velocity of ultrasonic, sonic or infrasonic waves
1/04	 of vibrations which are transverse to direction of 	7/00	Measuring reverberation time
1/06 1/08 1/10	propagation• Frequency• Amplitude• of torsional vibrations	9/00	Measuring mechanical vibrations or ultrasonic, sonic or infrasonic waves by using radiation-sensitive means, e.g. optical means
1/12	• of longitudinal or not specified vibrations [4]	11/00	Measuring mechanical vibrations or ultrasonic, sonic
1/14 1/16	• Frequency [4]• Amplitude [4]		or infrasonic waves by detecting changes in electric or magnetic properties
1/10	Ampittude [4]	11/02	by magnetic means, e.g. reluctance [4]
3/00	Measuring vibrations by using a detector in a fluid	11/04	 using magnetostrictive devices [4]
	(G01H 7/00, G01H 9/00, G01H 11/00 take precedence)	11/06	• by electric means [4]
3/04	 Frequency 	11/08	 using piezo-electric devices [4]
3/06	by electric means		
3/08	 Analysing frequencies present in complex vibrations, e.g. comparing harmonics present 	13/00	Measuring resonant frequency
3/10	Amplitude; Power	15/00	Measuring mechanical or acoustic impedance [3]
3/12	• • by electric means (G01H 3/14 takes precedence) [2]	17/00	Measuring mechanical vibrations or ultrasonic, sonic or infrasonic waves, not provided for in the other
3/14	Measuring mean amplitude; Measuring mean power: Measuring time integral of power [2].		groups of this subclass [4]

G01J MEASUREMENT OF INTENSITY, VELOCITY, SPECTRAL CONTENT, POLARISATION, PHASE OR PULSE CHARACTERISTICS OF INFRA-RED, VISIBLE OR ULTRA-VIOLET LIGHT; COLORIMETRY; RADIATION PYROMETRY [2]

Note(s)

- This subclass <u>covers</u> the detection of the presence or absence of infra-red, visible, or ultra-violet light, not otherwise provided for.
- Attention is drawn to the Notes following the title of class G01.

1/58 • using luminescence generated by light

PHOTOMETRY; PYROMETRY	.1/00,	5/00
SPECTROMETRY; MEASURING: POLARISATION; VELOCITY; PHASE; PULSES	.3/00,	4/00, 7/00, 9/00, 11/00

1/00	Photometry, e.g. photographic exposure meter (spectrophotometry G01J 3/00; specially adapted for	1/60	• by measuring the pupil of the eye
	radiation pyrometry G01J 5/00)	3/00	Spectrometry; Spectrophotometry;
1/02	• Details	2/02	Monochromators; Measuring colours [4]
1/04	 Optical or mechanical part 	3/02	• Details
1/06	 Restricting the angle of incident light 	3/04	Slit arrangements
1/08	Arrangements of light sources specially adapted	3/06	Scanning arrangements
	for photometry	3/08	Beam-switching arrangements
1/10	by comparison with reference light or electric value	3/10	 Arrangements of light sources specially adapted for spectrometry or colorimetry
1/12	• • using wholly visual means (G01J 1/20 takes	3/12	Generating the spectrum; Monochromators
1/14	precedence)using comparison with a surface of graded	3/14	• • using refracting elements, e.g. prism (G01J 3/18,
	brightness		G01J 3/26 take precedence)
1/16	 using electric radiation detectors (G01J 1/20 takes 	3/16	• • • with autocollimation
	precedence)	3/18	 using diffraction elements, e.g. grating
1/18	using comparison with a reference electric	3/20	 Rowland circle spectrometers
	value	3/22	 Littrow mirror spectrometers
1/20	 intensity of the measured or reference value being varied to equalise their effects at the detector, e.g. 	3/24	 using gratings profiled to favour a specific order
1/22	by varying incidence angleusing a variable element in the light-path, e.g.	3/26	 using multiple reflection, e.g. Fabry-Perot interferometer, variable interference filter
	filter, polarising means (G01J 1/34 takes precedence)	3/28	• Investigating the spectrum (using colour filters G01J 3/51) [4]
1/24	 • • • using electric radiation detectors 	3/30	 Measuring the intensity of spectral lines directly
1/26	• • • • adapted for automatic variation of the measured or reference value	3,30	on the spectrum itself (G01J 3/42, G01J 3/44 take precedence)
1/28	• • using variation of intensity or distance of source (G01J 1/34 takes precedence)	3/32	Investigating bands of a spectrum in sequence by a single detector
1/30	• • • using electric radiation detectors	3/36	 Investigating two or more bands of a spectrum
1/32	• • • • adapted for automatic variation of the	5/50	by separate detectors
	measured or reference value	3/40	 Measuring the intensity of spectral lines by
1/34	• • • using separate light-paths used alternately or sequentially, e.g. flicker		determining density of a photograph of the spectrum; Spectrography (G01J 3/42, G01J 3/44
1/36	• • • using electric radiation detectors		take precedence) [4]
1/38	 using wholly visual means (G01J 1/10 takes precedence) 	3/42	• • Absorption spectrometry; Double-beam spectrometry; Flicker spectrometry; Reflection
1/40	using limit of visibility or extinction effect		spectrometry (beam-switching arrangements
1/42	using electric radiation detectors (optical or		G01J 3/08) [4]
	mechanical part G01J 1/04; by comparison with a	3/427	- · · · · ·
1/44	reference light or electric value G01J 1/10) • Electric circuits	3/433	 • Modulation spectrometry; Derivative spectrometry [4]
1/46	using a capacitor	3/44	Raman spectrometry; Scattering spectrometry [4]
1/48	using a capacitor using chemical effects	3/443	
1/40	 using change in colour of an indicator, e.g. 	3/447	
1/30	actinometer	3/45	 Interferometric spectrometry [4]
1/52	using photographic effects	3/453	
1/54	 by observing photo-reactions between gases 	3/457	-
1/56	using radiation pressure or radiometer effect		(G01J 3/453 takes precedence) [4]

		11/00	Measuring the characteristics of individual optical pulses or of optical pulse trains [5]
5/26	• • • • Special adaptation for indicating or recording		the lower frequency obtained [3]
5/24	 • • • Use of a specially-adapted circuit, e.g. bridge circuit 	9/04	 by beating two waves of the same source but of different frequency and measuring the phase shift of
5/22	Electrical features List of a provide advantal singuit a graph of the control of the contr	9/02	 by interferometric methods [3]
5/20	using resistors, thermistors, or semiconductors sensitive to radiation		degree of coherence; Measuring optical wavelength (spectrometry G01J 3/00) [3]
5/18	• • • Special adaptation for indicating or recording	9/00	Measuring optical phase difference; Determining
F /10	ambient temperature or other variables	7/00	Measuring velocity of light
3/10	junction; Compensating influence of	5/62	 using means for chopping the light
5/14	Arrangements with respect to the cold	5/60	 using determination of colour temperature
5/14	using thermoelectric elements, e.g. thermocouples Electrical features		extinction effect
5/10	 using electric radiation detectors using thermoelectric elements, e.g. thermocouples 	5/58	 using absorption; using polarisation; using
5/08 5/10	 • Optical features using electric radiation detectors	5/56	• • • Electrical features
F /00	radiation	5/54	disappearing-filament pyrometer • • Optical features
5/06	Arrangements for eliminating effects of disturbing	5/52	• using comparison with reference sources, e.g.
5/04	• • Casings	5/50	 using techniques specified in the subgroups below
5/02	• Details	5/48	 using wholly visual means
5/00	Radiation pyrometry	5/46	 using radiation pressure or radiometer effect
4/04	 Polarimeters using electric detection means (G01J 4/02 takes precedence) [2] 	5/44	• • using change of resonant frequency, e.g. of piezo- electric crystal
4/04	half-shadow type [2]	5/42	using Golay cells
4/02	Polarimeters of separated-field type; Polarimeters of	5/40	using bimetallic elements
4/00	Measuring polarisation of light [2]	5/38	 using extension or expansion of solids or fluids
		5/36	using ionisation of gases
3/52	using colour charts	5/34	using capacitors
3/51	• • • using colour filters [4]	57 5 2	recording
3/50	• using electric radiation detectors [4]	5/32	• • • Special adaptation for indicating or
	G01J 5/60) [4]	5/30	• • Electrical features
	e.g. colorimeters (measuring colour temperature		voltaic cells

G01K MEASURING TEMPERATURE; MEASURING QUANTITY OF HEAT; THERMALLY-SENSITIVE ELEMENTS NOT OTHERWISE PROVIDED FOR (radiation pyrometry G01J 5/00)

Note(s)

- 1. In this subclass, the following term is used with the meaning indicated:
 - "thermometer" includes thermally-sensitive elements not provided for in other subclasses.
- 2. Attention is drawn to the Notes following the title of class G01.

Subclass index

MEASURING TEMPERATURE	
characterised by principle of operation	5/00, 7/00, 9/00, 11/00
Thermometers giving an indication other than the instantaneous value	3/00
Details of thermometers not specially adapted for particular types of thermometers	1/00
Adaptations of thermometers for specific purposes	
Testing and calibrating of thermometers	15/00
MEASURING QUANTITY OF HEAT; TESTING AND CALIBRATING OF CALORIMETERS	17/00, 19/00

1/00	Details of thermometers not specially adapted for particular types of thermometer (circuits for reducing thermal inertia G01K 7/42) [6]
1/02	• Special applications of indicating or recording means, e.g. for remote indications
1/04	• • Scales
1/06	• • • Arrangements for facilitating reading, e.g. illumination, magnifying glass

- 1/08 Protective devices, e.g. casings
- 1/10 • for preventing chemical attack
- 1/12 • for preventing damage due to heat overloading
- 1/14 Supports; Fastening devices; Mounting thermometers in particular locations
- 1/16 Special arrangements for conducting heat from the object to the sensitive element
- 1/18 • for reducing thermal inertia

 Compensating for effects of temperature changes other than those to be measured, e.g. changes in 	5/52	• • • with electrical conversion means for final indication
	5/54	 consisting of pivotally-connected elements
having parts which are deformable or displaceable	5/56	 constrained so that expansion or contraction causes a deformation of the solid
• • by means of compounded strips or plates, e.g.	5/58	• • • the solid body being constrained at more than one point, e.g. rod, plate, diaphragm
	F / CO	(G01K 5/62 takes precedence)
Compensating for effects of pressure changes		• • • the body being a flexible wire or ribbon
Thermometers giving results other than momentary value of temperature (G01K 7/42 takes		the solid body being formed of compounded strips or plates, e.g. bimetallic strip
		• • • Details of the compound system
	5/66	• • • • Selection of composition of the
in respect of time	F /C0	components of the system
• • in respect of space		• • • • Shape of the system
 giving differences of values; giving differentiated 	5/70	• specially adapted for indicating or recording• with electric transmission means for final
• • in respect of time, e.g. reacting only to a quick	7/00	indication
	7/00	Measuring temperature based on the use of electric
		or magnetic elements directly sensitive to heat (giving results other than momentary value of temperature
		G01K 3/00)
in respect of space	7/01	 using semiconducting elements having PN junctions
Measuring temperature based on the expansion or contraction of a material (G01K 9/00 takes	7/01	(G01K 7/02, G01K 7/16, G01K 7/30 take precedence) [6]
precedence; giving other than momentary value of	7/02	 using thermo-electric elements, e.g. thermo-couples
temperature G01K 3/00)		 the object to be measured not forming one of the
 the material being a liquid (G01K 5/32 takes 	7704	thermo-electric materials
*	7/06	• • • the thermo-electric materials being arranged
• • Details	.,	one within the other with the junction at one
Arrangements for driving back the liquid column	7/08	end exposed to the object, e.g. sheathed typethe object to be measured forming one of the
Capillary tubes	7700	thermo-electric materials, e.g. pointed type
	7/10	Arrangements for compensating for auxiliary
	7710	variables, e.g. length of lead
the liquid displacing a further liquid column or a solid body (for maximum or minimum indication	7/12	• • • Arrangements with respect to the cold junction, e.g. preventing influence of temperature of
		surrounding air
		• • • Circuits for cold-junction compensation [6]
	7/14	Arrangements for modifying the output
	E /40	characteristic, e.g. linearising
· · · · · · · · · · · · · · · · · · ·		using resistive elements
more than a few degrees, e.g. clinical thermometer	7/18	• • the element being a linear resistance, e.g. platinum resistance thermometer (G01K 7/26 takes
· · · · · · · · · · · · · · · · · · ·	5 (00	precedence)
		• • • in a specially-adapted circuit, e.g. bridge circuit
e.g. Beckmann thermometer		• • • • for modifying the output characteristic, e.g. linearising [6]
	7/22	 the element being a non-linear resistance, e.g. thermistor (G01K 7/26 takes precedence)
*	7/24	
		• • • in a specially-adapted circuit, e.g. bridge circuit
having parts which are deformable or displaceable		• • • for modifying the output characteristic, e.g. linearising [6]
		the element being an electrolyte
		• • • in a specially-adapted circuit, e.g. bridge circuit
		using thermal noise of resistances or conductors
-		• using change of resonant frequency of a crystal
		 using capacitative elements
-		 using magnetic elements, e.g. magnets, coils
	7/38	• • the variations of temperature influencing the
		magnetic permeability
		using ionisation of gases
	7/42	Circuits for reducing thermal inertia; Circuits for
the indental being a solid arranged for free expansion or contraction		predicting the stationary value of temperature [6]
	other than those to be measured, e.g. changes in ambient temperature • by means of fluid contained in a hollow body having parts which are deformable or displaceable under the pressure developed by the fluid • by means of compounded strips or plates, e.g. bimetallic strips • Compensating for effects of pressure changes Thermometers giving results other than momentary value of temperature (G01K 7/42 takes precedence) [6] • giving mean values; giving integrated values • in respect of time • in respect of space • giving differences of values; giving differentiated values • in respect of time, e.g. reacting only to a quick change of temperature • based upon expansion or contraction of materials • in respect of space Measuring temperature based on the expansion or contraction of a material (G01K 9/00 takes precedence; giving other than momentary value of temperature G01K 3/00) • the material being a liquid (G01K 5/32 takes precedence) • Details • Arrangements for driving back the liquid column or a solid body (for maximum or minimum indication G01K 5/20) • with electric contacts • with electric contacts • with electric contacts • with electric contacts • with provision for expansion indicating over not more than a few degrees, e.g. clinical thermometer • with provision for measuring the difference between two temperatures • with provision for masuring zero point of scale, e.g. Beckmann thermometer • the material being a gas (G01K 5/32 takes precedence) • the gas displacing a liquid column • the material being a fluid contained in a hollow body having parts which are deformable or displaceable under the pressure developed by the material (under pressure developed by the material (under pressure developed by evaporation G01K 1/04) • the body being a bellows • the body being a capsule (G01K 5/36, G01K 5/42 take precedence) • the body being a capsule (G01K 5/36, G01K 5/42 take precedence) • the body being a capsule (G01K 5/36, G01K 5/42 take precedence)	ambient temperature • by means of fluid contained in a hollow body having parts which are deformable or displaceable under the pressure developed by the fluid • by means of compounded strips or plates, e.g. bimetallic strips • Compensating for effects of pressure changes Thermometers giving results other than momentary value of temperature (GOIK 7/42 takes precedence) [6] • giving mean values; giving integrated values • in respect of time • in respect of space • giving differences of values; giving differentiated values • in respect of space • in respect of space • in in respect of time, e.g. reacting only to a quick change of temperature • in in respect of space • based upon expansion or contraction of materials • in respect of space • in respect of space • in respect of space • based upon expansion or contraction of materials • in respect of space 7/00 Measuring temperature based on the expansion or contraction of a material (GOIK 9/00 takes precedence; giving other than momentary value of temperature GOIK 3/00) • Details • Arrangements for driving back the liquid column or a ordinate ordina

3/00	weasuring temperature based on movements caused	13/00	iii iiiicai iiioveinent
	by redistribution of weight, e.g. tilting thermometer	13/08	 in rotary movement
	(not giving momentary value of temperature	13/10	 for measuring temperature within piled or stacked
	G01K 3/00)		materials (by special arrangements for conducting
			heat from the object to the sensitive element
11/00	Measuring temperature based on physical or		G01K 1/16)
	chemical changes not covered by group G01K 3/00,	13/12	 combined with sampling devices for measuring
11/00	G01K 5/00, G01K 7/00, or G01K 9/00		temperatures of samples of material
11/02	using evaporation or sublimation, e.g. by observing belief		
11/04	boiling	15/00	Testing or calibrating of thermometers
11/04	 from material contained in a hollow body having parts which are deformable or displaceable under 	17/00	Managering grantity of heat
	the pressure developed by the vapour		Measuring quantity of heat
11/06	using melting, freezing, or softening	17/02	 Calorimeters using transport of an indicating substance, e.g. evaporation calorimeters
11/08	 • of disposable test bodies, e.g. cone 	17/04	Calorimeters using compensation methods
11/00	 using sintering 		
11/10	using sinteringusing change of colour or translucency	17/06	 Measuring quantity of heat conveyed by flowing media, e.g. in heating systems (G01K 17/02,
11/12	(G01K 11/32 takes precedence) [6]		G01K 17/04 take precedence)
11/14	 of inorganic materials 	17/08	 based upon measurement of temperature
11/14	of organic materials of organic materials	17,00	difference
11/18	of materials which change translucency	17/10	 • between an inlet and an outlet point, combined
11/10	using thermoluminescent materials (G01K 11/32)		with measurement of rate of flow of the
11/20	takes precedence) [6]		medium
11/22	 using measurement of acoustic effects 	17/12	• • • • Indicating product of flow and temperature
11/24	of the velocity of propagation of sound		difference directly
11/24	of resonant frequencies	17/14	 • • • using mechanical means for both
11/28	 using measurements of density 		measurements
11/20	 using measurement of the effect of a material on X- 	17/16	 • • • using electrical means for both
11/30	radiation, gamma radiation or particle radiation [5]		measurements
11/32	 using changes in transmission, scattering or 	17/18	• • • • using electrical means for one
11/52	fluorescence in optical fibres [6]		measurement and mechanical means for
	naorescence in optical notes [6]	15/00	the other
13/00	Adaptations of thermometers for specific purposes	17/20	across a radiating surface, combined with ascertainment of the heat-transmission
13/02	 for measuring temperature of moving fluids or 		coefficient
	granular materials capable of flow		Cocincient
13/04	 for measuring temperature of moving solid bodies 	19/00	Testing or calibrating calorimeters
			-
G01L	MEASURING FORCE, STRESS, TORQUE, WORK,	, MECHANI	ICAL POWER, MECHANICAL EFFICIENCY, OR
	FLUID PRESSURE (weighing G01G) [4]		•

13/06

in linear movement

Note(s)

9/00

Measuring temperature based on movements caused

Attention is drawn to the Notes following the title of class G01.

Subclass index

MEASURING FORCE, STRESS, TORQUE, WORK, MECHANICAL POWER, MECHANICAL **EFFICIENCY** MEASURING FLUID PRESSURE SPECIAL ADAPTATIONS OF MEASURING APPARATUS INDICATORS OF FAST CHANGES, PARTICULARLY IN THE OPERATION OF FLUID-PRESSURE

1/00 Measuring force or stress, in general (measuring force due to impact G01L 5/00) [4]

1/02 • by hydraulic or pneumatic means 1/04 · by measuring elastic deformation of gauges, e.g. of

by measuring the permanent deformation of gauges, 1/06 e.g. of compressed bodies

1/08	•	by the use	of coun	terbalar	ncing forces
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- by measuring variations of frequency of stressed vibrating elements, e.g. of stressed strings (using resistance strain gauges G01L 1/22)
- by measuring variations in the magnetic properties of materials resulting from the application of stress
- by measuring variations in capacitance or inductance of electrical elements, e.g. by measuring variations of frequency of electrical oscillators
- 1/16 using properties of piezo-electric devices
- using properties of piezo-resistive materials, i.e. materials of which the ohmic resistance varies according to changes in magnitude or direction of force applied to the material
- by measuring variations in ohmic resistance of solid materials or of electrically-conductive fluids (of piezo-resistive materials G01L 1/18); by making use of electrokinetic cells, i.e. liquid-containing cells wherein an electrical potential is produced or varied upon the application of stress
- 1/22 using resistance strain gauges
- by measuring variations of optical properties of material when it is stressed, e.g. by photoelastic stress analysis
- using wave or particle radiation, e.g. X-rays, neutrons (G01L 1/24 takes precedence) [4]
- Auxiliary measures taken, or devices used, in connection with the measurement of force, e.g. for preventing influence of transverse components of force, for preventing overload

3/00 Measuring torque, work, mechanical power, or mechanical efficiency, in general

- 3/02 Rotary-transmission dynamometers
- wherein the torque-transmitting element comprises a torsionally-flexible shaft
- 3/06 • involving mechanical means for indicating
- 3/08 • involving optical means for indicating
- 3/10 • involving electric or magnetic means for indicating
- 3/12 • involving photoelectric means
- 3/14 • wherein the torque-transmitting element is other than a torsionally-flexible shaft
- 3/16 Rotary-absorption dynamometers, e.g. of brake type
- 3/18 • mechanically actuated
- 3/20 • fluid actuated
- 3/22 electrically or magnetically actuated
- Devices for determining the value of power, e.g. by measuring and simultaneously multiplying the values of torque and revolutions per unit of time, by multiplying the values of tractive or propulsive force and velocity
- Devices for measuring efficiency, i.e. the ratio of power output to power input

5/00 Apparatus for, or methods of, measuring force, e.g. due to impact, work, mechanical power, or torque, adapted for special purposes

- for measuring release force of ski safety bindings
- for measuring tension in ropes, cables, wires, threads, belts, bands, or like flexible members
- 5/06 • using mechanical means
- 5/08 • using fluid means
- 5/10 using electric means
- for measuring axial thrust in a rotary shaft, e.g. of propulsion plants

- for measuring the tractive or propulsive power of vehicles
- for measuring the force of explosions; for measuring the energy of projectiles
- 5/16 for measuring several components of force
- 5/18 for measuring ratios of force
- 5/20 for measuring wheel side-thrust
- for measuring the force applied to control members,
 e.g. control members of vehicles, triggers
- 5/24 for determining value of torque or twisting moment for tightening a nut or other member which is similarly stressed
- for determining the characteristic of torque in relation to revolutions per unit of time
- 5/28 for testing brakes

Measuring fluid pressure

- 7/00 Measuring the steady or quasi-steady pressure of a fluid or a fluent solid material by mechanical or fluid pressure-sensitive elements (transmitting or indicating the displacement of mechanical pressure-sensitive elements by electric or magnetic means G01L 9/00; measuring differences of two or more pressure values G01L 13/00; measuring two or more pressure values simultaneously G01L 15/00)
- 7/02 in the form of elastically-deformable gauges
- 7/04 in the form of flexible, deformable tubes, e.g. Bourdon gauges
- 7/06 • of the bellows type
- 7/08 • of the flexible-diaphragm type
- 7/10 • of the capsule type
- 7/12 • with exhausted chamber; Aneroid barometers
- 7/14 • with zero-setting means
- 7/16 in the form of pistons
- using liquid as the pressure-sensitive medium, e.g. liquid-column gauges
- involving a closed chamber above the liquid level, the chamber being exhausted or housing lowpressure gas; Liquid barometers
- 7/22 involving floats, e.g. floating bells
- 7/24 involving balances in the form of rings partly filled with liquid
- 9/00 Measuring steady or quasi-steady pressure of a fluid or a fluent solid material by electric or magnetic pressure-sensitive elements; Transmitting or indicating the displacement of mechanical pressure-sensitive elements, used to measure the steady or quasi-steady pressure of a fluid or fluent solid material, by electric or magnetic means (measuring differences of two or more pressure values G01L 13/00; measuring two or more pressure values simultaneously G01L 15/00)
- 9/02 by making use of variations in ohmic resistance, e.g. of potentiometers
- 9/04 • of resistance strain gauges
- 9/06 • of piezo-resistive devices
- 9/08 by making use of piezo-electric devices
- 9/10 by making use of variations in inductance
- 9/12 by making use of variations in capacitance
- 9/14 involving the displacement of magnets, e.g. electromagnets
- 9/16 by making use of variations in the magnetic properties of material resulting from the application of stress

5/03

9/18	 by making use of electrokinetic cells, i.e. liquid- 	21/18	using a pendulum
	containing cells wherein an electric potential is	21/20	 using members oscillating about a vertical axis
	produced or varied upon the application of stress	21/22	 using resonance effects of a vibrating body;
	• • •	21/22	Vacuum gauges of the Klumb type
11/00	Measuring steady or quasi-steady pressure of a fluid	24 /24	
	or a fluent solid material by means not provided for	21/24	• using rotating members; Vacuum gauges of the
	in group G01L 7/00 or G01L 9/00		Langmuir type
11/02		21/26	 by making use of radiometer action, i.e. of the
	by optical means [6]		pressure caused by the momentum of molecules
11/04	 by acoustic means [6] 		passing from a hotter to a cooler member; Vacuum
11/06	 Ultrasonic means [6] 		gauges of the Knudsen type
		21/28	 using torsional rotary measuring members
13/00	Devices or apparatus for measuring differences of		
	two or more fluid pressure values	21/30	 by making use of ionisation effects
13/02	 using elastically-deformable members or pistons as 	21/32	 using electric discharge tubes with thermionic
,	sensing elements		cathodes
12/04		21/34	 using electric discharge tubes with cold cathodes
13/04	using floats or liquids as sensing elements	21/36	using radioactive substances
13/06	using electric or magnetic pressure-sensitive elements		using radioactive substances
15/00	Devices or apparatus for measuring two or more		
	fluid pressure values simultaneously		
	· · · · · · · · · · · · · · · · · · ·	23/00	Devices or apparatus for measuring or indicating or
17/00	Devices or apparatus for measuring tyre pressure or		recording rapid changes, such as oscillations, in the
	the pressure in other inflated bodies		pressure of steam, gas, or liquid; Indicators for
	F		determining work or energy of steam, internal-
19/00	Details of, or accessories for, apparatus for		combustion, or other fluid-pressure engines from the
	measuring steady or quasi-steady pressure of a fluent		condition of the working fluid
	medium insofar as such details or accessories are not	23/02	 mechanically indicating or recording and involving
	special to particular types of pressure gauges	25/02	loaded or return springs
19/02	Arrangements for preventing, or for compensating	22/04	
19/02		23/04	involving means subjected to known counteracting
	for, effects of inclination or acceleration of the		pressure
	measuring device; Zero-setting means (for aneroid	23/06	 Indicating or recording by optical means
	barometers G01L 7/14)	23/08	 operated electrically
19/04	 Means for compensating for effects of changes of 	23/10	 by pressure-sensitive members of the piezo-
	temperature		electric type
19/06	 Means for preventing overload or deleterious 	23/12	by changing capacitance or inductance
	influence of the measured medium on the measuring	23/14	 by electromagnetic elements
	device or <u>vice versa</u>		•
19/08	 Means for indicating or recording, e.g. for remote 	23/16	 by photoelectric means
10,00	indication	23/18	 by resistance strain gauges
10/10		23/20	 combined with planimeters or integrators
19/10	• • mechanical	23/22	 for detecting or indicating knocks in internal-
19/12	 Alarms or signals 	20,22	combustion engines; Units comprising pressure-
19/14	 Housings 		sensitive members combined with ignitors for firing
19/16	Dials; Mounting of dials		
		22.42.4	internal-combustion engines
21/00	Vacuum gauges	23/24	for measuring pressure in inlet or exhaust ducts of
21/02	 having a compression chamber in which gas, whose 		internal-combustion engines
21702	pressure is to be measured, is compressed	23/26	 Details or accessories
21/04	 • wherein the chamber is closed by liquid; Vacuum 	23/28	 Cooling means
21/04		23/30	 Means for indicating consecutively positions of
	gauges of the McLeod type		pistons or cranks of internal-combustion engines
21/06	 actuated by rotating or inverting the measuring 		in combination with pressure indicators
	device	23/32	 Apparatus specially adapted for recording pressure
21/08	 by measuring variations in the transmission of 	23/32	
	acoustic waves through the medium, the pressure of		changes measured by indicators
	which is to be measured	DE (00	m d la la dia dia dia dia dia dia dia dia dia di
21/10	 by measuring variations in the heat conductivity of 	25/00	Testing or calibrating of apparatus for measuring
41/10	the medium, the pressure of which is to be measured		force, torque, work, mechanical power, or
04 /40			mechanical efficiency [2]
21/12	measuring changes in electric resistance of	D= /00	m
	measuring members, e.g. of filaments; Vacuum	27/00	Testing or calibrating of apparatus for measuring
	gauges of the Pirani type		fluid pressure [2]
21/14	 using thermocouples 	27/02	 of indicators
21/16	 by measuring variation of frictional resistance of 		
	gases		

G01M TESTING STATIC OR DYNAMIC BALANCE OF MACHINES OR STRUCTURES; TESTING OF STRUCTURES OR APPARATUS, NOT OTHERWISE PROVIDED FOR

Note(s)

Attention is drawn to the Notes following the title of class G01.

	lass	

TESTING STATIC OR DYNAMIC BALANCE OF MACHINES OR STRUCTURES	
VIBRATION- OR SHOCK-TESTING	
Aerodynamic; hydrodynamic testing	
Optical testing	
Mechanical or engine testing	
1/00 Testing static or dynamic balance of machines or structures 3/12 • by observing elastic covers or coatings, soapy water 1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/30, G01M 1/38 take precedence) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body to be tested 1/18 • and running the body down from a speed greater than normal forces due to unbalance 1/20 • and applying external forces compensating forces due to unbalance 1/20 • and applying external forces compensating forces due to unbalance 1/20 • for pipes, cables, or tubes; for pipe join seals; for valves (appears to pipe join seals; for valves (by flow determining unbalance) 1/20 • and applying external forces compensating forces due to unbalance	
structures 1/02 • Details of balancing machines or devices 1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body down from a speed greater than normal 1/20 • and applying external forces compensating for eceiving the body to be tested on the side of the compensating for cest due to unbalance 3/18 • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/16 • • static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 3/18 • • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/18 • • • for pipes, cables, or tubes; for pipe journs in the pipe journs	
structures 1/02 • Details of balancing machines or devices 1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body down from a speed greater than normal 1/20 • and applying external forces compensating for eceiving the body to be tested on the side of the compensating for cest due to unbalance 3/18 • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/16 • • static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 3/18 • • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/18 • • • for pipes, cables, or tubes; for pipe journs in the pipe journs	
structures 1/02 • Details of balancing machines or devices 1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body down from a speed greater than normal 1/20 • and applying external forces compensating for eceiving the body to be tested on the side of the compensating for cest due to unbalance 3/18 • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/16 • • static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 3/18 • • • by observing elastic covers or coatings, soapy water 3/14 • • for pipes, cables, or tubes; for pipe journs seals; for valves 3/18 • • • for pipes, cables, or tubes; for pipe journs in the pipe journs	
1/02 • Details of balancing machines or devices 1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance G01M 3/16 • using electric detection means (G01M 3/24, G01M 3/26 take precedence) 3/18 • • for pipes, cables, or tubes; for pipe juseals; for valves 3/18 • • for pipes, cables, or tubes; for pipe juseals; for valves 3/20 • using infrasonic, sonic, or ultrasonic via seals; for valves 3/22 • • for pipes, cables, or tubes; for pipe juseals; for valves 3/24 • using infrasonic, sonic, or ultrasonic via pressure-responsive devices, by flow detection means (G01M 3/18, S01M 3/26, S01M 3/26	
1/04 • Adaptation of bearing support assemblies for receiving the body to be tested 1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body to be tested 1/18 • and running the body down from a speed greater than normal 1/20 • and applying external forces compensating forces due to unbalance 1/20 • and applying external forces compensating forces due to unbalance 1/20 • and applying external forces compensating forces due to unbalance 1/20 • for pipes, cables, or tubes; for pipe join seals; for valves 1/20 • for pipes, cables, or tubes; for pipe join seals; for valves 1/20 • for pipes, cables, or tubes; for pipe join seals; for valves 1/20 • and applying external forces compensating forces due to unbalance	s, e.g.
1/06 • Adaptation of drive assemblies for receiving the body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body to be tested 1/18 • • and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • and applying external forces compensating forces due to unbalance 3/16 • • using electric detection means (G01M 3/24, G01M 3/22, G01M 3/24, G01M 3/26 take precedence) 3/18 • • • for pipes, cables, or tubes; for pipe join seals; for valves 3/20 • • using special tracer materials, e.g. dye, fluorescent material, radioactive materials, e.g. dye, fluorescent material, radioactive materials, e.g. dye, fluorescent materials, e.g. dye,	joints or
body to be tested 1/08 • Instruments for indicating directly the magnitude and phase of the unbalance 1/10 • Determining the moment of inertia 1/12 • Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body to be tested 1/18 • • and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • and applying external forces compensating forces due to unbalance 1/20 • • • for pipes, cables, or tubes; for pipe join seals; for valves 1/20 • • • for pipes, cables, or tubes; for pipe join seals; for valves [2]	3/06
and phase of the unbalance 1/10 Determining the moment of inertia 1/12 Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • by oscillating or rotating the body to be tested 1/18 • • and running the body down from a speed greater than normal 1/20 • • and applying external forces compensating forces due to unbalance 3/18 • • • for pipes, cables, or tubes; for pipe join seals; for valves 3/20 • • using special tracer materials, e.g. dye, fluorescent material, radioactive materials, e.g. dye, fluorescent	3/00,
 1/10 Determining the moment of inertia 1/12 Static balancing; Determining position of centre of gravity (by determining unbalance G01M 1/14) 1/14 Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/18 Image: A seals; for valves of luorescent materials, e.g. dye, fluorescent material, radioactive materials, radioacti	ioints or
gravity (by determining unbalance G01M 1/14) 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • • by oscillating or rotating the body to be tested 1/18 • • • and running the body down from a speed greater than normal 1/20 • • • and applying external forces compensating forces due to unbalance 1/20 • • • and applying external forces compensating forces due to unbalance 1/20 • • • and applying external forces compensating forces due to unbalance 1/20 • • • and applying external forces compensating forces due to unbalance 1/20 • • • • for pipes, cables, or tubes; for pipe join seals; for valves [2]	,
 1/14 • Determining unbalance (G01M 1/30, G01M 1/38 take precedence) 1/16 • • by oscillating or rotating the body to be tested 1/18 • • • and running the body down from a speed greater than normal 1/20 • • • and applying external forces compensating forces due to unbalance 3/22 • • • for pipes, cables, or tubes; for pipe join seals; for valves 3/24 • • using infrasonic, sonic, or ultrasonic viiing for a valves 3/26 • by measuring rate of loss or gain of fluid, pressure-responsive devices, by flow detections and applying external forces compensating seals; for valves [2] 	
1/16 • • by oscillating or rotating the body to be tested 1/18 • • • and running the body down from a speed greater than normal 1/20 • • • and applying external forces compensating forces due to unbalance 3/24 • • using infrasonic, sonic, or ultrasonic vi 3/26 • by measuring rate of loss or gain of fluid, pressure-responsive devices, by flow detection seals; for valves [2]	joints or
1/18 • • • and running the body down from a speed greater than normal 1/20 • • • and applying external forces compensating forces due to unbalance 3/26 • • by measuring rate of loss or gain of fluid, pressure-responsive devices, by flow detection for pipes, cables, or tubes; for pipe join seals; for valves [2]	ibrations
1/20 • • • and applying external forces compensating forces due to unbalance 3/28 • • • for pipes, cables, or tubes; for pipe join seals; for valves [2]	
2/20	nts or
1/22 • • • and converting vibrations due to unbalance into electric variables 3/30 • • • using progressive displacement of or by another [2]	one fluid
1/24 • • • Performing balancing on elastic shafts, e.g. for 3/32 • • • for containers, e.g. radiators [2]	
crankshafts 3/34 • • • by testing the possibility of maintain vacuum in containers, e.g. in can-tes	-
drilling machines [2]	
1/28 • • • with special adaptations for determining unbalance of the body <u>in situ</u> , e.g. of vehicle	
wheels 3/38 • by using light (G01M 3/02 takes precedence)	
 Compensating unbalance (G01M 1/38 takes precedence) by using electric means, e.g. by observing electric means, e.g.	ectric
• • by adding material to the body to be tested, e.g. by correcting-weights 5/00 Investigating the elasticity of structures, e.g.	
1/34 • by removing material from the body to be tested, e.g. from the tread of tyres deflection of bridges or aircraft wings (G01M 9/00 takes precedence)	
1/36 • • by adjusting position of masses built-in the body to be tested	g of
*** to be tested *** structures (G01M 9/00 takes precedence) 1/38	
and correcting unbalance 7/02 • Monodirectional test stands [5]	
3/00 Investigating fluid tightness of structures 7/06 • Multidirectional test stands [5]	
3/02 • by using fluid or vacuum 7/08 • Shock-testing [5]	
3/04 • • by detecting the presence of fluid at the leakage	
point suppole funders	ı wind
3/06 • • • by observing bubbles in a liquid pool 9/02 • Wind tunnels [5]	
3/08 • • • • for pipes, cables, or tubes; for pipe joints or seals; for valves 9/04 • Details [5]	

9/06	 Measuring arrangements specially adapted for aerodynamic testing [5] 	15/06	 by monitoring positions of pistons or cranks [2006.01]
9/08	Aerodynamic models [5]	15/08	• • by monitoring pressure in cylinders [2006.01]
10/00	Hydrodynamic testing; Arrangements in or on shiptesting tanks or water tunnels	15/09 15/10	 by monitoring pressure in fluid ducts, e.g. in lubrication or cooling parts [2006.01] by monitoring exhaust gases [2006.01]
11/00	Testing of optical apparatus; Testing structures by optical methods not otherwise provided for	15/11 15/12	by detecting misfire [2006.01]by monitoring vibrations [2006.01]
11/02	 Testing of optical properties 	15/14	Testing of gas-turbine plants or jet-propulsion
11/04	 Optical benches 		plants [2006.01]
11/06	 Testing of alignment of vehicle head-light devices 	17/00	Testing of vehicles (G01M 15/00 takes precedence;
11/08	Testing of mechanical properties		testing fluid tightness G01M 3/00; testing elastic
13/00	Testing of machine parts		properties of bodies or chassis, e.g. torsion-testing, G01M 5/00; testing alignment of vehicle head-lighting
13/02	 Testing of gearing or of transmission mechanisms 		devices G01M 11/06)
13/04	Testing of bearings	17/007	• of wheeled or endless-tracked vehicles (G01M 17/08 takes precedence) [6]
15/00	Testing of engines [4]	17/013	• • of wheels [6]
15/02	 Details or accessories of testing apparatus [2006.01] 	17/02	• • of tyres [6]
15/04	 Testing of internal-combustion engines, e.g. 	17/03	• • of endless-tracks [6]
	diagnostic testing of piston engines [2006.01]	17/04	 of suspension or of damping [6]
15/05	by combined monitoring of two or more different	17/06	 of steering behaviour; of rolling behaviour [6]
	engine parameters [2006.01]	17/08	• of railway vehicles [6]
	Note(s) [2006.01]	17/10	• • of suspensions, axles or wheels [6]
	Group G01M 15/05 takes precedence over groups G01M 15/06-G01M 15/12.	99/00	Subject matter not provided for in other groups of this subclass [2011.01]

G01N INVESTIGATING OR ANALYSING MATERIALS BY DETERMINING THEIR CHEMICAL OR PHYSICAL PROPERTIES (measuring or testing processes other than immunoassay, involving enzymes or micro-organisms C12M, C12Q)

Note(s)

- In this subclass, the following terms are used with the meanings indicated:
 - "investigating" means testing or determining;
 - "materials" includes solid, liquid or gaseous media, e.g. the atmosphere.
- Attention is drawn to the Notes following the title of class G01. 2.
- Investigating the properties of materials, specially adapted for use in processes covered by subclass B23K, is classified in group B23K 31/12.

Subclass index

SAMPLING, PREPARING	1/00
INVESTIGATING OR ANALYSING CHARACTERISED BY THE PROPERTY INVESTIGATED Mechanical strength; density; flow	2/00 0/00 11/00
Surface or boundary effects; characteristics of particles, permeability; friction, adhesive force	
Resistance to atmospheric agents	
INVESTIGATING OR ANALYSING CHARACTERISED BY THE METHOD USED	
Weighing; measuring pressure or volume of gas; mechanical	
Optical; by microwaves; by radiation	21/00, 22/00, 23/00
Magnetic resonance or other spin effects	24/00
Thermal; electric, electrochemical, magnetic; sonic	25/00, 27/00, 29/00
By separation into components; by the use of the chemical methods	30/00, 31/00
OTHER INVESTIGATING OR ANALYSING CHARACTERISED BY THE MATERIAL	
INVESTIGATED	33/00
Immunoassay	33/53
AUTOMATIC ANALYSIS	
DETAILS NOT COVERED BY THE PRECEDING GROUPS	37/00

11111111	1110dSSdy		
AUTOM	ATIC ANALYSIS	35/00	
	S NOT COVERED BY THE PRECEDING GROUPS		
	· ·		
1/00	Sampling; Preparing specimens for investigation	1/08 • • • involving an extracting tool,	e g core hit
1,00	(handling materials for automatic analysis G01N 35/00)	1/10 • • in the liquid or fluent state	c.g. core or
1 /00	,	1	
1/02	 Devices for withdrawing samples 	1/12 • • • Dippers; Dredgers [5]	
1/04	 in the solid state, e.g. by cutting 	1/14 • • • Suction devices, e.g. pumps:	Ejector devices
1/06	 providing a thin slice, e.g. microtome 		-

1/16	• • with provision for intake at several levels	3/317	• • generated by electromagnetic means [7]
4 /40	(G01N 1/12, G01N 1/14 take precedence)	3/32	 by applying repeated or pulsating forces
1/18	• • • with provision for splitting samples into portions (G01N 1/12, G01N 1/14 take	3/34	 generated by mechanical means, e.g. hammer blows
	precedence; fraction-collection apparatus for	3/36	 generated by pneumatic or hydraulic means
1 /20	chromatography B01D 15/08)	3/38	 generated by electromagnetic means
1/20	• • for flowing or falling materials (G01N 1/12, G01N 1/14 take precedence)	3/40	 Investigating hardness or rebound hardness
1/22	• • in the gaseous state	3/42	• • by performing impressions under a steady load by
1/24	Suction devices		indentors, e.g. sphere, pyramid (G01N 3/54 takes
1/26	• • with provision for intake from several spaces	D / 4.4	precedence)
1/28	 Preparing specimens for investigation (mounting 	3/44	• • • the indentors being put under a minor load and a subsequent major load, i.e. Rockwell system
	specimens on microscopic slides G02B 21/34; means for supporting the objects or the materials to be	3/46	 the indentors performing a scratching movement
4 /00	analysed in electron microscopes H01J 37/20)	3/48	 by performing impressions under impulsive load
1/30	Staining; Impregnating		by indentors, e.g. falling ball (G01N 3/54 takes
1/31	• • Apparatus therefor [6]		precedence)
1/32	Polishing; Etching	3/50	• • by measuring rolling friction, e.g. by rocking
1/34	Purifying; Cleaning	D /=0	pendulum (G01N 3/54 takes precedence)
1/36	• • Embedding or analogous mounting of samples [6]	3/52	• • by measuring extent of rebound of a striking body
1/38	• • Diluting, dispersing or mixing samples [6]	2/54	(G01N 3/54 takes precedence)
1/40	 Concentrating samples [6] 	3/54	Performing tests at high or low temperatures
1/42	• Low-temperature sample treatment, e.g.	3/56	Investigating resistance to wear or abrasion
	cryofixation [6]	3/58	Investigating machinability by cutting tools; Investigating the cutting ability of tools.
1/44	• • Sample treatment involving radiation, e.g. heat [6]	3/60	Investigating the cutting ability of tools
3/00	Investigating strength properties of solid materials	3/60	 Investigating resistance of materials, e.g. refractory materials, to rapid heat changes
3/00	by application of mechanical stress	3/62	Manufacturing, calibrating, or repairing devices used
	Note(s)	3/02	in investigations covered by the preceding subgroups
	This group <u>covers</u> the stressing of materials not only	E /00	Analysing materials by vaighing a granishing small
	below but also beyond the elastic limit, e.g. until	5/00	Analysing materials by weighing, e.g. weighing small particles separated from a gas or liquid (G01N 9/00
	breaking occurs.		takes precedence)
3/02	• Details	5/02	 by absorbing or adsorbing components of a material
3/04	• • Chucks	57 02	and determining change of weight of the adsorbent,
3/06	Special adaptations of indicating or recording		e.g. determining moisture content
	means	5/04	 by removing a component, e.g. by evaporation, and
3/08	 by applying steady tensile or compressive forces 		weighing the remainder
	(G01N 3/28 takes precedence)	7/00	And the new table was trade and a second
3/10	 generated by pneumatic or hydraulic pressure 	7/00	Analysing materials by measuring the pressure or
	(G01N 3/18 takes precedence)	7/02	volume of a gas or vapourby absorption, adsorption, or combustion of
3/12	• • • Pressure-testing	7702	components and measurement of the change in
3/14	 generated by dead weight, e.g. pendulum; 		pressure or volume of the remainder
	generated by spring tension (G01N 3/18 takes	7/04	 by absorption or adsorption alone
	precedence)	7/06	 by combustion alone
3/16	• applied through gearing (G01N 3/18 takes	7/08	 by combustion followed by absorption or
2/10	precedence)	.,	adsorption of the combustion products
3/18	Performing tests at high or low temperatures A part of the self-in feature (COLN 2/26) The s	7/10	 by allowing diffusion of components through a
3/20	 by applying steady bending forces (G01N 3/26, G01N 3/28 take precedence) 		porous wall and measuring a pressure or volume
3/22	 by applying steady torsional forces (G01N 3/26, 		difference
3/22	G01N 3/28 take precedence)	7/12	 the diffusion being followed by combustion or
3/24	 by applying steady shearing forces (G01N 3/26, 		catalytic oxidation
3/24	G01N 3/28 take precedence)	7/14	• by allowing the material to emit a gas or vapour, e.g.
3/26	Investigating twisting or coiling properties		water vapour, and measuring a pressure or volume
3/28	Investigating ductility, e.g. suitability of sheet metal		difference
5/20	for deep-drawing or spinning	7/16	by heating the material
3/30		7/18	by allowing the material to react
	• DV applying a single impulsive force (investigating	7/20	• • the reaction being formentation
	 by applying a single impulsive force (investigating hardness by performing impressions under impulsive 	7/20	• • • the reaction being fermentation
		7/20 7/22	• • • of dough
3/303	hardness by performing impressions under impulsive	7/22	• • • of dough
	 hardness by performing impressions under impulsive load G01N 3/48) generated only by free-falling weight [7] generated by a compressed or tensile-stressed 		• • • of dough Investigating density or specific gravity of materials;
3/303	 hardness by performing impressions under impulsive load G01N 3/48) generated only by free-falling weight [7] generated by a compressed or tensile-stressed spring; generated by pneumatic or hydraulic 	7/22	• • • • of dough Investigating density or specific gravity of materials; Analysing materials by determining density or
3/303	 hardness by performing impressions under impulsive load G01N 3/48) generated only by free-falling weight [7] generated by a compressed or tensile-stressed 	7/22	• • • of dough Investigating density or specific gravity of materials;

3/31 • • generated by a rotating fly-wheel [7] 3/313 • • generated by explosives [7]

9/04

• • of fluids

9/06	• • • with continuous circulation through a pivotally- supported member	15/08	• Investigating permeability, pore volume, or surface area of porous materials
9/08	by measuring buoyant force of solid materials by	15/10	Investigating individual particles [4]
	weighing both in air and in a liquid	15/12	Coulter-counters [4]
9/10	 by observing bodies wholly or partially immersed in 	15/14	Electro-optical investigation [4]
9/12	fluid materials • by observing the depth of immersion of the bodies,	17/00	Investigating resistance of materials to the weather,
3/12	e.g. hydrometers	17700	to corrosion, or to light
9/14	 the body being built into a container 	17/02	 Electrochemical measuring systems for weathering,
9/16	• • the body being pivoted		corrosion or corrosion-protection measurement
9/18	• • • Special adaptations for indicating, recording, or		(G01N 17/04 takes precedence) [5]
	control	17/04	 Corrosion probes [5]
9/20	 by balancing the weight of the bodies 	10/00	Investigating materials by machanical methods
9/22	 • with continuous circulation of the fluid 	19/00	Investigating materials by mechanical methods (G01N 3/00-G01N 17/00 take precedence)
9/24	 by observing the transmission of wave or particle 	19/02	Measuring coefficient of friction between materials
	radiation through the material	19/02	Measuring adhesive force between materials, e.g. of
9/26	 by measuring pressure differences 	13/04	sealing tape, of coating
9/28	 by measuring the blowing pressure of gas bubbles 	19/06	 Investigating by removing material, e.g. spark-testing
	escaping from nozzles at different depths in a	19/08	Detecting presence of flaws or irregularities
	liquid	19/10	Measuring moisture content, e.g. by measuring
9/30	 by using centrifugal effects 	13/10	change in length of hygroscopic filament;
9/32	 by using flow properties of fluids, e.g. flow through tubes or apertures 		Hygrometers
9/34	by using elements moving through the fluid, e.g. vane	21/00	Investigating or analysing materials by the use of optical means, i.e. using infra-red, visible or ultra-
9/36	 Analysing materials by measuring the density or 		violet light (G01N 3/00-G01N 19/00 take precedence)
	specific gravity, e.g. determining quantity of moisture		- '
	(methods of measurement G01N 9/02-G01N 9/32)		Note(s)
			This group <u>does not cover</u> the investigation of spectral
11/00	Investigating flow properties of materials, e.g.		properties of light <u>per se</u> , or measurements of the
	viscosity, plasticity; Analysing materials by determining flow properties		properties of materials where spectral properties of light
11/02	by measuring flow of the material		are sensed and primary emphasis is placed on creating,
	•		detecting or analysing the spectrum providing that the properties of the materials to be investigated are of
11/04	• through a restricted passage, e.g. tube, aperture		minor importance (see also Note (4) after the title of
11/06	• • • by timing the outflow of a known quantity		class G01). Those subjects are covered by group
11/08	by measuring pressure required to produce a known flow		G01J 3/00.
11/10	by moving a body within the material	21/01	• Arrangements or apparatus for facilitating the optical
11/12	 by measuring rising or falling speed of the body; 		investigation [3]
11/1 =	by measuring penetration of wedged gauges	21/03	 Cuvette constructions [3]
	(G01N 11/16 takes precedence)	21/05	 • Flow-through cuvettes (G01N 21/09 takes
11/14	• • by using rotary bodies, e.g. vane (G01N 11/16		precedence) [3]
	takes precedence)	21/07	• • Centrifugal type cuvettes (G01N 21/09 takes
11/16	 by measuring damping effect upon oscillatory 		precedence) [3]
	body	21/09	• • • adapted to resist hostile environments or
12/00	To add and one of an all and a officers and	24.44	corrosive or abrasive materials [3]
13/00	Investigating surface or boundary effects, e.g. wetting power; Investigating diffusion effects;	21/11	• • Filling or emptying of cuvettes [3]
	Analysing materials by determining surface,	21/13	Moving of cuvettes or solid samples to or from the
	boundary, or diffusion effects (scanning-probe	04./45	investigating station [3]
	techniques or apparatus G01Q) [1, 7]	21/15	Preventing contamination of the components of
13/02	Investigating surface tension of liquids		the optical system or obstruction of the light path [3]
13/04	Investigating osmotic effects	21/17	Systems in which incident light is modified in
		21/1/	accordance with the properties of the material
15/00	Investigating characteristics of particles;		investigated (where the material investigated is
	Investigating permeability, pore-volume or surface-		optically excited causing a change in wavelength of
	area of porous materials (identification of micro-		the incident light G01N 21/63) [3]
	organisms C12Q) [4]	21/19	• • Dichroism [3]
15/02	Investigating particle size or size distribution (CO1N 15/04 CO1N 15/10 cd constant)	21/21	 Polarisation-affecting properties (G01N 21/19
	(G01N 15/04, G01N 15/10 take precedence; by		takes precedence) [3]
15/04	measuring osmotic pressure G01N 7/10) [4]	21/23	• • • Bi-refringence [3]
15/04	Investigating sedimentation of particle suspensions	21/25	Colour; Spectral properties, i.e. comparison of
15/05	• • in blood [4]		effect of material on the light at two or more
15/06	• Investigating concentration of particle suspensions		different wavelengths or wavelength bands [3]
	(G01N 15/04, G01N 15/10 take precedence; by weighing G01N 5/00) [3]	21/27	• • using photo-electric detection (G01N 21/31
	"Cigning Gotti 9/00) [9]		takes precedence) [3]

21/29	• • • using visual detection (G01N 21/31 takes precedence) [3]	21/74 • • • using flameless atomising, e.g. graphite furnaces [3]
21/31	Investigating relative effect of material at wavelengths characteristic of specific elements or malegyles, e.g. atomic absorption.	• Systems in which material is subjected to a chemical reaction, the progress or the result of the reaction
	or molecules, e.g. atomic absorption spectrometry [3]	being investigated (systems in which material is burnt in a flame or plasma G01N 21/72, G01N 21/73) [3]
21/33	• • • using ultra-violet light (G01N 21/39 takes	21/76 • Chemiluminescence; Bioluminescence [3]
21/33	precedence) [3]	21/77 • by observing the effect on a chemical indicator [3]
21/35	• • • using infra-red light (G01N 21/39 takes	21/78 • • • producing a change of colour [3]
	precedence) [3, 2014.01]	21/79 • • • Photometric titration [3]
21/3504	• • • • for analysing gases, e.g. multi-gas	21/80 • • • • Indicating pH value [3]
	analysis [2014.01]	21/81 • • • • Indicating humidity [3]
21/3518	3 3 1	21/82 • • • producing a precipitate or turbidity [3]
	techniques; Devices using gas pressure	21/83 • • • Turbidimetric titration [3]
	modulation techniques [2014.01]	• Systems specially adapted for particular
	Note(s) [2014.01]	applications [3]
	This group also <u>covers</u> devices without instrumental	21/85 • • Investigating moving fluids or granular solids [3]
	sources, e.g. radiometric-type devices using ambient	21/86 • • Investigating moving sheets (G01N 21/89 takes
	infra-red light.	precedence) [3]
21/3554	• • • • for determining moisture content [2014.01]	21/87 • • Investigating jewels (G01N 21/88 takes precedence) [3]
21/3559	• • • • • in sheets, e.g. in paper [2014.01]	21/88 • • Investigating the presence of flaws, defects or
21/3563	• • • • for analysing solids; Preparation of	contamination [3]
	samples therefor [2014.01]	21/89 • • in moving material, e.g. paper, textiles
21/3577	• • • • for analysing liquids, e.g. polluted water [2014.01]	(G01N 21/90, G01N 21/91, G01N 21/94 take precedence) [3, 7]
21/3581	• • • • using far infra-red light; using Terahertz	21/892 • • • characterised by the flaw, defect or object
	radiation [2014.01]	feature examined [7] 21/894 • • • • • Pinholes [7]
21/3586	3 1 13	21/896 • • • • • Optical defects in or on transparent
21/250	[THz-TDS] [2014.01]	materials, e.g. distortion, surface flaws [7]
21/359	• • • • using near infra-red light [2014.01]	21/898 • • • • Irregularities in textured or patterned
21/37	• • • • using pneumatic detection [3]	surfaces, e.g. textiles, wood [7]
21/39 21/41	 • • using tunable lasers [3] • Refractivity; Phase-affecting properties, e.g. 	21/90 • • • in a container or its contents (G01N 21/91 takes precedence) [3]
	optical path length (G01N 21/21 takes precedence) [3]	21/91 • • • using penetration of dyes, e.g. fluorescent ink [3]
21/43	• • • by measuring critical angle [3]	21/93 • • • Detection standards; Calibrating [7]
21/45	using interferometric methods; using Schlieren methods [3] Section (COALY 24/25)	21/94 • • • Investigating contamination, e.g. dust (G01N 21/85 takes precedence) [7]
21/47	• • Scattering, i.e. diffuse reflection (G01N 21/25, G01N 21/41 take precedence) [3]	21/95 • • • characterised by the material or shape of the object to be examined (G01N 21/89-
21/49	• • • within a body or fluid [3]	G01N 21/91, G01N 21/94 take precedence) [7]
21/51	• • • inside a container, e.g. in an ampoule	21/952 • • • • Inspecting the exterior surface of cylindrical
04 (50	(G01N 21/53 takes precedence) [3]	bodies or wires (G01N 21/956 takes
21/53	• • • within a flowing fluid, e.g. smoke [3]	precedence) [7]
21/55	• • Specular reflectivity [3, 2014.01]	21/954 • • • Inspecting the inner surface of hollow
21/552	Attenuated total reflection [2014.01] Managina class [2]	bodies, e.g. bores [7]
21/57	• • • Measuring gloss [3]	21/956 • • • Inspecting patterns on the surface of
21/59	• • Transmissivity (G01N 21/25 takes precedence) [3]	objects [7]
21/61	• Non-dispersive gas analysers [3]• Systems in which the material investigated is excited	21/958 • • • • Inspecting transparent materials [7]
21/62	whereby it emits light or causes a change in wavelength of the incident light [3]	22/00 Investigating or analysing materials by the use of microwaves (G01N 3/00-G01N 17/00, G01N 24/00
21/63	 optically excited [3] 	take precedence) [3]
21/64	• • Fluorescence; Phosphorescence [3]	• Investigating the presence of flaws [3]
21/65	• • • Raman scattering [3]	• Investigating moisture content [3]
21/66	• • electrically excited, e.g. electroluminescence [3]	
21/67	• • using electric arcs or discharges [3]	23/00 Investigating or analysing materials by the use of
21/68	• • using high frequency electric fields [3]	wave or particle radiation not covered by group G01N 21/00 or G01N 22/00, e.g. X-rays, neutrons
21/69	• • • specially adapted for fluids [3]	(G01N 3/00-G01N 17/00 take precedence)
21/70	• • mechanically excited, e.g. triboluminescence [3]	23/02 • by transmitting the radiation through the material
21/71	• • thermally excited [3]	23/04 • • and forming a picture
21/72	• • • using flame burners [3]	23/05 • • • using neutrons [3]
21/73	• • • using plasma burners or torches [3]	23/06 • • and measuring the absorption
	· · · · · · · · · · · · · · · · · · ·	25. 20 and mediating the dosorphon

23/08	• • using electric detection means	25/18	• by investigating thermal conductivity (by calorimetry
23/083	• • • the radiation being X-rays (G01N 23/10-		G01N 25/20; by measuring change of resistance of an
	G01N 23/18 take precedence) [5]		electrically-heated body G01N 27/18)
23/087	• • • • using polyenergetic X-rays [5]	25/20	 by investigating the development of heat, i.e.
23/09	• • • the radiation being neutrons [3]		calorimetry, e.g. by measuring specific heat, by measuring thermal conductivity
23/10	• • • the material being confined in a container (G01N 23/09 takes precedence) [3]	25/22	 on combustion or catalytic oxidation, e.g. of
23/12	 • • • the material being a flowing fluid or a 	25/24	components of gas mixtures
	flowing granular solid (G01N 23/09 takes	25/24	• • using combustion tubes, e.g. for micro-analysis
22/14	precedence) [3]	25/26	 using combustion with oxygen under pressure, e.g. in bomb calorimeter
23/14	• • • specially adapted for controlling or monitoring operations or for signalling	25/28	the rise in temperature of the gases resulting from combustion being measured directly
23/16	• • • the material being a moving sheet (G01N 23/09, G01N 23/18 take precedence) [3]	25/30	• • • using electric temperature-responsive elements
23/18	• • • Investigating the presence of flaws or	25/32	• • • • using thermoelectric elements
25, 10	inclusions (G01N 23/09 takes precedence) [3, 5]	25/34	• • • using mechanical temperature-responsive elements, e.g. bimetallic
23/20	 by using diffraction of the radiation, e.g. for 	25/36	• • • for investigating the composition of gas
	investigating crystal structure; by using reflection of		mixtures
	the radiation	25/38	 • • using the melting or combustion of a solid
23/201	by measuring small-angle scattering [2]	25/40	• • • the heat developed being transferred to a
23/202	• • • using neutrons [3]	05/40	flowing fluid
23/203	by measuring back scattering [2]	25/42	• • • continuously
23/204		25/44	• • • the heat developed being transferred to a fixed
23/205	· · · · · · · · · · · · · · · · · · ·	25/46	quantity of fluid • • • for investigating the composition of gas
23/206	takes precedence) [2] • • the radiation being neutrons [3]	23/40	mixtures
	by means of diffractometry using detectors, e.g.	25/48	 on solution, sorption, or a chemical reaction not
	using an analysing crystal or a crystal to be		involving combustion or catalytic oxidation
	analysed in a central position and one or more	25/50	 by investigating flash-point; by investigating
	displaceable detectors in circumferential positions		explosibility
00/00	(G01N 23/201 takes precedence) [2]	25/52	 by determining flash-point of liquids
23/22	by measuring secondary emission [2]	25/54	 by determining explosibility
23/221	• • by activation analysis [2]	25/56	by investigating moisture content
23/222	• using neutrons [3]• by irradiating the sample with X-rays and by	25/58	by measuring changes of properties of the material due to heat gold or expansion.
23/223	measuring X-ray fluorescence [2]	25/60	due to heat, cold, or expansion
23/225		25/62	for determining the wetness of steamby psychrometric means, e.g. wet-and-dry-bulb
	 by measuring photoelectric effect, e.g. Auger 	25/02	thermometers
	electrons [2]	25/64	• • using electric temperature-responsive elements
		25/66	by investigating dew-point
24/00	Investigating or analysing materials by the use of	25/68	• • by varying the temperature of a condensing
	nuclear magnetic resonance, electron paramagnetic resonance or other spin effects [3, 4, 5]		surface
24/08	• by using nuclear magnetic resonance (G01N 24/12	25/70	• • by varying the temperature of the material, e.g.
24/00	takes precedence) [3]		by compression, by expansion
24/10	by using electron paramagnetic resonance	25/72	 Investigating presence of flaws
	(G01N 24/12 takes precedence) [3]	27/00	Investigating or analysing materials by the use of
24/12	 by using double resonance [3] 	27/00	electric, electro-chemical, or magnetic means
24/14	 by using cyclotron resonance [3] 		(G01N 3/00-G01N 25/00 take precedence; measurement
25 /00	Investigation on analysis of materials but the consection		or testing of electric or magnetic variables or of electric
25/00	Investigating or analysing materials by the use of thermal means (G01N 3/00-G01N 23/00 take		or magnetic properties of materials G01R)
	precedence)	27/02	by investigating impedance
25/02	 by investigating changes of state or changes of phase; 	27/04	• • by investigating resistance
	by investigating sintering	27/06	• • of a liquid (involving electrolysis G01N 27/26)
25/04	 of melting point; of freezing point; of softening point 	27/07	 Construction of measuring vessels; Electrodes therefor [2]
25/06	Analysis by measuring change of freezing point	27/08	• • • which is flowing continuously
	 of boiling point 	27/10	• • • • Investigation or analysis specially
25/08			adapted for controlling or monitoring
25/08 25/10	Analysis by measuring change of boiling point		Operations or for signalling
	 • Analysis by measuring change of boiling point • of critical point; of other phase change	27/12	operations or for signalling • • • of a solid body in dependence upon absorption
25/10		27/12	• • • of a solid body in dependence upon absorption of a fluid; of a solid body in dependence upon
25/10 25/12	 of critical point; of other phase change by using distillation, extraction, sublimation,	27/12	 • of a solid body in dependence upon absorption

27/14	•	•	•	of an electrically-heated body in dependence	27/49	•	•	Systems involving the determination of the
				upon change of temperature				current at a single specific value, or small range
27/16	•	•	•	caused by burning or catalytic oxidation of				of values, of applied voltage for producing selective measurement of one or more
27/10				surrounding material to be tested, e.g. of gas				particular ionic species [5]
27/18	•	•	•		27/60		1	by investigating electrostatic variables
				conductivity of a surrounding material to be tested (G01N 27/20 takes precedence)	27/61			• Investigating the presence of flaws [3]
27/20	_				27/61			
27/20				Investigating the presence of flaws	2//62	٠		by investigating the ionisation of gases; by investigating electric discharges, e.g. emission of
27/22				y investigating capacitance				cathode
27/24				Investigating the presence of flaws	27/64			 using wave or particle radiation to ionise a gas,
27/26	•			nvestigating electrochemical variables; by using	27704	-		e.g. in an ionisation chamber
27/27				rolysis or electrophoresis [5]	27/66			and measuring current or voltage
27/27	•	•		association of two or more measuring systems or	27/68			using electric discharge to ionise a gas
				ells, each measuring a different parameter, where ne measurement results may be either used	27/70			 and measuring current or voltage
				dependently, the systems or cells being	27/70			by investigating magnetic variables
				hysically associated, or combined to produce a	27/72			
				alue for a further parameter [5]				of fluids (G01N 24/00 takes precedence)
27/28	•	•		lectrolytic cell components	27/76			• • by investigating susceptibility
27/30				Electrodes, e.g. test electrodes; Half-cells	27/80	•	•	for investigating mechanical hardness, e.g. by
27750				(G01N 27/414 takes precedence) [5]				investigating saturation or remanence of ferromagnetic material
27/31				Half-cells with permeable membranes, e.g.	27/02			•
27751				semi-porous or perm-selective	27/82			for investigating the presence of flaws
				membranes [5]	27/83			• • by investigating stray magnetic fields [3]
27/32	•	•		Calomel electrodes	27/84	•	•	• • by applying magnetic powder or magnetic
27/327				Biochemical electrodes [5]	25.405			ink [3]
27/333				Ion-selective electrodes or membranes (glass)	27/85			• • using magnetographic methods [3]
277000				electrodes G01N 27/36) [5]	27/87			• • using probes [3]
27/34				Dropping-mercury electrodes	27/90			• using eddy currents [3]
27/36				Glass electrodes	27/92	•		by investigating breakdown voltage (G01N 27/60,
27/38				Cleaning of electrodes			(G01N 27/62 take precedence) [3]
27/40				Semi-permeable membranes or partitions	29/00	Tr	nx	restigating or analysing materials by the use of
27/401				Salt-bridge leaks; Liquid junctions [5]	25/00			rasonic, sonic or infrasonic waves; Visualisation of
		-		Sait-bridge leaks, Liquid junctions [5]				
27/403	•	•	C	ells and electrode assemblies [5]		th	he	interior of objects by transmitting ultrasonic or
	•	•	C	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte		th so	he on	interior of objects by transmitting ultrasonic or ic waves through the object ($G01N\ 3/00$ -
27/403	•	•	C	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane	29/02	th so G	he on 30	interior of objects by transmitting ultrasonic or nic waves through the object (G01N 3/00- 1N 27/00 take precedence) [4]
27/403 27/404	•	•	·	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5]	29/02	th so G	he on 30	interior of objects by transmitting ultrasonic or ic waves through the object ($G01N\ 3/00$ -
27/403 27/404 27/406	•	•	C .	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5]	29/02 29/024	th so G	he on GO	interior of objects by transmitting ultrasonic or lic waves through the object (G01N 3/00- 1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01]
27/403 27/404 27/406 27/407	:	•	C .	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5]		th so G	he on GO	interior of objects by transmitting ultrasonic or nic waves through the object (G01N 3/00- 1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques
27/403 27/404 27/406 27/407 27/409		•	C	ells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] for investigating or analysing gases [5] Oxygen concentration cells [5]	29/024	th so G	he on GO	interior of objects by transmitting ultrasonic or tic waves through the object (G01N 3/00- 1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation
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27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/419 27/42 27/44 27/44 27/447 27/453	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5]	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12	the source of th	GO CONTRACTOR CONTRACT	interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] using acoustic emission techniques [5, 2006.01]
27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/42 27/42	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5] using polarography, i.e. measuring changes in	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12 29/14 29/22	th so G	in the second se	interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] hy measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] cusing acoustic emission techniques [5, 2006.01] Details [5]
27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/419 27/42 27/44 27/44 27/447 27/453	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5]	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12 29/14 29/22 29/24	th so G		interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] using acoustic emission techniques [5, 2006.01] Details [5] Probes [5]
27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/419 27/42 27/44 27/44 27/447 27/453	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5] using polarography, i.e. measuring changes in	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12 29/14 29/22 29/24 29/26	th so G		interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] using acoustic emission techniques [5, 2006.01] Details [5] Probes [5] Arrangements for orientation or scanning [5]
27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/419 27/42 27/44 27/44 27/447 27/453	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5] using polarography, i.e. measuring changes in	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12 29/14 29/22 29/24 29/26	th so G	illing in the second se	interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] hy measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] using acoustic emission techniques [5, 2006.01] Details [5] Probes [5] Arrangements for orientation or scanning [5] by moving the sensor relative to a stationary
27/403 27/404 27/406 27/407 27/409 27/41 27/411 27/413 27/414 27/416 27/417 27/419 27/42 27/44 27/44 27/447 27/453	• • • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • • •		cells and electrode assemblies [5] Cells with anode, cathode and cell electrolyte on the same side of a permeable membrane which separates them from the sample fluid [5] Cells and probes with solid electrolytes [5] • for investigating or analysing gases [5] • Oxygen concentration cells [5] • Oxygen pumping cells [5] • for investigating or analysing of liquid metals [5] Concentration cells using liquid electrolytes [5] Ion-sensitive or chemical field-effect transistors, i.e. ISFETS or CHEMFETS [5] ystems (G01N 27/27 takes precedence) [5] using cells and probes with solid electrolytes [5] • Measuring voltages or currents with a combination of oxygen pumping cells and oxygen concentration cells [5] Measuring deposition or liberation of materials from an electrolyte; Coulometry, i.e. measuring coulomb-equivalent of material in an electrolyte [5] • using electrolysis to generate a reagent, e.g. for titration [5] using electrophoresis [5] • Cells therefor [5] using polarography, i.e. measuring changes in	29/024 29/028 29/032 29/036 29/04 29/06 29/07 29/09 29/11 29/12 29/14 29/22 29/24 29/26 29/265	th so G	illing in the second se	interior of objects by transmitting ultrasonic or ic waves through the object (G01N 3/00-1N 27/00 take precedence) [4] Analysing fluids (using acoustic emission techniques G01N 29/14) [5, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] hy measuring frequency or resonance of acoustic waves [2006.01] Analysing solids (using acoustic emission techniques G01N 29/14) [4, 5, 2006.01] Visualisation of the interior, e.g. acoustic microscopy [4, 2006.01] by measuring propagation velocity or propagation time of acoustic waves [2006.01] by measuring mechanical or acoustic impedance [2006.01] by measuring attenuation of acoustic waves [2006.01] by measuring frequency or resonance of acoustic waves [5, 2006.01] custing acoustic emission techniques [5, 2006.01] Details [5] Probes [5] Arrangements for orientation or scanning [5] by moving the sensor relative to a stationary material [2006.01]

20/275	h.,	20/50	
29/275	• • • by moving both the sensor and the material [2006.01]	30/50	 Conditioning of the sorbent material or stationary liquid [4]
29/28	 providing acoustic coupling [5] 	30/52	• • • Physical parameters [4]
29/30	Arrangements for calibrating or comparing, e.g.	30/54	• • • • Temperature [4]
20 /22	with standard objects [2006.01]	30/56	• • • Packing methods or coating methods [4]
29/32	Arrangements for suppressing undesired influences, a.g. temporative or pressure.	30/58	• • • the sorbent moving as a whole [4]
	influences, e.g. temperature or pressure variations [2006.01]	30/60	Construction of the column [4]
29/34	Generating the ultrasonic, sonic or infrasonic	30/62	• • Detectors specially adapted therefor [4]
23734	waves [2006.01]	30/64	• • • Electrical detectors [4]
29/36	Detecting the response signal [2006.01]	30/66	• • • • Thermal conductivity detectors [4]
29/38	• • by time filtering, e.g. using time gates [2006.01]	30/68	• • • Flame ionisation detectors [4]
29/40	by amplitude filtering, e.g. by applying a	30/70	• • • Electron capture detectors (G01N 30/68 takes precedence) [4]
20 / 42	threshold [2006.01]	30/72	 • • Mass spectrometers [4]
29/42	• • by frequency filtering [2006.01]	30/74	• • • Optical detectors [4]
29/44	Processing the detected response signal [2006.01] Processing the detected response signal	30/76	• • Acoustical detectors [4]
29/46	 by spectral analysis, e.g. Fourier analysis [2006.01] 	30/78	 using more than one detector [4]
29/48	• • by amplitude comparison [2006.01]	30/80	 Fraction collectors [4]
29/50	 using auto-correlation techniques or cross- 	30/82	 • • Automatic means therefor [4]
23/30	correlation techniques [2006.01]	30/84	• • Preparation of the fraction to be distributed [4]
29/52	using inversion methods other than spectral	30/86	Signal analysis [4]
20,02	analysis, e.g. conjugated gradient	30/88	 Integrated analysis systems specially adapted
	inversion [2006.01]		therefor, not covered by a single one of groups G01N 30/04-G01N 30/86 [4]
30/00	Investigating or analysing materials by separation into components using adsorption, absorption or	30/89	 Inverse chromatography, i.e. with the analyte in stationary phase [2006.01]
	similar phenomena or using ion-exchange, e.g. chromatography (G01N 3/00-G01N 29/00 take	30/90	 Plate chromatography, e.g. thin layer or paper chromatography [4]
	precedence) [4]	30/91	Application of the sample [4]
30/02	Column chromatography [4]	30/92	Construction of the plate [4]
	Note(s)	30/93	• • • Application of the sorbent layer [4]
	• • • • • • • • • • • • • • • • • • • •	30/94	• • Development [4]
	In this group, the following term is used with the	30/95	Detectors specially adapted therefor; Signal
	meaning indicated: "conditioning" means the adjustment or		analysis [4]
	control of environmental parameters, e.g. temperature or pressure.	30/96	 using ion-exchange (G01N 30/02, G01N 30/90 take precedence) [4]
30/04	Preparation or injection of sample to be		
50,01	analysed [4]	31/00	Investigating or analysing non-biological materials
30/06	• • • Preparation [4]		by the use of the chemical methods specified in the
30/08	• • • • using an enricher [4]		subgroups; Apparatus specially adapted for such methods [4]
30/10	• • • • using a splitter [4]		methods [4]
30/12	• • • • by evaporation [4]		Note(s)
30/14	• • • by elimination of some components [4]		The observation of the progress of the reactions covered
30/16	• • • Injection (G01N 30/24 takes precedence) [4]		by groups G01N 31/02-G01N 31/22 by any of the
30/18	• • • • using a septum or microsyringe [4]		methods specified in groups G01N 3/00-G01N 29/00, if
30/20	• • • • using a sampling valve [4]		this observation is of major importance, is classified in
30/22	• • • • in high pressure liquid systems [4]	24 /02	the relevant group covering the method.
30/24	• • • Automatic injection systems [4]	31/02	using precipitation
30/26	• • Conditioning of the fluid carrier; Flow patterns [4]	31/10	• using catalysis
30/28	Control of physical parameters of the fluid	31/12	• using combustion (G01N 25/20 takes precedence)
	carrier [4]	31/16	• using titration
30/30	• • • of temperature [4]	31/18	Burettes specially adapted for titration
30/32	• • • of pressure or speed (G01N 30/36 takes	31/20	• using micro-analysis, e.g. drop reaction
	precedence) [4]	31/22	• using chemical indicators (G01N 31/02 takes
30/34	 • • of fluid composition, e.g. gradient 		precedence)
	(G01N 30/36 takes precedence) [4]	33/00	Investigating or analysing materials by specific
30/36	• • • in high pressure liquid systems [4]		methods not covered by groups G01N 1/00-
30/38	• • • Flow patterns [4]		G01N 31/00
30/40	• • • using back flushing [4]	33/02	• Food
30/42	• • • using counter-current [4]	33/03	 Edible oils or edible fats [4]
30/44	• • • using recycling of the fraction to be	33/04	 Dairy products
20/10	distributed [4]	33/06	 • Determining fat content, e.g. by butyrometer
30/46	• • • using more than one column [4]	33/08	 Eggs, e.g. by candling
		33/10	• • Starch-containing substances, e.g. dough

33/12 • • Meat; fish			e complex formed in liquid
33/14 • Beverages		phase [4] 33/537 • • • • with sepa	nration of immune complex from
33/15 • Medicinal preparations [3]33/18 • Water			antigen or antibody [4]
33/20 • Metals			bent column, particles or resin
33/22 • Fuels; explosives		strip [
33/24 • Earth materials (G01N 33/42	2 takes precedence)		ring precipitating reagent [4]
33/26 • Oils; viscous liquids; paints;			uble or second antibody [4]
precedence)			ic inhibition or signal tion, e.g. fluorescent
• • Oils (edible oils or edible		quenchin	
33/30 • • • for lubricating properti	es	_	luble carrier for immobilising
33/32 • Paints; inks		immunoche	9
33/34 • Paper 33/36 • Textiles			er being organic [4]
33/38 • Concrete; lime; mortar; gyps	um: bricks: ceramics:	33/545 • • • • • Synthe	
glass	ani, oriens, cerumics,		water suspendable particles [4]
33/40 • Grinding-materials			h antigen or antibody attached to carrier <u>via</u> a bridging agent [4]
• Road-making materials (G01	IN 33/38 takes		hydrates, e.g. dextran [4]
precedence)			ntigen or antibody entrapped
• Resins; plastics; rubber; lead • Wood	ner	within	the carrier [4]
33/46 • Wood33/48 • Biological material, e.g. bloc	od urino (C01N 33/02		er being inorganic [4]
G01N 33/26, G01N 33/44, C	601N 33/46 take	33/552 • • • • • Glass	
precedence); Haemocytomet	ers (counting blood	33/553 • • • • • Metal	
corpuscules distributed over			er being a biological cell or cell , e.g. bacteria, yeast cells [4]
the surface G06M 11/02) [3,		33/555 • • • • • Red b	
33/483 • • Physical analysis of biolo 33/487 • • • of liquid biological ma			ed or stabilised red blood cell [4]
33/49 • • • • blood [4]	teriai [4]		c measurement, i.e. time rate of
33/493 • • • • urine [4]		progress of	an antigen-antibody
33/497 • • • of gaseous biological r	naterial, e.g. breath [4]	interaction [
33/50 • • Chemical analysis of biol			ion or migration of antigen or
blood, urine; Testing invo		antibody [4] 33/559 • • • • through a	ı ı gel, e.g. Ouchterlony
binding methods; Immune		technique	
(measuring or testing pro- immunological involving		-	electrophoresis [4]
organisms, compositions		33/563 • • • involving ar	ntibody fragments [4]
processes of forming such			ring immune complex or
responsive control in mici enzymological processes		autoimmune	
enzymologicai processes	C12Q) [3]		ic carrier or receptor proteins as ng reagent [4]
Note(s)		33/567 • • • • utilising	-
In this group, the following exp	pression is used with the	binding a	
meaning indicated: • "involving" when i	and in relation to a		ganisms, e.g. protozoa, bacteria,
 "involving", when material, includes t 		viruses [4]	
	employing the material		eal disease, e.g. syphilis, ea, herpes [4]
as a determinant or	reactant in a test for a	33/573 • • • • for enzymes	
different material.		33/574 • • • • for cancer [4	
Note(s)		33/576 • • • • for hepatitis	_
In groups G01N 33/52-G01N 3	3/98, in the absence of	33/577 • • • • involving m	onoclonal antibodies [4]
an indication to the contrary, cl		33/579 • • • involving limu	lus lysate [4]
the last appropriate place.		33/58 • • • involving label	
33/52 • • • Use of compounds or colorimetric, spectroph			akes precedence) [3]
	ion, e.g. use of reagent	33/60 • • • involving ra 33/62 • • involving urea	dioactive labelled substances [3]
paper [3]	, 0	33/64 • • • involving ketor	
33/53 • • • Immunoassay; Biospec	cific binding assay;	_	d sugars, e.g. galactose [3]
Materials therefor [4]			eins, peptides or amino acids [3]
33/531 • • • • Production of immumaterials [4]	nochemical test	33/70 • • • involving creat	
33/532 • • • • Production of lab	pelled		d pigments, e.g. hemoglobin,
immunochemica		bilirubin [3]	[0]
33/533 • • • • with fluoresce		33/74 • • • involving horm	
33/534 • • • • with radioacti		33/76 • • • • Human chor 33/78 • • • Thyroid glar	
33/535 • • • • • with enzyme l	abel [4]	55/70 - • • Ingroid gla	na normones [3]

35/00	Automatic analysis not limited to methods or materials provided for in any single one of groups G01N 1/00-G01N 33/00; Handling materials		
		37/00	Details not covered by any other group of this subclass [3]
33/98	• • involving alcohol, e.g. ethanol in breath [4]	37/00	Details not serveyed by any other group of this
33/96	• • • involving blood or serum control standard [3]		devices [6]
33/94	 involving narcotics [3] 		analysis apparatus, e.g. suction devices, injection
33/92	 involving lipids, e.g. cholesterol [3] 	35/10	Devices for transferring samples to, in, or from, the analysis apparatus a g systion devices injection.
33/90	 • involving iron binding capacity of blood [3] 	25/10	
33/88	• • • involving prostaglandins [3]	35/08	• using a stream of discrete samples flowing along a tube system, e.g. flow injection analysis [3]
33/86	 • involving blood coagulating time [3] 		* * *
		35/04	 Details of the conveyor system [3]
33/84	• • • involving inorganic compounds or pH [3]		analysis stations [3]
33/82	• • • involving vitamins [3]		conveyor system past one or more treatment or
33/80	 involving blood groups or blood types [3] 	35/02	 using a plurality of sample containers moved by a

MEASURING LINEAR OR ANGULAR SPEED, ACCELERATION, DECELERATION OR SHOCK; INDICATING PRESENCE OR ABSENCE OF MOVEMENT; INDICATING DIRECTION OF MOVEMENT (measuring angular rate using gyroscopic effects G01C 19/00; combined measuring devices for measuring two or more variables of movement G01C 23/00; measuring velocity of sound G01H 5/00; measuring velocity of light G01J 7/00; determining direction or velocity of solid objects by reflection or reradiation of radio or other waves and based on propagation effects, e.g. Doppler effect, propagation time or direction of propagation, G01S; measuring speed of nuclear radiation G01T)

Note(s)

- This subclass <u>covers</u> measuring direction or velocity of flowing fluids using propagation effects of radiowaves or other waves caused in the fluid itself, e.g. by laser anemometer, by ultrasonic flowmeter with "sing-around-system".
- 2. Attention is drawn to the Notes following the title of class G01.

Subclass index

therefor [3]

INDICATING MOVEMENT OR DIRECTION OF MOVEMENT	13/00
MEASURING LINEAR OR ANGULAR SPEED OF SOLID BODIES	
Characterised by prevailing principle of action of the means	3/00
By integration; by gyroscopic effect; by averaging	7/00, 11/00
MEASURING SPEED OF FLUIDS OR RELATIVE SPEED OF SOLID TO FLUID OR FLUID TO	
SOLID	5/00
MEASURING ACCELERATION OR SUDDEN CHANGE OF ACCELERATION	15/00
DETAILS	1/00
FUNCTIONAL TESTING OR CALIBRATING	21/00

1/00	Details of instruments		Note(s)
1/02 1/04 1/07 1/08	 Housings Special adaptations of driving means Indicating devices, e.g. for remote indication [3] Arrangements of scales, pointers, lamps, or 	2./02	Groups G01P 3/02-G01P 3/64 are distinguished by the method of measurement which is of major importance. Thus the mere application of other methods for giving a final indication does not affect the classification.
	acoustic indicators, e.g. in automobile speedometers	3/02	 Devices characterised by the use of mechanical means
1/10	 for indicating predetermined speeds 	3/04	 by comparing two speeds
1/11	• • • by the detection of the position of the	3/06	• • using a friction gear
	indicator needle [3]	3/08	 using differential gearing
1/12	 Recording devices [3] 	3/10	 by actuating an indicating element, e.g. pointer,
1/14	 for permanent recording [3] 		for a fixed time
1/16	 for erasable recording, e.g. magnetic recording [3] 	3/12	 by making use of a system excited by impact
3/00	Measuring linear or angular speed; Measuring differences of linear or angular speeds (G01P 5/00-G01P 11/00 take precedence; measuring angular rate using gyroscopic effects G01C 19/00)	3/14 3/16 3/18 3/20 3/22	 by exciting one or more mechanical resonance systems by using centrifugal forces of solid masses transferred to the indicator by mechanical means transferred to the indicator by fluid means transferred to the indicator by electric or magnetic means
		3/24	 by using friction effects (G01P 3/06 takes precedence)

3/26	• Devices characterised by the use of fluids	5/07	• • • with electrical coupling to the indicating
3/28	• • by using pumps	F /00	device [3]
3/30	by using centrifugal forces of fluids	5/08	 by measuring variation of an electric variable directly affected by the flow, e.g. by using dynamo-electric
3/32	• • in a rotary container communicating with a fixed container		effect
3/34	by using friction effects	5/10	 by measuring thermal variables
3/36	Devices characterised by the use of optical means,	5/12	• using variation of resistance of a heated conductor
5750	e.g. using infra-red, visible, or ultra-violet light	5/14	 by measuring differences of pressure in the fluid
	(G01P 3/68 takes precedence)	5/16	 using Pitot tubes
3/38	 using photographic means 	5/165	• • • Arrangements or constructions of Pitot
3/40	 using stroboscopic means 		tubes [3]
3/42	 Devices characterised by the use of electric or 	5/17	Coupling arrangements to the indicating
	magnetic means (G01P 3/66 takes precedence)	E /485	device [3]
3/44	• • for measuring angular speed (G01P 3/56 takes	5/175	• • • • with the determination of Mach number [3]
2/46	precedence)	5/18	• by measuring the time taken by the fluid to traverse a fixed distance [1, 7]
3/46	 • by measuring amplitude of generated current or voltage 	5/20	 using particles entrained by a fluid stream
3/48	• • by measuring frequency of generated current or	3/20	(G01P 5/22 takes precedence) [4]
37 13	voltage	5/22	using auto-correlation or cross-correlation
3/481	• • • • of pulse signals [3]		detection means [4]
3/482	• • • delivered by nuclear radiation	5/24	 by measuring the direct influence of the streaming
	detectors [3]		fluid on the properties of a detecting acoustical
3/483	 • • • delivered by variable capacitance 	= 100	wave [7]
	detectors [3]	5/26	by measuring the direct influence of the streaming fluid on the proporties of a detecting entirel views [7]. [7]
3/484	• • • • delivered by contact-making switches [3]		fluid on the properties of a detecting optical wave [7]
3/486	• • • • delivered by photo-electric detectors [3]	7/00	Measuring speed by integrating acceleration (inertial
3/487	• • • • delivered by rotating magnets [3]		navigation, i.e. calculating position or speed aboard the
3/488	• • • • delivered by variable reluctance detectors [3]		object being navigated, by integration of speed or
3/489	• • • • • Digital circuits therefor [3]		acceleration G01C 21/16)
3/49	• • using eddy currents	11/00	Measuring average value of speed (by determining
3/495	• • • where the indicating means responds to		time taken to traverse a fixed distance G01P 3/64,
<i>57</i> 155	forces produced by the eddy currents and the		G01P 5/18)
	generating magnetic field [3]	11/02	• Measuring average speed of a number of bodies, e.g.
3/50	 for measuring linear speed (G01P 3/56 takes 		of vehicles for traffic control
	precedence)	13/00	Indicating or recording presence or absence of
3/52	• • by measuring amplitude of generated current or	13, 00	movement; Indicating or recording of direction of
3/54	voltage• by measuring frequency of generated current or		movement
3/34	voltage	13/02	 Indicating direction only, e.g. by weather vane
3/56	for comparing two speeds	13/04	 Indicating positive or negative direction of a linear
3/58	• • by measuring or comparing amplitudes of		movement or clockwise or anti-clockwise
	generated currents or voltages		direction of a rotational movement [3]
3/60	 • • by measuring or comparing frequency of 	15/00	Measuring acceleration; Measuring deceleration;
	generated currents or voltages		Measuring shock, i.e. sudden change of acceleration
3/62	• Devices characterised by the determination of the	15/02	• by making use of inertia forces (G01P 15/14 takes
	variation of atmospheric pressure with height to		precedence) [1, 7, 2013.01]
2/64	measure the vertical components of speed	15/03	 by using non-electrical means [3]
3/64	 Devices characterised by the determination of the time taken to traverse a fixed distance 	15/04	for indicating maximum value
3/66	using electric or magnetic means (G01P 3/80 takes)	15/06	using members subjected to a permanent deformation
57 00	precedence) [4]	15/00	deformation
3/68	using optical means, i.e. using infra-red, visible, or	15/08 15/09	with conversion into electric or magnetic valuesby piezo-electric pick-up [3]
	ultra-violet light (G01P 3/80 takes precedence) [4]	15/093	by piezo-electric pick-up [5]by photoelectric pick-up [7]
3/80	using auto-correlation or cross-correlation	15/097	• • • by vibratory elements [7]
	detection means [4]	15/10	• • • by vibratory strings
5/00	Measuring speed of fluids, e.g. of air stream;	15/105	• • by magnetically sensitive devices [7]
5/00	Measuring speed of bodies relative to fluids, e.g. of	15/11	• • • • by inductive pick-up [3]
	ship, of aircraft (application of speed-measuring	15/12	• • by alteration of electrical resistance
	devices for measuring volume of fluids G01F)	15/125	• • by capacitive pick-up [3]
5/01	 by using swirlflowmeter [3] 	15/13	• • by measuring the force required to restore a
5/02			
	by measuring forces exerted by the fluid on solid		proofmass subjected to inertial forces to a null
	bodies, e.g. anemometer		position [3]
5/04 5/06		15/135	

15/14	by making use of gyroscopes [1, 7, 2013.01]	21/00	Testing or calibrating of apparatus or devices
15/16	 by evaluating the time-derivative of a measured 		covered by the other groups of this subclass
	speed signal [3, 7, 2013.01]	21/02	 of speedometers
15/18	 in two or more dimensions [7, 2013.01] 		

G01Q SCANNING-PROBE TECHNIQUES OR APPARATUS; APPLICATIONS OF SCANNING-PROBE TECHNIQUES, e.g. SCANNING-PROBE MICROSCOPY [SPM] [2010.01]

Note(s) [2010.01]

In this subclass, the first place priority rule is applied, i.e. at each hierarchical level, classification is made in the first appropriate place.

10/00	Scanning or positioning arrangements, i.e. arrangements for actively controlling the movement	60/12	• • STS [Scanning Tunnelling Spectroscopy] [2010.01]
40.400	or position of the probe [2010.01]	60/14	STP [Scanning Tunnelling
10/02	Coarse scanning or positioning [2010.01]		Potentiometry] [2010.01]
10/04	• Fine scanning or positioning [2010.01]	60/16	Probes, their manufacture or their related
10/06	• • Circuits or algorithms therefor [2010.01]	60/10	instrumentation, e.g. holders [2010.01]
20/00	Monitoring the movement or position of the	60/18	SNOM [Scanning Near-Field Optical Microscopy] or SNOM probes [2010.01]
20/00	probe [2010.01]	60/20	apparatus therefor, e.g. SNOM probes [2010.01]
20/02	 by optical means [2010.01] 	60/20	• • Fluorescence [2010.01]
20/02	• Self-detecting probes, i.e. wherein the probe itself	60/22	• • Probes, their manufacture or their related
20/04	generates a signal representative of its position, e.g.	60/24	instrumentation, e.g. holders [2010.01]AFM [Atomic Force Microscopy] or apparatus
	piezo-electric gauge [2010.01]	00/24	therefor, e.g. AFM probes [2010.01]
		60/26	 Friction force microscopy [2010.01]
30/00	Auxiliary means serving to assist or improve the	60/28	 Adhesion force microscopy [2010.01]
	scanning probe techniques or apparatus, e.g. display	60/30	 • Scanning potential microscopy [2010.01]
	or data processing devices [2010.01]	60/30	• • AC mode [2010.01]
30/02	Non-SPM analysing devices, e.g. SEM [Scanning]	60/34	
	Electron Microscope], spectrometer or optical		 • Tapping mode [2010.01] • DC mode [2010.01]
20/04	microscope [2010.01]	60/36	
30/04	Display or data processing devices [2010.01] The array processing [2010.01]	60/38	 Probes, their manufacture or their related instrumentation, e.g. holders [2010.01]
30/06	• • for error compensation [2010.01]	60/40	• • Conductive probes [2010.01]
30/08	 Means for establishing or regulating a desired environmental condition within a sample 	60/40	• • • Functionalisation [2010.01]
	chamber [2010.01]	60/42	
30/10	Thermal environment [2010.01]	00/44	 SICM [Scanning Ion-Conductance Microscopy] or apparatus therefor, e.g. SICM probes [2010.01]
30/10	Fluid environment [2010.01]	60/46	 SCM [Scanning Capacitance Microscopy] or
30/12	Liquid environment [2010.01]	00740	apparatus therefor, e.g. SCM probes [2010.01]
30/14	Vacuum environment [2010.01]	60/48	 • Probes, their manufacture or their related
30/18	Means for protecting or isolating the interior of a	007 40	instrumentation, e.g. holders [2010.01]
30/10	sample chamber from external environmental	60/50	MFM [Magnetic Force Microscopy] or apparatus
	conditions or influences, e.g. vibrations or		therefor, e.g. MFM probes [2010.01]
	electromagnetic fields [2010.01]	60/52	• • Resonance [2010.01]
30/20	Sample handling devices or methods [2010.01]	60/54	 Probes, their manufacture or their related
			instrumentation, e.g. holders [2010.01]
40/00	Calibration, e.g. of probes [2010.01]	60/56	• • • Probes with magnetic coating [2010.01]
40/02	 Calibration standards or methods of fabrication 	60/58	 SThM [Scanning Thermal Microscopy] or apparatus
	thereof [2010.01]		therefor, e.g. SThM probes [2010.01]
60/00	Particular types of SPM [Scanning-Probe	60/60	 SECM [Scanning Electro-Chemical Microscopy] or
00/00	Microscopy] or apparatus therefor; Essential		apparatus therefor, e.g. SECM probes [2010.01]
	components thereof [2010.01]	= 0.400	C I CONT I II I
60/02	Multiple-type SPM, i.e. involving two or more SPM	70/00	General aspects of SPM probes, their manufacture
00702	techniques [2010.01]		or their related instrumentation, insofar as they are not specially adapted to a single SPM technique
60/04	STM [Scanning Tunnelling Microscopy]		covered by group G01Q 60/00 [2010.01]
	combined with AFM [Atomic Force	70/02	 Probe holders [2010.01]
	Microscopy] [2010.01]	70/04	 with compensation for temperature or vibration
60/06	SNOM [Scanning Near-field Optical Microscopy]	, 0, 04	induced errors [2010.01]
	combined with AFM [Atomic Force	70/06	 Probe tip arrays [2010.01]
	Microscopy] [2010.01]	70/08	• Probe characteristics [2010.01]
60/08	MFM [Magnetic Force Microscopy] combined	70/10	 Shape or taper [2010.01]
	with AFM [Atomic Force Microscopy] [2010.01]	70/10	• • Nano-tube tips [2010.01]
60/10	STM [Scanning Tunnelling Microscopy] or apparatus the of the second STM and the [2010 01].	70/12	Particular materials [2010.01]
	therefor, e.g. STM probes [2010.01]	. 0/ 11	- arrenar materials [motoror]

70/16	•	Probe manufacture [2010.01]
70/18	•	• Functionalisation [2010.01]

80/00 Applications, other than SPM, of scanning-probe techniques (manufacture or treatment of microstructures B81C; manufacture or treatment of nanostructures B82B 3/00; recording or reproducing information using near-field interaction G11B 9/12, G11B 11/24 or G11B 13/08) [2010.01]

90/00 Scanning-probe techniques or apparatus not otherwise provided for [2010.01]

G01R MEASURING ELECTRIC VARIABLES; MEASURING MAGNETIC VARIABLES (indicating correct tuning of resonant circuits H03J 3/12)

Note(s)

- This subclass covers:
 - measuring all kinds of electric or magnetic variables directly or by derivation from other electric or magnetic variables;
 - measuring all kinds of electric or magnetic properties of materials;
 - testing electric or magnetic devices, apparatus or networks (e.g. discharge tubes, amplifiers) or measuring their characteristics;
 - indicating presence or sign of current or voltage;
 - NMR, EPR or other spin-effect apparatus, not specially adapted for a particular application;
 - equipment for generating signals to be used for carrying out such tests and measurements.
- 2. In this subclass, the following terms or expressions are used with the meanings indicated:
 - "measuring" includes investigating;
 - "instruments" or "measuring instruments" means electro-mechanical measuring mechanisms;
 - "arrangements for measuring" means apparatus, circuits, or methods for measuring;
- Attention is drawn to the Notes following the title of class G01. 3.
- In this subclass, instruments or arrangements for measuring electric variables are classified in the following way:
 - Electromechanical instruments where the measured electric variables directly effect the indication of the measured value, including combined effects of two or more values, are classified in groups G01R 5/00-G01R 11/00.
 - Details common to different types of the instruments covered by groups G01R 5/00-G01R 11/00 are classified in group G01R 1/00.
 - Arrangements involving circuitry to obtain an indication of a measured value by deriving, calculating or otherwise processing electric variables, e.g. by comparison with another value, are classified in groups G01R 17/00-G01R 29/00.
 - Details common to different types of arrangements covered by groups G01R 17/00-G01R 29/00 are classified in group G01R 15/00.

5. In this subclass, group G01R 17/00 takes precedence over group	ps G01R 19/00-G01R 31/00.
Subclass index	
ELECTRIC MEASURING INSTRUMENTS In general	
 1/00 Details of instruments or arrangements of the types covered by groups G01R 5/00-G01R 13/00 or G01R 31/00 (constructional details particular to electromechanical arrangements for measuring the electric consumption G01R 11/02) [3, 2006.01] 1/02 • General constructional details 1/04 • Housings; Supporting members; Arrangements of terminals 	 1/08 • Pointers; Scales, Scale illumination 1/10 • Arrangements of bearings 1/12 • • of strip or wire bearings 1/14 • Braking arrangements; Damping arrangements 1/16 • Magnets 1/18 • Screening arrangements against electric or magnetic fields, e.g. against earth's field

1/06 Measuring leads; Measuring probes (G01R 19/145, G01R 19/165 take precedence) [3] 1/067 • • • Measuring probes **[3]** 1/07 • • • Non contact-making probes [6]

1/073 • • • • Multiple probes **[3]**

1/20 · Modifications of basic electric elements for use in electric measuring instruments; Structural combinations of such elements with such instruments

1/22 Tong testers acting as secondary windings of current transformers

1/24	Transmission-line, e.g. waveguide, measuring	11/00	Electromechanical arrangements for measuring time
1 /06	sections, e.g. slotted section		<pre>integral of electric power or current, e.g. of consumption (monitoring electric consumption of</pre>
1/26	• • • with linear movement of probe		electrically-propelled vehicles B60L 3/00)
1/28	 Provision in measuring instruments for reference values, e.g. standard voltage, standard waveform 	11/02	Constructional details
1/30	Structural combination of electric measuring	11/04	Housings; Supporting racks; Arrangements of
1750	instruments with basic electronic circuits, e.g. with	11/06	terminals
1/36	amplifier Overload protection arrangements or sirguits for	11/06	 Magnetic circuits of induction meters [2] Coils therefor [2]
1/30	 Overload-protection arrangements or circuits for electric measuring instruments 	11/06/	• • • Armatures therefor [2]
1/38	Arrangements for altering the indicating	11/0/3	• • • Disc armatures [2]
1750	characteristic, e.g. by modifying the air gap	11/09	Braking magnets; Damping arrangements
1/40	 Modifications of instruments to indicate the 	11/10	Arrangements of bearings
	maximum or the minimum value reached in a time	11/12	• • • with magnetic relief
	interval, e.g. by maximum indicator pointer [3]	11/16	Adaptations of counters to electricity meters
1/42	 thermally operated 	11/17	 Compensating for errors; Adjusting or regulating
1/44	 Modifications of instruments for temperature compensation [2] 		means therefor [2]
3/00	Apparatus or processes specially adapted for the	11/18	 Compensating for variations in ambient conditions [2]
3700	manufacture of measuring instruments	11/185	• • • • Temperature compensation [2]
	munucui e vi meuvui mg mori umento	11/19	• • Compensating for errors caused by disturbing
5/00	Instruments for converting a single current or a single voltage into a mechanical displacement		torque, e.g. rotating-field errors of polyphase meters [2]
5/02	 Moving-coil instruments 	11/20	 Compensating for phase errors in induction
5/04	 with magnet external to the coil 		meters [2]
5/06	with core magnet	11/21	 Compensating for errors caused by damping
5/08	 specially adapted for wide angle deflection; with eccentrically-pivoted moving coil 		effects of the current, e.g. adjustment in the overload range [2]
5/10	String galvanometers	11/22	 • Adjusting torque, e.g. adjusting starting torque,
5/12	Loop galvanometers		adjusting of polyphase meters for obtaining
5/14	 Moving-iron instruments 	11/22	equal torques [2]
5/16	with pivoting magnet	11/23	 Compensating for errors caused by friction, e.g adjustment in the light-load range [2]
5/18	 with pivoting soft iron, e.g. needle galvanometer 	11/24	Arrangements for avoiding or indicating
5/20	 Induction instruments e.g. Ferraris instruments 	11/24	fraudulent use [4]
5/22	 Thermoelectric instruments 	11/25	Arrangements for indicating or signalling
5/24	 operated by elongation of a strip or wire or by expansion of a gas or fluid 		faults [2, 4]
5/26	 operated by deformation of a bimetallic element 		Note(s)
5/28	 Electrostatic instruments 		Groups G01R 11/48-G01R 11/56 take precedence over
5/30	 Leaf electrometers 		groups G01R 11/30-G01R 11/46.
5/32	 Wire electrometers; Needle electrometers 	11/30	 Dynamo-electric motor meters
5/34	 Quadrant electrometers 	11/32	 Watt-hour meters
5 /00	T	11/34	 Ampère-hour meters
7/00	Instruments capable of converting two or more	11/36	 Induction meters, e.g. Ferraris meters
	currents or voltages into a single mechanical displacement (G01R 9/00 takes precedence)	11/38	 for single-phase operation
7/02	 for forming a sum or a difference 	11/40	 for polyphase operation
7/04	 for forming a quotient (for measuring resistance 	11/42	Circuitry therefor
	G01R 27/08)	11/46	 Electrically-operated clockwork meters; Oscillatory meters; Pendulum meters
7/06	• • moving-iron type	11/48	 Meters specially adapted for measuring real or
7/08	moving-coil type, e.g. crossed-coil type		reactive components; Meters specially adapted for
7/10	• • having more than two moving coils		measuring apparent energy
7/12	for forming product	11/50	 for measuring real component
7/14	• • moving-iron type	11/52	 for measuring reactive component
7/16	having both fixed and moving coils, i.e. dynamometers A state of the condition of the	11/54	 for measuring simultaneously at least two of the following three variables: real component, reactive
7/18	 • with iron core magnetically coupling fixed and moving coils 	11/56	component, apparent energy • Special tariff meters
	<u> </u>	11/50	Multi-rate meters (G01R 11/63 takes)
9/00	Instruments employing mechanical resonance	11/3/	precedence) [2]
9/02	 Vibration galvanometers, e.g. for measuring current 	11/58	• • • Tariff-switching devices therefor [2]
9/04	 using vibrating reeds, e.g. for measuring frequency 	11/60	Subtraction meters; Meters measuring maximum
9/06	 magnetically driven 		or minimum-load hours

9/08 • • piezo-electrically driven

11/63	 Over-consumption meters, e.g. measuring 	15/24	 using light-modulating devices [6]
	consumption while a predetermined level of power	15/26	 using modulation of waves other than light, e.g.
	is exceeded [2]		radio or acoustic waves [6]
11/64	Maximum meters, e.g. tariff for a period is based	17/00	Managering agreements involving comparison with
11/00	on maximum demand within that period	17/00	Measuring arrangements involving comparison with a reference value, e.g. bridge
11/66	· · · Circuitry	17/02	Arrangements in which the value to be measured is
13/00	Arrangements for displaying electric variables or	17702	automatically compared with a reference value
	waveforms [4]	17/04	 in which the reference value is continuously or
13/02	 for displaying measured electric variables in digital 		periodically swept over the range of values to be
	form [4]		measured
13/04	 for producing permanent records [4] 	17/06	 Automatic balancing arrangements
13/06	 Modifications for recording transient disturbances, 	17/08	 in which a force or torque representing the
	e.g. by starting or accelerating a recording medium		measured value is balanced by a force or torque
13/08	Electromechanical recording system using a		representing the reference value
	mechanical direct-writing method	17/10	ac or dc measuring bridges
13/10	• • • with intermittent recording by representing the	17/12	• • using comparison of currents, e.g. bridges with
	variable by the length of a stroke or by the	45/44	differential current output
13/12	position of a dot • Chemical recording, e.g. clydonographs	17/14	• • with indication of measured value by calibrated null indicator, e.g. percent bridge, tolerance bridge
13/12	(G01R 13/14 takes precedence)		(G01R 17/12, G01R 17/16 take precedence)
13/14	Recording on a light-sensitive material	17/16	 with discharge tubes or semiconductor devices in
13/16	Recording on a magnetic medium	17710	one or more arms of the bridge, e.g. voltmeter
13/18	• using boundary displacement		using a difference amplifier
13/20	Cathode-ray oscilloscopes	17/18	 with more than four branches
13/22	Circuits therefor	17/20	 ac or dc potentiometric measuring arrangements
13/24	Time-base deflection circuits	17/22	• • with indication of measured value by calibrated
13/26	Circuits for controlling the intensity of the		null indicator
	electron beam	10/00	A
13/28	• • Circuits for simultaneous or sequential	19/00	Arrangements for measuring currents or voltages or for indicating presence or sign thereof (G01R 5/00
	presentation of more than one variable		takes precedence; for measuring bioelectric currents or
13/30	• • Circuits for inserting reference markers, e.g. for		voltages A61B 5/04) [4]
	timing, for calibrating, for frequency marking		
13/32	 Circuits for displaying non-recurrent functions 		Note(s)
	such as transients; Circuits for triggering;		Within groups G01R 19/02-G01R 19/32, group
	Circuits for synchronisation; Circuits for time-		G01R 19/28 takes precedence. Groups G01R 19/18-
13/34	base expansion• Circuits for representing a single waveform by		G01R 19/25 take precedence over groups G01R 19/02-G01R 19/165 and G01R 19/30.
13/34	• • Circuits for representing a single waveform by sampling, e.g. for very high frequencies [2]	19/02	Measuring effective values, i.e. root-mean-square
13/36	using length of glow discharge, e.g. glowlight	19/02	values
10,00	oscilloscopes [4]	19/03	using thermoconverters [4]
13/38	 using the steady or oscillatory displacement of a light 	19/04	Measuring peak values of ac or of pulses [2]
	beam by an electromechanical measuring system [4]	19/06	Measuring real component; Measuring reactive
13/40	 using modulation of a light beam otherwise than by 		component
	mechanical displacement, e.g. by Kerr effect [4]	19/08	Measuring current density
13/42	 Instruments using length of spark discharge, e.g. by 	19/10	Measuring sum, difference, or ratio
	measuring maximum separation of electrodes to	19/12	Measuring rate of change
	produce spark	19/14	 Indicating direction of current; Indicating polarity of
15/00	Details of measuring arrangements of the types		voltage
	provided for in groups G01R 17/00-G01R 29/00,	19/145	 Indicating the presence of current or voltage [3]
	G01R 33/00-G01R 33/26 or G01R 35/00 [1, 2006.01]	19/15	 Indicating the presence of current [3]
15/04	Voltage dividers [6]	19/155	 Indicating the presence of voltage [3]
15/06	having reactive components, e.g. capacitive	19/165	Indicating that current or voltage is either above or
	transformer [6]		below a predetermined value or within or outside a
15/08	Circuits for altering the measuring range	10/17	predetermined range of values [3]
15/09	Autoranging circuits [6]	19/17	 giving an indication of the number of times this occurs [3]
15/12	Circuits for multi-testers, e.g. for measuring voltage, current, or impedance at will	19/175	Indicating the instants of passage of current or
15/14	current, or impedance at will	13/1/3	voltage through a given value, e.g. passage through
15/14	 Adaptations providing voltage or current isolation, e.g. for high-voltage or high-current networks [6] 		zero [3]
15/16	• using capacitive devices [6]	19/18	 using conversion of dc into ac, e.g. with choppers
15/18	 using capacitive devices [6] using inductive devices, e.g. transformers [6] 	19/20	• • using transductors
15/10	using inductive devices, e.g. transformers [0] using galvano-magnetic devices, e.g. Hall-effect	19/22	 using conversion of ac into dc
10/20	devices [6]	19/25	 using digital measurement techniques [3]
15/22	• using light-emitting devices, e.g. LED,		·
	optocouplers [6]		

19/252	 using analogue/digital converters of the type with conversion of voltage or current into frequency and measuring of this frequency [4] 	23/09	 • • using analogue integrators, e.g. capacitors establishing a mean value by balance of input signals and defined discharge signals or
19/255	 using analogue/digital converters of the type with counting of pulses during a period of time 	23/10	leakage [2]by converting frequency into a train of pulses,
	proportional to voltage or current, delivered by a	00/40	which are then counted
19/257	pulse generator with fixed frequency [4]using analogue/digital converters of the type with	23/12 23/14	by converting frequency into phase shift by betandyming by best frequency
15/25/	comparison of different reference values with the	23/14	 by heterodyning; by beat-frequency comparison [2]
	value of voltage or current, e.g. using step-by-step	23/15	 Indicating that frequency of pulses is either above
19/28	 method [4] adapted for measuring in circuits having distributed constants 		or below a predetermined value or within or outside a predetermined range of values, by making use of non-linear or digital elements [3]
19/30	Measuring the maximum or the minimum value of	23/16	Spectrum analysis; Fourier analysis
	current or voltage reached in a time interval (G01R 19/04 takes precedence) [2, 3]	23/163	 adapted for measuring in circuits having distributed constants [3]
19/32	 Compensating for temperature change [2] 	23/165	• • using filters [3]
21/00	Arrangements for measuring electric power or	23/167	• • • with digital filters [3]
	power factor (G01R 7/12 takes precedence) [4]	23/17	with optical auxiliary devices [3]
21/01	 in circuits having distributed constants (G01R 21/04, G01R 21/07, G01R 21/09, G01R 21/12 take 	23/173	Wobbulating devices similar to swept panoramic receivers [3]
54.455	precedence) [2]	23/175 23/177	 by delay means, e.g. tapped delay lines [3] Analysis of very low frequencies [3]
21/02 21/04	 by thermal methods [2] • in circuits having distributed constants	23/1//	 Analysis of very low frequencies [5] with provision for recording frequency spectrum
21/04	 by measuring current and voltage (G01R 21/08- 	23/20	Measurement of non-linear distortion
21700	G01R 21/133 take precedence) [4]	25 (22	
21/07	• • in circuits having distributed constants (G01R 21/09 takes precedence) [2]	25/00	Arrangements for measuring phase angle between a voltage and a current or between voltages or currents [2]
21/08	by using galvanomagnetic-effect devices, e.g. Hall-	25/02	in circuits having distributed constants
21 /00	effect devices [2]	25/04	 involving adjustment of a phase shifter to produce a
21/09 21/10	in circuits having distributed constants [2]by using square-law characteristics of circuit		predetermined phase difference, e.g. zero difference
21/10	elements, e.g. diodes, to measure power absorbed by	25/06	employing quotient instrument
	loads of known impedance (G01R 21/02 takes precedence) [2]	25/08 27/00	 by counting of standard pulses [2] Arrangements for measuring resistance, reactance,
21/12	in circuits having distributed constants	27700	impedance, or electric characteristics derived
21/127	 by using pulse modulation (G01R 21/133 takes precedence) [4] 		therefrom
21/133	by using digital technique [4]	27/02	Measuring real or complex resistance, reactance,
21/14	Compensating for temperature change [2]		impedance, or other two-pole characteristics derived therefrom, e.g. time constant (by measuring phase angle only G01R 25/00)
22/00	Arrangements for measuring time integral of electric	27/04	 in circuits having distributed constants
	power or current, e.g. electricity meters [4, 2006.01] Note(s)	27/06	• • • Measuring reflection coefficients; Measuring standing-wave ratio
	An arrangement for measuring time integral of electric power is classified in group G01R 21/00 if the essential	27/08	 Measuring resistance by measuring both voltage and current
	characteristic is the measuring of electric power.	27/10	• • using two-coil or crossed-coil instruments
22/02	• by electrolytic methods [4]	27/12	forming quotient
22/04	by calorimetric methods [4]	27/12 27/14	• • using hand generators, e.g. meggers• Measuring resistance by measuring current or
22/06	• by electronic methods [2006.01]	2//17	voltage obtained from a reference source
22/08 22/10	using analogue techniques [2006.01]using digital techniques [2006.01]		(G01R 27/16, G01R 27/20, G01R 27/22 take
22/10	using digital techniques [2000.01]	27/16	precedence)
23/00	Arrangements for measuring frequencies;	27/16	 Measuring impedance of element or network through which a current is passing from another
23/02	Arrangements for analysing frequency spectraArrangements for measuring frequency, e.g. pulse		source, e.g. cable, power line
25/02	repetition rate; Arrangements for measuring period of current or voltage	27/18 27/20	• • Measuring resistance to earth• Measuring earth resistance; Measuring contact
23/04	adapted for measuring in circuits having distributed constants	27/22	resistance of earth connections, e.g. plates • Measuring resistance of fluids
23/06	by converting frequency into an amplitude of current or voltage	27/26	• • Measuring inductance or capacitance; Measuring quality factor, e.g. by using the resonance method;
23/07	• • using response of circuits tuned on resonance, e.g. grid-drip meter [2]		Measuring loss factor; Measuring dielectric constants
23/08	• • • using response of circuits tuned off resonance		

27/28	Measuring attenuation, gain, phase shift, or derived	• • Preparation of articles or specimens to facilitate
	characteristics of electric four-pole networks, i.e. two-port networks; Measuring transient response (in	testing
	line transmission systems H04B 3/46)	• Testing of discharge tubes (during manufacture H01J 9/42) [2]
27/30	 with provision for recording characteristics, e.g. 	31/25 • • Testing of vacuum tubes [2]
27750	by plotting Nyquist diagram	31/26 • Testing of vacuum tubes [2] 31/26 • Testing of individual semiconductor devices (testing
27/32	• • in circuits having distributed constants [2]	or measuring during manufacture or treatment
	()	H01L 21/66; testing of photovoltaic devices
29/00	Arrangements for measuring or indicating electric	H02S 50/10) [2, 2014.01]
	quantities not covered by groups G01R 19/00-	31/265 • • Contactless testing [6]
	G01R 27/00	31/27 • • Testing of devices without physical removal from
29/02	Measuring characteristics of individual pulses, e.g.	the circuit of which they form part, e.g.
	deviation from pulse flatness, rise time or duration [3]	compensating for effects due to surrounding
29/027	Indicating that a pulse characteristic is either	elements [6]
237027	above or below a predetermined value or within or	• Testing of electronic circuits, e.g. by signal tracer
	beyond a predetermined range of values [3]	(testing computers during standby operation or idle time G06F 11/22)
29/033	• • • giving an indication of the number of times this	31/30 • • Marginal testing, e.g. by varying supply voltage
	occurs [3]	(testing computers during standby operation or
29/04	 Measuring form factor, i.e. quotient of root-mean- 	idle time G06F 11/22) [2]
	square value and arithmetic mean of instantaneous	31/302 • • Contactless testing [5]
	value; Measuring peak factor, i.e. quotient of	31/303 • • • of integrated circuits (G01R 31/305-
29/06	maximum value and root-mean-square valueMeasuring depth of modulation	G01R 31/315 take precedence) [6]
29/08	Measuring depth of modulation Measuring electromagnetic field characteristics	31/304 • • of printed or hybrid circuits (G01R 31/305-
29/10	Radiation diagrams of aerials	G01R 31/315 take precedence) [6]
29/12	Measuring electrostatic fields	31/305 • • • using electron beams [5]
29/14	Measuring field distribution	31/306 • • • • of printed or hybrid circuits [6]
29/16	Measuring asymmetry of polyphase networks	31/307 • • • • of integrated circuits [6]
29/18	Indicating phase sequence; Indicating synchronism	31/308 • • • using non-ionising electromagnetic radiation,
29/20	Measuring number of turns; Measuring	e.g. optical radiation [5] 31/309 • • • of printed or hybrid circuits [6]
	transformation ratio or coupling factor of windings	31/311 • • • • of integrated circuits [6]
29/22	Measuring piezo-electric properties	31/312 • • • by capacitive methods [5]
29/24	 Arrangements for measuring quantities of charge [2] 	31/315 • • • by inductive methods [5]
29/26	 Measuring noise figure; Measuring signal-to-noise 	31/316 • • Testing of analog circuits [6]
	ratio [2]	31/3161 • • • Marginal testing [6]
31/00	Arrangements for testing electric properties.	31/3163 • • • Functional testing [6]
31/00	Arrangements for testing electric properties; Arrangements for locating electric faults;	31/3167 • Testing of combined analog and digital circuits [6]
	Arrangements for electrical testing characterised by	31/317 • • Testing of digital circuits [6]
	what is being tested not provided for elsewhere	31/3173 • • • Marginal testing [6]
	(testing or measuring semiconductors or solid state	31/3177 • • • Testing of logic operation, e.g. by logic
	devices during manufacture H01L 21/66; testing line	analysers [6]
21 /01	transmission systems H04B 3/46)	31/3181 • • • Functional testing (G01R 31/3177 takes
31/01	 Subjecting similar articles in turn to test, e.g. "go/no-go" tests in mass production; Testing objects at points 	precedence) [6]
	as they pass through a testing station (G01R 31/18	31/3183 • • • Generation of test inputs, e.g. test vectors,
	takes precedence) [6]	patterns or sequences [6]
31/02	 Testing of electric apparatus, lines, or components for 	31/3185 • • • • Reconfiguring for testing, e.g. LSSD, partitioning [6]
	short-circuits, discontinuities, leakage, or incorrect	31/3187 • • • Built-in tests [6]
	line connection	31/319 • • • • Tester hardware, i.e. output processing
31/04	Testing connections, e.g. of plugs, of non-	circuits [6]
D4 /06	disconnectable joints	31/3193 • • • • with comparison between actual response
31/06	Testing of electric windings, e.g. for polarity Testing of faces [6].	and known fault-free response [6]
31/07	• Testing of fuses [6]	31/327 • Testing of circuit interrupters, switches or circuit-
31/08	 Locating faults in cables, transmission lines, or networks 	breakers [6]
31/10	by increasing destruction at fault, e.g. burning-in	31/333 • • Testing of the switching capacity of high-voltage
51/10	by using a pulse generator operating a special	circuit-breakers [6]
	programme	• Testing dynamo-electric machines [3]
24/11	using pulse-reflection methods	• Apparatus for testing electrical condition of
31/11		accumulators or electric batteries, e.g. capacity or
31/11	Testing dielectric strength or breakdown voltage	charge condition (accumulators combined with
		charge condition (accumulators combined with arrangements for measuring, testing or indicating
31/12	Testing dielectric strength or breakdown voltage	charge condition (accumulators combined with arrangements for measuring, testing or indicating condition H01M 10/48) [3]
31/12 31/14	 Testing dielectric strength or breakdown voltage Circuits therefor Construction of testing vessels; Electrodes therefor Subjecting similar articles in turn to test, e.g. 	arrangements for measuring, testing or indicating
31/12 31/14 31/16	 Testing dielectric strength or breakdown voltage Circuits therefor Construction of testing vessels; Electrodes therefor 	arrangements for measuring, testing or indicating condition H01M 10/48) [3]
31/12 31/14 31/16	 Testing dielectric strength or breakdown voltage Circuits therefor Construction of testing vessels; Electrodes therefor Subjecting similar articles in turn to test, e.g. 	arrangements for measuring, testing or indicating condition H01M 10/48) [3] 31/40 • Testing power supplies (testing photovoltaic devices

31/44	• Testing lamps [6]	33/381 • • • using electromagnets [6]
33/00	Arrangements or instruments for measuring	33/3815 • • • • with superconducting coils, e.g. power supply therefor [6]
33/02	magnetic variablesMeasuring direction or magnitude of magnetic fields	33/383 • • • using permanent magnets [6]
33702	or magnetic flux (G01R 33/20 takes precedence) [4]	33/385 • • • using gradient magnetic field coils [6]
33/022	Measuring gradient [3]	33/387 • • • • Compensation of inhomogeneities [6]
		33/3873 • • • • using ferromagnetic bodies [6] 33/3875 • • • • using correction coil assemblies, e.g.
	Note(s)	active shimming [6]
	Group G01R 33/022 or group G01R 33/10 takes	33/389 • • • Field stabilisation [6]
22/025	precedence over groups G01R 33/025-G01R 33/06.	33/42 • • • Screening [5, 6]
33/025 33/028	 Compensating stray fields [3] Electrodynamic magnetometers [3]	33/421 • • • of main or gradient magnetic field [6]
33/020	using magneto-optic devices, e.g. Faraday [3]	33/422 • • • of the radiofrequency field [6]
33/035	 using magneto-optic devices, e.g. raraday [5] using superconductive devices [3] 	33/44 • • using nuclear magnetic resonance (NMR)
33/038	 using permanent magnets, e.g. balances, torsion 	(G01R 33/24, G01R 33/62 take precedence) [5]
557 050	devices [3]	33/46 • • • NMR spectroscopy [5]
33/04	using the flux-gate principle	33/465 • • • applied to biological material, e.g. <u>in vitro</u>
33/05	• • • in thin-film element [3]	testing [6]
33/06	 using galvano-magnetic devices 	33/48 • • • NMR imaging systems [5]
33/07	• • • Hall-effect devices [6]	33/483 • • • with selection of signal or spectra from particular regions of the volume, e.g. <u>in vivo</u>
33/09	• • • Magneto-resistive devices [6]	spectroscopy [6]
33/10	 Plotting field distribution 	33/485 • • • • based on chemical shift information [6]
33/12	Measuring magnetic properties of articles or	33/50 • • • • based on the determination of relaxation
	specimens of solids or fluids (involving magnetic	times [5]
33/14	resonance G01R 33/20) [4]	33/54 • • • • Signal processing systems, e.g. using pulse
33/14	 Measuring or plotting hysteresis curves Measuring susceptibility	sequences [5]
33/18	Measuring magnetostrictive properties	33/56 • • • • Image enhancement or correction, e.g.
33/20	involving magnetic resonance (medical aspects	subtraction or averaging techniques [5]
33720	A61B 5/055; magnetic resonance gyrometers G01C 19/60) [4, 5]	33/561 • • • • by reduction of the scanning time, i.e. fast acquiring systems, e.g. using echoplanar pulse sequences [6]
33/24	• • for measuring direction or magnitude of magnetic fields or magnetic flux [4]	33/563 • • • • • of moving material, e.g. flow-contrast angiography [6]
33/26	• • • using optical pumping [4]	33/565 • • • • • Correction of image distortions, e.g.
33/28	 Details of apparatus provided for in groups G01R 33/44-G01R 33/64 [5] 	due to magnetic field inhomogeneities [6]
33/30	Sample handling arrangements, e.g. sample	33/567 • • • • gated by physiological signals [6]
00.404	cells, spinning mechanisms [5]	33/58 • • • Calibration of imaging systems, e.g. using
33/31	• • • Temperature control thereof [6]	test probes [5]
33/32	• • Excitation or detection systems, e.g. using radiofrequency signals [5]	33/60 • using electron paramagnetic resonance (G01R 33/24, G01R 33/62 take precedence) [5]
33/34	• • • Constructional details, e.g. resonators [5]	33/62 • using double resonance (G01R 33/24 takes
33/341	• • • • comprising surface coils [6]	precedence) [5]
	comprising arrays of sub-coils [6]	33/64 • using cyclotron resonance (G01R 33/24 takes
33/343	• • • • of slotted-tube or loop-gap type [6]	precedence) [5]
33/345	• • • • of waveguide type (G01R 33/343 takes precedence) [6]	35/00 Testing or calibrating of apparatus covered by the other groups of this subclass [2]
33/36	• • • • Electrical details, e.g. matching or coupling of the coil to the receiver [5]	• of auxiliary devices, e.g. of instrument transformers
33/38	• • Systems for generation, homogenisation or	according to prescribed transformation ratio, phase angle, or wattage rating
	stabilisation of the main or gradient magnetic field [5]	 35/04 • of instruments for measuring time integral of power or current
	Note(s)	35/06 • • by stroboscopic methods
	Compact Cost D 22/205 Cost D 22/200 (cl. cost d)	22. 22 by subsector memous

Note(s)

Groups G01R 33/385-G01R 33/389 take precedence over groups G01R 33/381-G01R 33/383.

G01S RADIO DIRECTION-FINDING; RADIO NAVIGATION; DETERMINING DISTANCE OR VELOCITY BY USE OF RADIO WAVES; LOCATING OR PRESENCE-DETECTING BY USE OF THE REFLECTION OR RERADIATION OF RADIO WAVES; ANALOGOUS ARRANGEMENTS USING OTHER WAVES

Note(s)

1. In this subclass, the following term is used with the meaning indicated:

difference of instantaneous frequencies of

received carrier waves

- "transponder" means an arrangement which reacts to an incoming interrogating or detecting wave by emitting a specific answering or identifying wave.
- 2. Attention is drawn to the Notes following the title of class G01 and to Note (1) following the title of subclass G09B.

Subclass index

Details. Using radio waves, using other waves where the wavelength or the kind of wave is irrelevant or unspecified. Using acoustic waves. Using acoustic waves. Using acoustic waves other than radio waves. 1500 SYSTEMS FOR DETERMINING DISTANCE OR VELOCITY NOT USING REFLECTION OR RERADIATION. 11/00 Beacons or beacon systems transmitting signals having a characteristic or characteristics capable of being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers cooperating therewith (position-fixing by co-ordinating a plurality of determinations of direction or position lines GOIS 5/00) [2] 1/02 1/02 1/03 1/04 1/05 1/06 1/06 1/06 1/06 1/06 1/06 1/06 1/06		N SYSTEMS; DIRECTION-FINDERS; POSITION FIXING		1/00, 19/00, 3/00, 5/00
Using acoustic waves. Using acoustic waves. Using acoustic waves. Using acoustic waves. Using acoustic waves other than radio waves. 1700 SYSTEMS FOR DETERMINING DISTANCE OR VELOCITY NOT USING REFLECTION OR RERADIATION. 1700 Beacons or beacon systems transmitting signals having a characteristic or characteristics capable of being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers cooperating therewith (position-fixing by co-ordinating a plurality of determinations of direction or position lines GOIS 5/00) [2] 1/02 using radio waves (GOIS 19/00 takes precedence) [1, 201.001] 1/04 • Details 1/06 • Systems for determining direction or position line 1/10 1/				7/00
Using acoustic waves. Using electromagnetic waves other than radio waves. SYSTEMS POR DETERMINING DISTANCE OR VELOCITY NOT USING REFLECTION OR RERADIATION. 1/00 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/100 1/101 1/100				
Using actoromagnetic waves other than radio waves				13/00
1/00 Beacons or beacon systems transmitting signals having a characteristic or characteristics capable of being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers coperating therewith (position-fixing by co-ordinating a plurality of determinations of direction or position lines (G015 5/00) [2] 1/02 • Issing radio waves (G01S 19/00 takes precedence) [1, 2010.01] 1/04 • Details 1/08 • Systems for determining direction or position line 1/10 • Issing amplitude comparison of signals transmitted sequentially from aerials or aerial systems having differently-oriented overlapping directivity-characteristics, e.g. by means of sequentially effective reflectors 1/14 • Issing amplitude comparison of signals transmitted simultaneously from aerials or aerial systems having differently-oriented overlapping directivity-characteristics are systems. In the content of the modulations of a significant part of the modulations of a significant part of the modulations or carried time-relationship with received signals, e.g. pulse duration coincides with time interval between arrival of significant part of the modulations or carried time-relationship with received signals, e.g. pulse duration coincides with time interval between arrival of significant part of the modulations or carried time-relationship with received signals, e.g. pulse duration coincides with time interval between arrival of significant part of the modulations or carried time-relationship with received signals, e.g. pulse duration coincides with time interval between arrival of significant part of the modulations or carried waves and the transmitter deference in significant part of the modulations or carried waves and time-relationship in microtal time of significant part of the modulations or carried waves and time-relationship with received signals, e.g. pulse duration coincides with time interval between arrival of significant part of the modulation or carried wave	Using	g acoustic waves		15/00
1/00 Beacons or beacon systems transmitting signals having a characteristic or characteristics capable of being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers cooperating therewith (position-lixing by co-ordinating a plurality of determinations of direction or position lines (GDIS 5/00) [2] 1/02 using radio waves (GDIS 19/00 takes precedence) [1, 2010.01] 1/04 Details 1/06 Details Deta				17/00
1/00 Beacons or beacon systems transmitting signals having a characteristic or characteristics capable of being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers coperating therewith (position-fixing by co-ordinating a plurality of determinations of direction or position lines (G015 5/00) [2] 1/02 • using radio waves (G015 19/00 takes precedence) [1, 2010.01] 1/04 • Details 1/08 • Systems for determining direction or position line transmitted sequentially from aerials or aerial systems having differently-oriented overlapping directivity-characteristics, e.g. equi-signal A-N type 1/12 • • • the signals being transmitted sequentially from an aerial or aerial system having differently-oriented overlapping directivity-characteristics periodically varied, e.g. by means of sequentially effective reflectors 1/14 • • • using amplitude comparison of signals transmitted simultaneously from aerials or aerial systems having differently-oriented overlapping directivity-characteristics overlapping directivity-characteristi				11/00
being detected by non-directional receivers and defining directions, positions, or position lines fixed relatively to the beacon transmitters; Receivers coperating therewith (position-lixing by co-ordinating a plurality of determinations of direction or position lines GO15 5:00) [2] 1/02 • using radio waves (GO1S 19/00 takes precedence) [1, 2010.01] 1/04 • Details 1/06 • • Means for providing multiple indication, e.g. coarse and fine indications or coarse and fine indications or coarse and fine indications or signals transmitted sequentially from aerials or aerial systems having differently-oriented overlapping directivity-characteristics, e.g., equi-signal A-N type 1/12 • • It is signal being transmitted sequentially from aerial sor aerial systems having differently-oriented overlapping directivity characteristics is transmitted simultaneously from aerials or aerial systems having differently-oriented overlapping directivity-characteristics is transmitted simultaneously from aerials or aerial systems having the orientation of its directivity characteristics are sequentially effective reflectors 1/14 • • It using amplitude comparison of signals transmitted simultaneously from aerials or aerial systems having differently-oriented overlapping directivity-characteristics 1/20 • Azimuthal guidance systems, e.g. system for defining aircraft approach path, localiser system 1/20 • It using a comparison of signals transmitted simultaneously from aerial or systems and a beat frequency, obtained by heterodyning the first signals with each other is compared in phase with a beat frequency obtained by heterodyning the first signals with a beat frequency obtained by heterodyning the synchronised signals transmitted from non-directional aerials or aerial systems spaced apart, i.e. path-difference systems and the transit times being frequency modulations on carrier waves and the transit times being and transmitted from the first and second aerial systems spaced apart, i.e. path-difference systems and the transit time of	RERADI	ATION		11/00
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1/20 • • • using a comparison of transit time of synchronised signals transmitted from non-directional aerials or aerial systems spaced apart, i.e. path-difference systems 1/22 • • • • the synchronised signals being frequency modulations on carrier waves and the transit 1/24 • • • • directional aerials or aerial systems spaced apart, i.e. path-difference systems 1/25 • • • • the synchronised signals being frequency modulations on carrier waves and the transit 1/26 • • • • the synchronised signals being frequency modulations on carrier waves and the transit 1/26 • • • • the synchronised signals being frequency modulations on carrier waves and the transit	1/18			
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synchronised signals transmitted from non- directional aerials or aerial systems spaced apart, i.e. path-difference systems 1/22 • • • • the synchronised signals being frequency modulations on carrier waves and the transit obtained by heterodyning the synchronised signals, is compared in phase with a reference signal having a phase substantially independent of direction	1/20		1/36 • • • •	Systems in which a beat frequency,
apart, i.e. path-difference systems 1/22 • • • the synchronised signals being frequency modulations on carrier waves and the transit synchronised signals, is compared in phase with a reference signal having a phase substantially independent of direction				
1/22 • • • • the synchronised signals being frequency phase substantially independent of modulations on carrier waves and the transit				synchronised signals, is compared in
modulations on carrier waves and the transit direction	1/22	· · · · · · · · · · · · · · · · · · ·		
	1/22			
				direction

40

1/38	• • •	using comparison of (1) the phase of the envelope of the change of frequency, due to Doppler effect, of the signal transmitted by an	1/68	 Marker, boundary, call-sign, or like beacons transmitting signals not carrying directional information
		aerial moving, or appearing to move, in a cyclic	1/70	
		path with (2) the phase of a reference signal,		using electromagnetic waves other than radio waves
		the frequency of this reference signal being	1/72	using ultrasonic, sonic, or infrasonic waves
		synchronised with that of the cyclic movement,	1/74	 Details [5]
4 / 40		or apparent cyclic movement, of the aerial	1/76	Systems for determining direction or position line [5]
1/40		 the apparent movement of the aerial being produced by cyclic sequential energisation of fixed aerials Conical-scan beam beacons transmitting signals 	1/78	using amplitude comparison of signals transmitted from transducers or transducer systems having differently-oriented
		which indicate at a mobile receiver any	1/80	characteristics [5]using a comparison of transit time of
		displacement of the receiver from the conical- scan axis, e.g. for "beam-riding" missile control [5]	1700	synchronised signals transmitted from non- directional transducers or transducer systems spaced apart, i.e. path-difference systems [5]
1/44	• • •	Rotating or oscillating beam beacons defining	1/82	Rotating or oscillating beam beacons defining
		directions in the plane of rotation or	1/02	directions in the plane of rotation or
		oscillation [5]		-
1/46		Broad-beam systems producing at a receiver		oscillation [5]
		a substantially continuous sinusoidal	3/00	Direction-finders for determining the direction from
		envelope signal of the carrier wave of the	3,00	which infrasonic, sonic, ultrasonic, or
		beam, the phase angle of which is dependent		electromagnetic waves, or particle emission, not
		upon the angle between the direction of the		having a directional significance, are being received
		receiver from the beacon and a reference		(position-fixing by co-ordinating a plurality of
		direction from the beacon, e.g. cardioid		determinations of direction or position lines G01S 5/00)
		system [5]	3/02	 using radio waves
1/48	• • •	wherein the phase angle of the direction-	3/04	• • Details
		dependent envelope signal is a multiple of	3/06	• • • Means for increasing effective directivity, e.g.
		the direction angle, e.g. for "fine" bearing indication [5]		by combining signals having differently-
1 /50				oriented directivity characteristics or by
1/50		 wherein the phase angle of the direction- dependent envelope signal is compared 		sharpening the envelope waveform of the signal
		with a non-direction- dependent reference		derived from a rotating or oscillating beam
		signal [5]		aerial (comparing amplitude of signals having
1/52		 wherein the phase angles of a plurality of 		differently-oriented directivity characteristics to
1/52		direction-dependent envelope signals		determine direction G01S 3/16, G01S 3/28)
		produced by a plurality of beams rotating	3/08	• • • Means for reducing polarisation errors, e.g. by
		at different speeds or in different	D /40	use of Adcock or spaced loop aerial systems
		directions are compared [5]	3/10	Means for reducing or compensating for
1/54		Narrow-beam systems producing at a	5 / 4 5	quadrantal, site, or like errors
		receiver a pulse-type envelope signal of the	3/12	• • Means for determining sense of direction, e.g.
		carrier wave of the beam, the timing of		by combining signals from directional aerial or
		which is dependent upon the angle between		goniometer search coil with those from non-
		the direction of the receiver from the beacon		directional aerial (determining direction by amplitude comparison of signals derived by
		and a reference direction from the beacon;		combining directional and non-directional
		Overlapping broad beam systems defining a		signals G01S 3/24, G01S 3/34)
		narrow zone and producing at a receiver a	3/14	Systems for determining direction or deviation
		pulse-type envelope signal of the carrier wave of the beam, the timing of which is		from predetermined direction
		dependent upon the angle between the	3/16	using amplitude comparison of signals derived
		direction of the receiver from the beacon and		sequentially from receiving aerials or aerial
		a reference direction from the beacon [5]		systems having differently-oriented directivity
1/56		 Timing the pulse-type envelope signals 		characteristics or from an aerial system having
		derived by reception of beam [5]		periodically-varied orientation of directivity
1/58		 wherein a characteristic of the beam 	7/10	characteristic
		transmitted or of an auxiliary signal is	3/18	• • • derived directly from separate directional
		varied in time synchronously with	2 /20	aerials
4 /50		rotation or oscillation of the beam [5]	3/20	 derived by sampling signal received by an aerial system having periodically-varied
1/60	• • •	• • Varying frequency of beam signal or of		orientation of directivity characteristic
1 /60		auxiliary signal [5]	3/22	• • • derived from different combinations of
1/62	• • •	Varying phase-relationship between how and auxiliary signal [5]	5122	signals from separate aerials, e.g. comparing
1/64		beam and auxiliary signal [5]		sum with difference
1/64		 Varying pulse timing, e.g. varying interval between pulses radiated in 	3/24	• • • • the separate aerials comprising one
		pairs [5]		directional aerial and one non-directional
1/66		• • • Superimposing direction-indicating		aerial, e.g. combination of loop and open
1,50		intelligence signals, e.g. speech,		aerials producing a reversed cardioid
		Morse [5]		directivity characteristic

	•	•	•	• • the separate aerials having differently-	3/64	•		•	•	•	• wherein the phase angle of the signal is
3/28				oriented directivity characteristics using amplitude comparison of signals derived							determined by phase comparison with a reference alternating signal varying in
3/20	·	•	Ĭ	simultaneously from receiving aerials or aerial							synchronism with the directivity variation
				systems having differently-oriented directivity characteristics	3/66	•	•	•	•	•	Narrow-beam systems producing in the receiver a pulse-type envelope signal of the
3/30	•	•	•	derived directly from separate directional							carrier wave of the beam, the timing of
3/32				systemsderived from different combinations of							which is dependent upon the angle between the direction of the transmitter from the
5/52				signals from separate aerials, e.g. comparing							receiver and a reference direction from the receiver; Overlapping broad-beam systems
3/34				sum with differencethe separate aerials comprising one							defining in the receiver a narrow zone and
				directional aerial and one non-directional							producing a pulse-type envelope signal of the carrier wave of the beam, the timing of
				aerial, e.g. combination of loop and open aerials producing a reversed cardioid							which is dependent upon the angle between
3/36	_			directivity characteristic							the direction of the transmitter from the receiver and a reference direction from the
3/30	•	•	٠	 the separate aerials having differently- oriented directivity characteristics 	3/68		_		_		receiver • wherein the timing of the pulse-type
3/38	•	•	•	using adjustment of real or effective orientation of directivity characteristic of an aerial or an	3/00	·			•	•	envelope signal is indicated by cathode-
				aerial system to give a desired condition of	3/70						ray tubewherein the timing of the pulse-type
				signal derived from that aerial or aerial system, e.g. to give a maximum or minimum signal	3/70						envelope signal is determined by bringing
2/40				(G01S 3/16, G01S 3/28 take precedence)							a locally-generated pulse-type signal into coincidence or other predetermined time-
3/40	•	•	•	 adjusting orientation of a single directivity characteristic to produce maximum or 	2 /72				Б		relationship with the envelope signal
				minimum signal, e.g. rotatable loop aerial, equivalent goniometer system	3/72	•	•	•			ersity systems specially adapted for direction- ing
3/42	•	•	•	 the desired condition being maintained 	3/74	•	•	•			ti-channel systems specially adapted for ction-finding, i.e. having a single aerial system
3/44				automaticallythe adjustment being varied periodically or					Cá	pa	ble of giving simultaneous indications of the
5/ 44				continuously until it is halted automatically							ctions of different signals (systems in which lirections of different signals are determined
3/46				when the desired condition is attained using aerials spaced apart and measuring phase					se	qu	entially and displayed simultaneously
				or time difference between signals therefrom,	3/78	•	ι	15			S 3/04, G01S 3/14) lectromagnetic waves other than radio waves
3/48				i.e. path-difference systemsthe waves arriving at the aerials being	3/781	•	•	•	D	eta	nils [5]
				continuous or intermittent and the phase	3/782	•	•	•			ems for determining direction or deviation predetermined direction [5]
				difference of signals derived therefrom being measured	3/783	•	•	•	•	us	sing amplitude comparison of signals derived
				the recover emissing at the serials being pulse							rom static detectors or detector systems [5] using a mosaic of detectors [5]
3/50	•	•	•	the waves arriving at the aerials being pulse modulated and the time difference of their	3/784	•	•	•	•		sing adjustment of orientation of directivity
	•	•	•	modulated and the time difference of their arrival being measured						-1	
3/50 3/52	•	•	•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to							haracteristics of a detector or detector system o give a desired condition of signal derived
3/52	•	•	•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal	3/785					to	haracteristics of a detector or detector system o give a desired condition of signal derived rom that detector or detector system [5]
	•	•	•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being						to	haracteristics of a detector or detector system o give a desired condition of signal derived
3/52			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed	3/785		•		•	fr •	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-
3/52			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically	3/785		•	•	•	fr • us	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation
3/52 3/54			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of	3/785 3/786 3/787 3/788		•	•		to fr	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5]
3/52 3/54			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using	3/785 3/786 3/787 3/788 3/789		•		•	to frr. us de	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5]
3/52 3/54 3/56			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for	3/785 3/786 3/787 3/788 3/789 3/80	•		ı	·	to fr	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves
3/52 3/54 3/56			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a	3/785 3/786 3/787 3/788 3/789	•		115.	· · · · · · · · · · · · · · · · · · ·	to fr us do us us g ui	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves wils [5] ems for determining direction or deviation
3/52 3/54 3/56			•	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802	•		ıısı	ing D Sy	to fr us do us gui eta	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves hils [5] ems for determining direction or deviation in predetermined direction [5]
3/52 3/54 3/56				modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the	3/785 3/786 3/787 3/788 3/789 3/80 3/801	•		ıısı	ing D Sy	us do	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves hils [5] ems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer
3/52 3/54 3/56 3/58				modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the receiver a substantially-sinusoidal envelope signal of the carrier wave of the beam, the	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802	•		ıısı	ing D Sy	us do us us guilleta	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-rependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves sails [5] rems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer systems having differently-oriented directivity
3/52 3/54 3/56 3/58				modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the receiver a substantially-sinusoidal envelope signal of the carrier wave of the beam, the phase angle of which is dependent upon the	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802	•		ıısı	ing D S; fr	us de us us	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves mils [5] ems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer systems having differently-oriented directivity haracteristics [5] sing adjustment of real or effective orientation
3/52 3/54 3/56 3/58		• • • •	• • • •	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the receiver a substantially-sinusoidal envelope signal of the carrier wave of the beam, the phase angle of which is dependent upon the angle between the direction of the transmitter from the receiver and a reference	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802 3/803	•		LIS:	ing D S; fr	us de us us de us	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves mils [5] ems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer systems having differently-oriented directivity characteristics [5] sing adjustment of real or effective orientation of directivity characteristics of a transducer or ransducer system to give a desired condition of
3/52 3/54 3/56 3/58			• • • •	modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the receiver a substantially-sinusoidal envelope signal of the carrier wave of the beam, the phase angle of which is dependent upon the angle between the direction of the	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802 3/803	•		LIS:	ing D S; fr	us de to us us grand us france character com us character character character since character ch	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-rependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves sails [5] rems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer systems having differently-oriented directivity characteristics [5] sing adjustment of real or effective orientation of directivity characteristics of a transducer or ransducer system to give a desired condition of signal derived from that transducer or
3/52 3/54 3/56 3/58				modulated and the time difference of their arrival being measured using a receiving aerial moving, or appearing to move, in a cyclic path to produce a Doppler variation of frequency of the received signal • the apparent movement of the aerial being produced by coupling the receiver cyclically and sequentially to each of several fixed spaced aerials Conical-scan beam systems using signals indicative of the deviation of the direction of reception from the scan axis Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or oscillation or for determining deviation from a predetermined direction in such a plane (G01S 3/16 takes precedence) • Broad-beam systems producing in the receiver a substantially-sinusoidal envelope signal of the carrier wave of the beam, the phase angle of which is dependent upon the angle between the direction of the transmitter from the receiver and a reference direction from the receiver, e.g. cardioid	3/785 3/786 3/787 3/788 3/789 3/80 3/801 3/802 3/803	•		LIS:	ing D S; fr	us de la communication de	haracteristics of a detector or detector system of give a desired condition of signal derived from that detector or detector system [5] the desired condition being maintained automatically [5] sing rotating reticles producing a direction-ependent modulation characteristic [5] producing a frequency modulation characteristic [5] sing rotating or oscillating beam systems, e.g. sing mirrors, prisms [5] ltrasonic, sonic, or infrasonic waves mils [5] ems for determining direction or deviation in predetermined direction [5] sing amplitude comparison of signals derived from receiving transducers or transducer systems having differently-oriented directivity characteristics [5] sing adjustment of real or effective orientation of directivity characteristics of a transducer or ransducer system to give a desired condition of

3/807	• • • the desired condition being maintained automatically [5]	7/08 • • • with vernier indication of distance, e.g. using two cathode-ray tubes
3/808	using transducers spaced apart and measuring phase or time difference between signals	7/10 • • • Providing two-dimensional co-ordinated display of distance and direction
D /000	therefrom, i.e. path-difference systems [5]	7/12 • • • • Plan-position indicators, i.e. P. P. I.
3/809	 Rotating or oscillating beam systems using continuous analysis of received signal for determining direction in the plane of rotation or 	 7/14 • • • • • Sector, off-centre, or expanded- angle display 7/16 • • • • • Signals displayed as intensity modulation
	oscillation or for determining deviation from a predetermined direction in such a plane [5]	with rectangular co-ordinates representing distance and bearing, e.g. type B
3/82	 with means for adjusting phase or compensating for time-lag errors 	7/18 • • • • Distance-height displays; Distance- elevation displays, e.g. type RHI, type E
3/84	 with indication presented on cathode-ray tubes 	7/20 • • • Stereoscopic displays; Three-dimensional
3/86	 with means for eliminating undesired waves, e.g. disturbing noises 	displays; Pseudo-three-dimensional displays 7/22 • • • Producing cursor lines and indicia by
5/00	Position-fixing by co-ordinating two or more	electronic means
	direction or position-line determinations; Position-	7/24 • • • the display being orientated or displaced in
	fixing by co-ordinating two or more distance determinations [2]	accordance with movement of object carrying the transmitting and receiving apparatus, e.g. true-motion radar
5/02	• using radio waves (G01S 19/00 takes	7/26 • • • Displays using electroluminescent panels
	precedence) [1, 2010.01]	7/28 • • Details of pulse systems
5/04	Position of source determined by a plurality of	7/282 • • • Transmitters [5]
	spaced direction-finders	7/285 • • • Receivers [5]
5/06	Position of source determined by co-ordinating a	7/288 • • • • Coherent receivers [5]
	plurality of position lines defined by path-	7/292 • • • • Extracting wanted echo-signals [5]
	difference measurements (G01S 5/12 takes precedence) [3]	7/295 • • • • Means for transforming co-ordinates or for
5/08	Position of single direction-finder fixed by	evaluating data, e.g. using computers [5]
3/00	determining direction of a plurality of spaced	7/298 • • • • Scan converters [5]
	sources of known location	7/32 • • • • Shaping echo pulse signals; Deriving non-
5/10	Position of receiver fixed by co-ordinating a plurality of position lines defined by path-	pulse signals from echo pulse signals [5] 7/34 • • • • Gain of receiver varied automatically during
	difference measurements (G01S 5/12 takes precedence) [3]	pulse-recurrence period, e.g. anti-clutter gain control [5]
5/12	 by co-ordinating position lines of different shape, 	7/35 • • Details of non-pulse systems [5]
	e.g. hyperbolic, circular, elliptical or radial	7/36 • • Means for anti-jamming
5/14	 Determining absolute distances from a plurality of 	7/38 • • Jamming means, e.g. producing false echoes [2]
	spaced points of known location	7/40 • • Means for monitoring or calibrating
5/16	 using electromagnetic waves other than radio waves 	7/41 • • using analysis of echo signal for target
5/18	 using ultrasonic, sonic, or infrasonic waves 	characterisation; Target signature; Target cross-
5/20	 Position of source determined by a plurality of 	section [6]
	spaced direction-finders [5]	7/42 • • Diversity systems specially adapted for radar
5/22	Position of source determined by co-ordinating a	7/48 • of systems according to group G01S 17/00
	plurality of position lines defined by path- difference measurements (G01S 5/28 takes	7/481 • • Constructional features, e.g. arrangements of
	precedence) [5]	optical elements [6]
5/24	 Position of single direction-finder fixed by 	7/483 • • Details of pulse systems [6]
5/21	determining direction of a plurality of spaced	7/484 • • • Transmitters [6]
	sources of known location [5]	7/486 • • • Receivers [6]
5/26	 Position of receiver fixed by co-ordinating a 	7/487 • • • Extracting wanted echo signals [6]
	plurality of position lines defined by path- difference measurements (G01S 5/28 takes	7/489 • • • • Gain of receiver varied automatically during pulse-recurrence period [6]
	precedence) [5]	7/491 • • Details of non-pulse systems [6]
5/28	by co-ordinating position lines of different shape, e.g. hyperbolic, circular, elliptical or radial [5]	7/493 • • • Extracting wanted echo signals [6]
5/30	Determining absolute distances from a plurality of	7/495 • Counter-measures or counter-counter-measures [6]
3/30	spaced points of known location [5]	7/497 • • Means for monitoring or calibrating [6]
	spaced points of known location [6]	7/499 • • using polarisation effects [6]
7/00	Details of systems according to groups G01S 13/00,	7/51 • • Display arrangements [6]
	G01S 15/00, G01S 17/00	7/52 • of systems according to group G01S 15/00
7/02	 of systems according to group G01S 13/00 	7/521 • • Constructional features [6]
7/03	 Details of HF subsystems specially adapted 	7/523 • • Details of pulse systems [6]
	therefor, e.g. common to transmitter and	7/524 • • • Transmitters [6]
	receiver [5]	7/526 • • • Receivers [6]
7/04	Display arrangements	7/527 • • • Extracting wanted echo signals [6]
7/06	Cathode-ray tube displays	7/529 • • • • Gain of receiver varied automatically during pulse-recurrence period [6]

7/53	• • • • Means for transforming co-ordinates or for evaluating data, e.g. using computers [6]	13/04 • • Systems determining presence of a target (based on relative movement of target G01S 13/56) [3]
7/531	• • • • Scan converters [6]	13/06 • • Systems determining position data of a target [3]
7/533	• • • • Data rate converters [6]	13/08 • • • Systems for measuring distance only (indirect
7/534	• • Details of non-pulse systems [6]	measurement G01S 13/46) [3]
7/536	 • Extracting wanted echo signals [6] 	13/10 • • • using transmission of interrupted pulse
7/537	Counter measures or counter-counter-measures,	modulated waves (determination of distance by phase measurement G01S 13/32) [3]
E/EDO	e.g. jamming, anti-jamming [6]	13/12 • • • • • wherein the pulse-recurrence frequency is
7/539	 using analysis of echo signal for target characterisation; Target signature; Target cross- 	varied to provide a desired time
	section [6]	relationship between the transmission of a
7/54	with receivers spaced apart	pulse and the receipt of the echo of a
7/56	Display arrangements	preceding pulse [3]
7/58	• • for providing variable ranges	13/14 • • • • • wherein a voltage or current pulse is initiated and terminated in accordance
7/60	• • for providing a permanent recording	respectively with the pulse transmission
7/62	Cathode-ray tube displays	and echo reception [3]
7/64	 Luminous indications (G01S 7/62 takes 	13/16 • • • • • using counters [3]
	precedence) [5]	13/18 • • • • wherein range gates are used [3]
11/00	Systems for determining distance or velocity not	13/20 • • • • whereby multiple time-around echos are
11/00	using reflection or reradiation (position-fixing by co-	used or eliminated [3]
	ordinating two or more distance determinations	13/22 • • • • using irregular pulse repetition
	G01S 5/00) [2]	frequency [3]
11/02	 using radio waves (G01S 19/00 takes 	13/24 • • • • using frequency agility of carrier
	precedence) [5, 2010.01]	wave [3] 13/26 • • • • wherein the transmitted pulses use a
11/04	• • using angle measurements [5]	frequency- or phase-modulated carrier
11/06	• • using intensity measurements [5]	wave [3]
11/08	• using synchronised clocks [5]	13/28 • • • • • with time compression of received
11/10 11/12	using Doppler effect [5]using electromagnetic waves other than radio	pulses [3]
	waves [5]	13/30 • • • • using more than one pulse per radar period [3]
11/14	• using ultrasonic, sonic or infrasonic waves [5]	13/32 • • • using transmission of continuous
11/16	 using difference in transit time between electromagnetic and sonic waves [5] 	unmodulated waves, amplitude-, frequency-
		or phase-modulated waves [3]
	Note(s)	13/34 • • • • using transmission of frequency-modulated waves and the received signal,
	1. Groups G01S 13/00-G01S 17/00 <u>cover</u> :	or a signal derived therefrom, being
	systems for detecting the presence of an shiret a g by reflection or reardiction from	heterodyned with a locally-generated
	object, e.g. by reflection or reradiation from the object itself, or from a transponder	signal related to the contemporaneous
	associated with the object, for determining	transmitted signal to give a beat- frequency signal [3]
	the distance or relative velocity of an object,	13/36 • • • • with phase comparison between the
	for providing a co-ordinated display of the	received signal and the
	distance and direction of an object or for obtaining an image thereof;	contemporaneously transmitted signal [3]
	 systems arranged for mounting on a moving 	13/38 • • • • wherein more than one modulation
	craft or vehicle and using the reflection of	frequency is used [3]
	waves from an extended surface external to	13/40 • • • • • wherein the frequency of transmitted signal is adjusted to give a
	the craft, e.g. the surface of the earth, to	predetermined phase relationship [3]
	determine the velocity and direction of motion of the craft relative to the surface.	13/42 • • • Simultaneous measurement of distance and
	2. Groups G01S 13/00-G01S 17/00 do not cover:	other coordinates (indirect measurement
	 systems for determining the direction of an 	G01S 13/46) [3]
	object by means not employing reflection or	13/44 • • • Monopulse radar, i.e. simultaneous
	reradiation, which are covered by groups	lobing [3]
	G01S 1/00 or G01S 3/00; • systems for determining distance or velocity	13/46 • • • Indirect determination of position data [3]
	of an object by means not employing	13/48 • • • • using multiple beams at emission or reception [3]
	reflection or reradiation, which are covered	13/50 • • Systems of measurement based on relative
	by group G01S 11/00.	movement of target [3]
13/00	Systems using the reflection or reradiation of radio	13/52 • • • Discriminating between fixed and moving
10/00	waves, e.g. radar systems; Analogous systems using	objects or between objects moving at different
	reflection or reradiation of waves whose nature or	speeds [3]
	wavelength is irrelevant or unspecified [3]	13/522 • • • • using transmissions of interrupted pulse modulated waves [5]
13/02	Systems using reflection of radio waves, e.g. primary radar systems: Analogous systems [3]	modulated waves [J]
	radar systems; Analogous systems [3]	

13/524	based upon the phase or frequency shift resulting from movement of objects, with reference to the transmitted signals, e.g. coherent MTi [5]	• Radar or analogous systems, specially adapted for specific applications (electromagnetic prospecting or detecting of objects, e.g. near-field detection, G01V 3/00) [3, 6]
13/526		13/89 • • for mapping or imaging [3]
15/520	spectrum without loss of range	13/90 • • using synthetic aperture techniques [3, 6]
	information, e.g. using delay line	
		13/91 • • for traffic control (G01S 13/93 takes
	cancellers or comb filters [5]	precedence) [3]
13/528	8 • • • • • with elimination of blind speeds [5]	13/92 • • • for velocity measurement [3]
13/53	 • • • • performing filtering on a single 	13/93 • • for anti-collision purposes [3]
	spectral line and associated with one or	13/94 • • for terrain-avoidance [3]
	more range gates with a phase detector	
	or a frequency mixer to extract the	13/95 • • for meteorological use [3]
	Doppler information, e.g. pulse	4T/00 C
	Doppler radar [5]	15/00 Systems using the reflection or reradiation of
13/532		acoustic waves, e.g. sonar systems [3]
13/332	memory matrix [5]	• using reflection of acoustic waves (G01S 15/66 takes
40 (50 4		precedence) [3]
13/534		• • Systems determining presence of a target [3]
	resulting from movement of objects,	15/06 • • Systems determining position data of a target [3]
	with reference to the surrounding	
	clutter echo signal, e.g. non-coherent	15/08 • • • Systems for measuring distance only (indirect
	MTi, clutter referenced MTi, externally	measurement G01S 15/46) [3]
	coherent MTi [5]	15/10 • • • using transmission of interrupted pulse-
13/536	6 • • • using transmission of continuous	modulated waves (determination of distance
	unmodulated waves, amplitude-, frequency-,	by phase measurement G01S 15/32) [3]
	or phase-modulated waves [5]	15/12 • • • • wherein the pulse-recurrence frequency is
13/538	-	varied to provide a desired time
13/330		relationship between the transmission of a
	between successive antenna scans, e.g. area	pulse and the receipt of the echo of a
40.450	MTi [5]	preceding pulse [3]
13/56	• • • for presence detection [3]	15/14 • • • • • wherein a voltage or current pulse is
13/58	 • Velocity or trajectory determination systems; 	initiated and terminated in accordance
	Sense-of-movement determination systems [3]	
13/60	 • • • wherein the transmitter and receiver are 	respectively with the pulse transmission
	mounted on the moving object, e.g. for	and echo reception [3]
	determining ground speed, drift angle,	15/18 • • • • wherein range gates are used [3]
	ground track (G01S 13/64 takes	15/32 • • • using transmission of continuous
	precedence) [3]	unmodulated waves, amplitude-, frequency-
13/62	• • • • Sense-of-movement determination [3]	or phase-modulated waves [3]
		15/34 • • • • using transmission of frequency-
13/64	• • • Velocity measuring systems using range	modulated waves and the received signal,
	gates [3]	or a signal derived therefrom, being
13/66	 Radar-tracking systems; Analogous systems [3] 	heterodyned with a locally-generated
13/68	 for angle tracking only [3] 	signal related to the contemporaneous
13/70	 for range tracking only [3] 	transmitted signal to give a beat-
13/72	 for two-dimensional tracking, e.g. combination of 	frequency signal [3]
10,,1	angle and range tracking, track-while-scan	15/36 • • • • with phase comparison between the
	radar [3]	
12/74		received signal and the
13/74	Systems using reradiation of radio waves, e.g. secondary radar systems: A palegous systems [2, 6].	contemporaneously transmitted signal [3]
40./55	secondary radar systems; Analogous systems [3, 6]	15/42 • • • Simultaneous measurement of distance and
13/75	• • using transponders powered from received waves,	other coordinates (indirect measurement
	e.g. using passive transponders [6]	G01S 15/46) [3]
13/76	 wherein pulse-type signals are transmitted [3] 	15/46 • • • Indirect determination of position data [3]
13/78	 discriminating between different kinds of 	15/50 • • Systems of measurement based on relative
	targets, e.g. IFF-radar, i.e. identification of	movement of target [3]
	friend or foe (G01S 13/75, G01S 13/79 takes	15/52 • • • Discriminating between fixed and moving
	precedence) [3]	objects or between objects moving at different
13/79	Systems using random coded signals or random	speeds [3]
- · · · -	pulse repetition frequencies [6]	15/58 • • • Velocity or trajectory determination systems;
13/82	 wherein continuous-type signals are 	Sense-of-movement determination systems [3]
13/04	transmitted [3]	· · · · · · · · · · · · · · · · · · ·
17/04		15/60 • • • • wherein the transmitter and receiver are
13/84	• • • for distance determination by phase	mounted on the moving object, e.g. for
	measurement [3]	determining ground speed, drift angle,
13/86	Combinations of radar systems with non-radar	ground track [3]
	systems, e.g. sonar, direction finder [3]	15/62 • • • • Sense-of-movement determination [3]
13/87	 Combinations of radar systems, e.g. primary radar 	15/66 • Sonar tracking systems [3]
	and secondary radar [3]	• Systems using reradiation of acoustic waves, e.g. IFF,
		i.e. identification of friend or foe [3]
		15/87 • Combinations of sonar systems [3]

15/00	Carron southern annially advantal for an aritic		NI-4-(-) [2010 01]
15/88	 Sonar systems, specially adapted for specific applications (seismic or acoustic prospecting or 		Note(s) [2010.01]
	detecting G01V 1/00) [3, 6]		The term "cooperating elements" designates additional
15/89	• for mapping or imaging [3]		elements or subsystems, including receivers of other
			users, which interact or communicate with the receiver
15/93	• • for anti-collision purposes [3]		or the satellite positioning system.
15/96	• • for locating fish [3]	19/04	• • • providing carrier phase data [2010.01]
17/00	Systems using the reflection or reradiation of	19/05	 providing aiding data [2010.01]
17700	electromagnetic waves other than radio waves, e.g.	19/06	 employing an initial estimate of the location
	lidar systems [3]		of the receiver as aiding data or in
17/02	Systems using the reflection of electromagnetic		generating aiding data [2010.01]
17702	waves other than radio waves (G01S 17/66 takes	19/07	• • providing data for correcting measured
	precedence) [3]		positioning data, e.g. DGPS [differential GPS]
17/06	Systems determining position data of a target [3]		or ionosphere corrections [2010.01]
17/08	• • for measuring distance only (indirect	19/08	• • • providing integrity information, e.g. health of
	measurement G01S 17/46; active triangulation	10/00	satellites or quality of ephemeris data [2010.01]
	systems G01S 17/48) [3, 2006.01]	19/09	• • • providing processing capability normally
17/10	• • • using transmission of interrupted pulse-	10/10	carried out by the receiver [2010.01]
	modulated waves (determination of distance	19/10	• • • providing dedicated supplementary positioning
	by phase measurements G01S 17/32) [3]	10/11	signals [2010.01]
17/32	 • • using transmission of continuous 	19/11	• • • • wherein the cooperating elements are
	unmodulated waves, amplitude-, frequency-,		pseudolites or satellite radio beacon positioning system signal
	or phase-modulated waves [3]		repeaters [2010.01]
17/36	• • • • with phase comparison between the	19/12	• • • • wherein the cooperating elements are
	received signal and the	15/12	telecommunication base stations [2010.01]
	contemporaneously transmitted signal [3]	19/13	• • Receivers [2010.01]
17/42	• • • Simultaneous measurement of distance and	19/14	• • specially adapted for specific
	other coordinates (indirect measurement	13/14	applications [2010.01]
	G01S 17/46) [3]	19/15	• • • Aircraft landing systems [2010.01]
17/46	• • • Indirect determination of position data [3]	19/16	• • • • Anti-theft; Abduction [2010.01]
17/48	• • • Active triangulation systems, i.e. using the	19/17	• • • • Emergency applications [2010.01]
	transmission and reflection of	19/17	• • • • Military applications [2010.01]
	electromagnetic waves other than radio waves [2006.01]	19/10	• • • Sporting applications [2010.01]
17/50	Systems of measurement based on relative	19/19	
17/50	movement of target [3]	19/20	 Integrity monitoring, fault detection or fault isolation of space segment [2010.01]
17/58	• • Velocity or trajectory determination systems;	19/21	7 0 1 1 5000000
17730	Sense-of-movement determination systems,	19/21	
17/66	Tracking systems using electromagnetic waves other	19/22	• • • Multipath-related issues [2010.01]
17700	than radio waves [3]	19/23	 Testing, monitoring, correcting or calibrating of a receiver element [2010.01]
17/74	Systems using reradiation of electromagnetic waves	19/24	• • Acquisition or tracking of signals transmitted
1,,,,	other than radio waves, e.g. IFF, i.e. identification of	13/24	by the system [2010.01]
	friend or foe [3]	19/25	• • • • involving aiding data received from a
17/87	 Combinations of systems using electromagnetic 	15/25	cooperating element, e.g. assisted
	waves other than radio waves [3]		GPS [2010.01]
17/88	 Lidar systems, specially adapted for specific 	19/26	• • • involving a sensor measurement for aiding
	applications [3]	107 = 0	acquisition or tracking [2010.01]
17/89	 for mapping or imaging [6, 2006.01] 	19/27	• • • creating, predicting or correcting ephemeris
17/93	 for anti-collision purposes [6, 2006.01] 		or almanac data within the
17/95	• • for meteorological use [6, 2006.01]		receiver [2010.01]
		19/28	• • • • Satellite selection [2010.01]
19/00	Satellite radio beacon positioning systems;	19/29	• • • carrier related [2010.01]
	Determining position, velocity or attitude using	19/30	• • • code related [2010.01]
	signals transmitted by such systems [2010.01]	19/31	• • • Acquisition or tracking of other signals for
19/01	Satellite radio beacon positioning systems		positioning [2010.01]
	transmitting time-stamped messages, e.g. GPS	19/32	• • Multimode operation in a single same satellite
	[Global Positioning System], GLONASS [Global Orbiting Navigation System] or		system, e.g. GPS L1/L2 [2010.01]
	Orbiting Navigation Satellite System] or GALILEO [2010.01]	19/33	• • • Multimode operation in different systems
19/02	 Details of the space or ground control 		which transmit time stamped messages, e.g.
13/04	segments [2010.01]		GPS/GLONASS [2010.01]
19/03	Cooperating elements; Interaction or	19/34	• • • Power consumption [2010.01]
10,00	communication between different cooperating	19/35	• • Constructional details or hardware or software
	elements or between cooperating elements and		details of the signal processing chain [2010.01]
	receivers [2010.01]	19/36	• • • relating to the receiver frond end [2010.01]
		19/37	• • • Hardware or software details of the signal
			processing chain [2010.01]

9 9	tion solution using signals lite radio beacon positioning	19/47	• • • •	 the supplementary measurement being an inertial measurement, e.g. tightly coupled inertial [2010.01]
transmitting time-s [Global Positionin	peacon positioning system stamped messages, e.g. GPS g System], GLONASS [Global on Satellite System] or D1]	19/48	•••	by combining or switching between position solutions derived from the satellite radio beacon positioning system and position solutions derived from a further system [2010.01]
19/40 • • • Correcting posi attitude [2010.0]	1]	19/49	• • • •	 whereby the further system is an inertial position system, e.g. loosely-
19/41 • • • Differential of		10/50		coupled [2010.01]
19/42 • • Determining po	GPS] [2010.01] sition [2010.01] phase measurements, e.g.	19/50	• • • •	whereby the position solution is constrained to lie upon a particular curve or surface, e.g. for locomotives on railway tracks [2010.01]
	sitioning; using long or short	19/51		Relative positioning [2010.01]
	rferometry [2010.01]	19/52	• • • D	etermining velocity [2010.01]
	nase ambiguity resolution;	19/53	• • • D	etermining attitude [2010.01]
squares A Adjustme	ambiguity; LAMBDA [Least- MBiguity Decorrelation nt] method [2010.01]	19/54	• • • •	using carrier phase measurements; using long or short baseline interferometry [2010.01]
		19/55	• • • •	 Carrier phase ambiguity resolution; Floating ambiguity; LAMBDA [Least-squares AMBiguity Decorrelation Adjustment] method [2010.01]
19/46 • • • • the supple	ementary measurement being of ave signal type [2010.01]			ragionnent memod [2010.01]

G01T MEASUREMENT OF NUCLEAR OR X-RADIATION (radiation analysis of materials, mass spectrometry G01N 23/00; tubes for determining the presence, intensity, density or energy of radiation or particles H01J 47/00)

Note(s)

- 1. This subclass <u>covers</u> the measurement of X-radiation, gamma radiation, corpuscular radiation, cosmic radiation, or neutron radiation.
- 2. Attention is drawn to the Notes following the title of class G01.

1/00	Measuring X-radiation, gamma radiation, corpuscular radiation, or cosmic radiation	1/169 • • Exploration, location of contaminated surface areas [2]
	(G01T 3/00, G01T 5/00 take precedence) [2]	1/17 • • Circuit arrangements not adapted to a particular
1/02	• Dosimeters (G01T 1/15 takes precedence) [2]	type of detector
1/04	 Chemical dosimeters (G01T 1/06, G01T 1/08 take precedence) 	1/172 • • • with coincidence circuit arrangements (G01T 1/178 takes precedence) [2]
1/06	 Glass dosimeters 	1/175 • • • Power supply circuits [2]
1/08	Photographic dosimeters	1/178 • • • for measuring specific activity in the presence
1/10	Luminescent dosimeters	of other radioactive substances, e.g. natural, in
1/105	• • Read-out devices (G01T 1/115 takes	the air or in liquids such as rain-water [2]
	precedence) [2]	1/18 • with counting-tube arrangements, e.g. with Geige
1/11	• • • Thermo-luminescent dosimeters	counters (tubes H01J 47/00)
1/115	• • • • Read-out devices [2]	1/185 • • with ionisation-chamber arrangements [2]
1/12	 Calorimetric dosimeters 	1/20 • with scintillation detectors
1/14	• • Electrostatic dosimeters (construction of ionisation	1/202 • • • the detector being a crystal
	chambers H01J 47/02)	1/203 • • • the detector being made of plastics
1/142	• • • Charging devices; Read-out devices [2]	1/204 • • • the detector being a liquid
1/15	 Instruments in which pulses generated by a radiation 	1/205 • • • the detector being a gas
	detector are integrated, e.g. by a diode pump circuit	1/208 • • • Circuits specially adapted for scintillation
1/16	 Measuring radiation intensity (G01T 1/29 takes precedence) [2] 	detectors, e.g. for the photo-multiplier section [2]
1/161	 Applications in the field of nuclear medicine, e.g. 	1/22 • • with Cerenkov detectors
	in vivo counting [2]	1/24 • • with semiconductor detectors
1/163	• • • Whole-body counters [2]	1/26 • • with resistance detectors
1/164	• • • Scintigraphy [2]	1/28 • • with secondary-emission detectors
1/166	• • • involving relative movement between detector and subject [2]	 Measurement performed on radiation beams, e.g. position or section of the beam; Measurement of
1/167	 Measuring radioactive content of objects, e.g. 	spatial distribution of radiation [2]
	contamination (whole-body counters	1/30 • Measuring half-life of a radioactive substance
	G01T 1/163) [2]	1/32 • Measuring polarisation of particles

1/34	 Measuring cross-section, e.g. absorption cross- 	5/04	 Cloud chambers, e.g. Wilson chamber
	section of particles	5/06	Bubble chambers
1/36	 Measuring spectral distribution of X-rays or of nuclear radiation 	5/08	• Scintillation chambers (discharge tubes H01J 40/00, H01J 47/00)
1/38	 Particle discrimination and measurement of relative mass, e.g. by measurement of loss of energy with distance (dE/dx) [2] 	5/10	 Plates or blocks in which tracks of nuclear particles are made visible by after-treatment, e.g. using photographic emulsion, using mica
1/40	Stabilisation of spectrometers [2]	5/12	• Circuit arrangements with multi-wire or parallel-plate chambers, e.g. spark chambers (tubes <u>per se</u>
3/00	Measuring neutron radiation (G01T 5/00 takes		H01J 47/00) [2]
	precedence) [2]		
3/02	 by shielding other radiation 	7/00	Details of radiation-measuring instruments
3/02 3/04	1 /	7/00 7/02	Details of radiation-measuring instruments Collecting-means for receiving or storing samples to
	by shielding other radiation		5
3/04	by shielding other radiationusing calorimetric devices		 Collecting-means for receiving or storing samples to
3/04 3/06	by shielding other radiationusing calorimetric deviceswith scintillation detectors [2]	7/02	Collecting-means for receiving or storing samples to be investigated
3/04 3/06 3/08	 by shielding other radiation using calorimetric devices with scintillation detectors [2] with semiconductor detectors [2] Recording of movements or tracks of particles (spark chambers H01J 47/14); Processing or analysis of such	7/02 7/04	 Collecting-means for receiving or storing samples to be investigated by filtration by electrostatic precipitation (G01T 7/04 takes
3/04 3/06 3/08	 by shielding other radiation using calorimetric devices with scintillation detectors [2] with semiconductor detectors [2] Recording of movements or tracks of particles (spark)	7/02 7/04 7/06	 Collecting-means for receiving or storing samples to be investigated by filtration by electrostatic precipitation (G01T 7/04 takes precedence)

GO1V GEOPHYSICS; GRAVITATIONAL MEASUREMENTS; DETECTING MASSES OR OBJECTS; TAGS (means for indicating the location of accidentally buried, e.g. snow-buried, persons A63B 29/02) **[4, 6]**

Note(s)

- 1. This subclass <u>covers</u> radar, sonar, lidar or analogous systems specifically designed for geophysical use. Radar, sonar, lidar or analogous systems, or details of such systems, if of a general interest, are also classified in subclass G01S.
- 2. In this subclass, the following term is used with the meaning indicated:
 - "tags" means arrangements cooperating with a detecting field, e.g. near field, and designed to produce a specific detectable effect; "tags" also means active markers capable of generating a detectable field.
- 3. In this subclass, the geophysical methods apply both to the earth and to other celestial objects, e.g. planets.
- 4. Attention is drawn to the Notes following the title of class G01.

Subclass index

Subclass	<u>index</u>		
APPARATUS OR METHODS OF PROSPECTING OR DETECTING Seismic or acoustic			
1/053 1/06 1/08 1/09 1/104 1/108	Seismology; Seismic or acoustic prospecting or detecting Generating seismic energy Petails Arrangements for coupling the generator to the ground [3] Figure of the generating transverse waves [3] Figure of the generating transverse waves [3] Figure of the generating transverse waves [3] Figure of the generator to the generator to the ground [3] Figure of the generator to the generator to the ground [3] Figure of the generator to the generator to the generator to the ground [3] Figure of the generator to the generator t	 1/116 • • • where pressurised combustion gases escape from the generator in a pulsating manner, e.g. for generating bursts [3] 1/13 • • Arrangements or disposition of charges to produce a desired pattern in space or time 1/133 • • using fluidic driving means, e.g. using highly pressurised fluids (G01V 1/104 takes precedence) [3] 1/135 • • • by deforming or displacing surfaces of enclosures [3] 1/137 • • • which fluids escape from the generator in a pulsating manner, e.g. for generating bursts [3] 1/143 • • using mechanical driving means (G01V 1/104, G01V 1/133 takes precedence) [3] 1/145 • • • by deforming or displacing surfaces [3] 1/147 • • using impact of dropping masses [3] 1/153 • • using rotary uphalanced masses [3] 	
1/112	• • • for use on the surface of the earth [3]	1/153 · · · using rotary unbalanced masses [3] 1/155 · · · using reciprocating masses [3]	

1/157 • using spark discharges; using exploding wires [3]

1/16	Receiving elements for seismic signals;	3/165	operating with magnetic or electric fields
1/18	Arrangements or adaptations of receiving elementsReceiving elements, e.g. seismometer,		produced or modified by the object or by the detecting device (with electromagnetic waves
4 /00	geophone [2]	2/17	G01V 3/17) [3]
1/20	Arrangements of receiving elements, e.g. geophone pattern	3/17 3/175	operating with electromagnetic waves [3]operating with electron or nuclear magnetic
1/22	Transmitting seismic signals to recording or	2/10	resonance [3]
1/24	processing apparatus	3/18	specially adapted for well-logging
1/24	Recording seismic data	3/20	• • operating with propagation of electric current [3]
1/26	 Reference-signal-transmitting devices, e.g. indicating moment of firing of shot 	3/22	• • • using dc [3]
1/28	Processing seismic data, e.g. analysis, for	3/24	• • • using ac [3]
	interpretation, for correction (G01V 1/48 takes precedence) [6]	3/26	 operating with magnetic or electric fields produced or modified either by the surrounding earth formation or by the detecting device (with
1/30	• • Analysis (G01V 1/50 takes precedence) [6]		electromagnetic waves G01V 3/30) [3]
1/32	Transforming one recording into another	3/28	• • • using induction coils [3]
1/34	Displaying seismic recordings	3/30	• • operating with electromagnetic waves [3]
1/36	Effecting static or dynamic corrections on records, e.g. correcting spread; Correlating seismic signals; This is the feature of the fea	3/32	operating with electron or nuclear magnetic resonance [3]
1/27	Eliminating effects of unwanted energy	3/34	Transmitting data to recording or processing
1/37	 • specially adapted for seismic systems using continuous agitation of the ground [3] 	2/26	apparatus; Recording data [3]
1/38	specially adapted for water-covered areas	3/36 3/38	 Recording data (G01V 3/34 takes precedence) [3] Processing data, e.g. for analysis, for interpretation or
1750	(G01V 1/28 takes precedence)	3/30	for correction [3]
1/387	Reducing secondary bubble pulse, i.e. reducing the detected signals resulting from the generation and release of gas bubbles after the primary	3/40	 specially adapted for measuring magnetic field characteristics of the earth [3]
	explosion [3]	5/00	Prospecting or detecting by the use of nuclear
1/393	Means for loading explosive underwater charges,		radiation, e.g. of natural or induced radioactivity
	e.g. combined with ignition devices [3]	5/02	 specially adapted for surface logging, e.g. from
1/40	 specially adapted for well-logging 		aircraft [3]
1/42	 using generators in one well and receivers 	5/04	 specially adapted for well-logging [3]
	elsewhere or vice-versa (G01V 1/52 takes	5/06	 for detecting naturally radioactive minerals [3]
	precedence) [6]	5/08	 using primary nuclear radiation sources or X-
1/44	• • using generators and receivers in the same well	= /	rays [3]
1 / 40	(G01V 1/52 takes precedence) [6]	5/10	• • • using neutron sources [3]
1/46	Data acquisition [6]Processing data [6]	5/12	• • • using gamma- or X-ray sources [3]
1/48 1/50	• • • Analysing data [6]	5/14	• • • using a combination of several sources, e.g. a
	• • Structural details [6]		neutron and a gamma source [3]
1/52	Structural details [0]	7/00	Measuring gravitational fields or waves; Gravimetric
3/00	Electric or magnetic prospecting or detecting;		prospecting or detecting
	Measuring magnetic field characteristics of the	7/02	 Details
	earth, e.g. declination or deviation [2, 4] Note(s)	7/04	• • Electric, photoelectric, or magnetic indicating or recording means
		7/06	 Analysis or interpretation of gravimetric records
	Groups G01V 3/15-G01V 3/18 take precedence over	7/08	 using balances
2 /02	groups G01V 3/02-G01V 3/14.	7/10	 using torsion balances, e.g. Eötvös balance
3/02	 operating with propagation of electric current using dc	7/12	 using pendulums
3/04	_	7/14	 using free-fall time
3/06	using ac approximate with magnetic or electric fields produced or	7/16	 specially adapted for use on moving platforms, e.g.
3/08	 operating with magnetic or electric fields produced or modified by objects or geological structures or by detecting devices (with electromagnetic waves 	8/00	ship, aircraft Prospecting or detecting by optical means [6]
	G01V 3/12)	0/00	
3/10	 using induction coils 		Note(s)
3/11	• • • for detecting conductive objects, e.g. firearms, cables or pipes [3]		This group <u>covers</u> the use of infra-red, visible or ultra-violet light.
3/12	operating with electromagnetic waves	8/02	Prospecting [6]
3/14	operating with electron or nuclear magnetic resonance	8/10	• Detecting, e.g. by using light barriers (by reflection from the object G01S 17/00) [6]
3/15	• specially adapted for use during transport, e.g. by a	8/12	 using one transmitter and one receiver [6]
	person vehicle or hoat [3]	0/14	

 using reflectors [6] specially adapted for use from aircraft 8/16 using optical fibres [6] (G01V 3/165-G01V 3/175 take precedence) [3] using mechanical scanning systems [6] 8/20 • • using multiple transmitters or receivers [6] IPC (2014.01), Section G 49

8/22	• • • using reflectors [6]	15/00	Tags attached to, or associated with, an object, in
8/24	• • • using optical fibres [6]		order to enable detection of the object (record carriers
8/26	• • • using mechanical scanning systems [6]		for use with machines having a detectable tag or marker G06K 19/00) [6]
9/00	Prospecting or detecting by methods not provided for in groups G01V 1/00-G01V 8/00 [6]		Note(s)
9/02	Determining existence or flow of underground water		This group <u>does not cover</u> detectors or detection methods, e.g. methods in which the object to be
11/00	Prospecting or detecting by methods combining		detected produces or modifies magnetic or electric
	techniques covered by two or more of main groups		fields, which are covered elsewhere, e.g. in group
	G01V 1/00-G01V 9/00		G01V 3/00.
13/00	Manufacturing, calibrating, cleaning, or repairing instruments or devices covered by groups G01V 1/00-G01V 11/00	99/00	Subject matter not provided for in other groups of this subclass [2009.01]
G01W	METEOROLOGY (radar, sonar, lidar or analogous sy	stems, desig	gned for meteorological use G01S 13/95. G01S 15/88.

METEOROLOGY (radar, sonar, lidar or analogous systems, designed for meteorological use G01S 13/95, G01S 15/88, G01S 17/95)

Note(s)

- In this subclass, the following term is used with the meaning indicated:
 - "meteorology" includes measurement of certain ambient atmospheric conditions. Attention is drawn to the Notes following the title of class G01.

1/00 1/02	Meteorology • Instruments for indicating weather conditions by	 Adaptations of balloons, missiles, or aircraft for meteorological purposes; Radiosondes
	measuring two or more variables, e.g. humidity,	1/10 • Devices for predicting weather conditions
	pressure, temperature, cloud cover, wind speed	1/11 • Devices for indicating atmospheric humidity
	(G01W 1/10 takes precedence)	1/12 • Sunshine-duration recorders
1/04	 giving only separate indications of the variables 	1/14 • Rainfall or precipitation gauges
1/06	 giving a combined indication of weather conditions (catathermometers for measuring "cooling value" related either to weather 	 Measuring atmospheric potential differences, e.g. due to electrical charges in clouds Catathermometers for measuring "cooling value" related either to weather conditions or to comfort of
	conditions or to comfort of other human environment G01W 1/17)	other human environment 1/18 • Testing or calibrating meteorological apparatus